

2-nd order Linear ODE with constant coefficients

1) Homogeneous case: $ay'' + by' + cy = 0$; $a, b, c \in \mathbb{R}$
 $y = y(t)$

Adams: § 3.7 page 206

Method of solution based on:

Hypothesis $y(t) = e^{rt}$, r to be determined

Lay: § 5.7 page 329

Method: $X'(t) = AX(t)$

Diagonalization of matrix A

Obs: • one special case of A represents the examples studied by Adams § 3.7

- the formulation presented by Lay § 5.7 is more general and enable us to study different systems of ODE, not only those specifically associated to $ay'' + by' + cy = 0$.

In any case, I would like to show that for equations $ay'' + by' + cy = 0$, both formulations (Adams & Lay) are equivalent and lead us to the same solution. (As it should be!)

2) Non-Homogeneous case: $ay'' + by' + cy = f(t)$ $a, b, c \in \mathbb{R}$
 $y = y(t)$

Solution $y(t) = y_H(t) + y_P(t)$

$y_H(t)$ = solution of the homogeneous part

$y_P(t)$ = particular solution depending on function $f(t)$.

Adams § 18.4 page 1017 general presentation

<u>Adams</u>	§ 18.4	page	1017	general presentation
	§ 18.5	page	1018	ODE with constant coeff Higher order (same hypothesis $y(t) = e^{rt}$)
	§ 18.6	page	1025	Non-homogeneous case

Lay: The Non-homogeneous case is not presented on Lay considering the vector form.

Extra material is provided for those who have interest.

For the examination (Tentamen MVE465 - 14/01/2021) we will consider only the formulation presented by Adams for the Non-homogeneous case.

Example: Solve the Initial Value Problem (IVP)

$$\begin{cases} y'' - 3y' + 2y = \cos 3t \\ y(0) = 2 \\ y'(0) = -3 \end{cases}$$

1) Resolution according to Adams § 3.7 for the Homogeneous part & Adams § 18.6 for the Non-homogeneous part.

Solution: y_H = solution of the Homogeneous ODE $y'' - 3y' + 2y = 0$.

Hypothesis $y(t) = e^{rt}$, r to be determined.

$$\begin{cases} y = e^{rt} \\ y' = r e^{rt} \\ y'' = r^2 e^{rt} \end{cases} \Rightarrow \text{substituting on the Homog. Eq}$$

$$r^2 e^{rt} - 3r e^{rt} + 2 e^{rt} = 0$$

$$(r^2 - 3r + 2) e^{rt} = 0 \Rightarrow \begin{cases} e^{rt} = 0 \\ \text{OR} \\ (r^2 - 3r + 2) = 0 \end{cases}$$

Characteristic equation: $r^2 - 3r + 2 = 0$

$$r_{1,2} = \frac{3 \pm \sqrt{9 - 4 \cdot 1 \cdot 2}}{2 \cdot 1}$$

$$\frac{3+1}{2} = \frac{4}{2} = 2$$

$$r_1 = 2$$

$$\frac{3-1}{2} = \frac{2}{2} = 1$$

$$r_2 = 1$$

So $y_H(t) = c_1 e^{2t} + c_2 e^t$

Homogeneous solution.

Now, to obtain y_p we have to analyse $f(t) = \cos(3t)$

So $y_p(t) = A \cos(3t) + B \sin(3t)$, A and B to be determined.

To substitute y_p into the equation, first we compute:

$$y_p = A \cos 3t + B \sin 3t$$

$$y_p' = -3A \sin 3t + 3B \cos 3t$$

$$y_p'' = -9A \cos 3t - 9B \sin 3t$$

The Non-Homogeneous EDO: $y'' - 3y' + 2y = \cos 3t = \underline{1} \cos 3t + \underline{0} \sin 3t$

$$\begin{array}{rcl} y'' & & -9A \cos 3t - 9B \sin 3t \\ -3y & & -3(-3A \sin 3t + 3B \cos 3t) \\ +2y & & 2(A \cos 3t + B \sin 3t) \\ \hline & = & \end{array}$$

$$\underline{1 \cos 3t + 0 \sin 3t} \quad \underline{(-9A - 9B + 2A) \cos 3t} + \underline{(-9B + 9A + 2B) \sin 3t}$$

$$\begin{cases} -7A - 9B = 1 \\ 9A - 7B = 0 \end{cases} \Rightarrow 9A = 7B \Rightarrow A = \frac{7}{9}B$$

$$-7\left(\frac{7}{9}\right)B - 9B = 1 \Rightarrow \left(-\frac{49}{9} - \frac{81}{9}\right)B = 1$$

$$B = -\frac{9}{130} \Rightarrow A = \frac{7}{9}\left(-\frac{9}{130}\right) = -\frac{7}{130}$$

$$\frac{1}{130} \frac{81}{49}$$

So the particular solution is given by:

$$y_p = -\frac{7}{130} \cos(3t) - \frac{9}{130} \sin(3t)$$

Now to obtain the solution for the IVP, we have to use the two information: $\begin{cases} y(0) = 2 \\ y'(0) = -3 \end{cases}$

$$y'(0) = -3$$

$$y(t) = y_H(t) + y_P(t) = C_1 e^{2t} + C_2 e^{1t} - \frac{7}{130} \cos(3t) - \frac{9}{130} \sin(3t)$$

$$y'(t) = y'_H(t) + y'_P(t) = 2C_1 e^{2t} + C_2 e^t + \frac{21}{130} \sin(3t) - \frac{27}{130} \cos(3t)$$

$$\begin{cases} y(0) = C_1 + C_2 - \frac{7}{130} = 2 \\ y'(0) = 2C_1 + C_2 - \frac{27}{130} = -3 \end{cases}$$

$$\begin{cases} C_1 + C_2 = 2 + \frac{7}{130} = \frac{267}{130} \\ 2C_1 + C_2 = -3 + \frac{27}{130} = -\frac{363}{130} \end{cases}$$

$$\begin{array}{r} 130 \\ \times 3 \\ \hline 390 \end{array} - \frac{390}{363}$$

$$\begin{cases} C_1 + C_2 = \frac{267}{130} \\ -2C_1 + C_2 = -\frac{363}{130} \end{cases}$$

$$\begin{array}{r} 11 \\ 363 \\ + 267 \\ \hline 630 \end{array}$$

$$-C_1 + 0 = \frac{267}{130} = \frac{630}{130} \quad C_1 = -\frac{630}{130}$$

$$C_2 = \frac{267}{130} - C_1 = \frac{267}{130} + \frac{630}{130} = \frac{897}{130}$$

Thus the solution of the IVP is:

$$y(t) = -\frac{63}{13} e^{2t} + \frac{897}{130} e^t - \frac{7}{130} \cos(3t) - \frac{9}{130} \sin(3t)$$

□

Now, we just solve the Homogeneous part again via eigenvalues & eigenvectors to show the connection between the 2 formulations:

Recal:

$$x'' - 3x' + 2x = 0$$

(Homogeneous Eq)
(Notation used in our class)

Solution:

1st) Matricial formulation of the equation:

$$\begin{cases} x_1 = x \\ x_2 = x' = x_1' \end{cases} \Rightarrow x_2' = x_1' = x'' \stackrel{\text{by the equation}}{=} -2x + 3x' \quad \begin{matrix} \text{(ii)} & & x_1 & x_2 \end{matrix}$$

$$\text{Now, } \begin{cases} x_1' = 0x_1 + 1x_2 & \text{(i)} \\ x_2' = -2x_1 + 3x_2 & \text{(ii)} \end{cases}$$

$$\begin{pmatrix} x_1' \\ x_2' \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ -2 & 3 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$$

$$X' = A_{2 \times 2} X$$

$$A = \begin{pmatrix} 0 & 1 \\ -2 & 3 \end{pmatrix} \quad \text{Let's try to diagonalize } A.$$

$$2^{\text{nd}}) \det(A - \lambda I) = 0$$

$$\det \begin{pmatrix} 0 - \lambda & 1 \\ -2 & 3 - \lambda \end{pmatrix} = 0 \Rightarrow (-\lambda)(3 - \lambda) + 2 = 0 \Rightarrow$$

$$-3\lambda + \lambda^2 + 2 = 0 \Rightarrow \lambda^2 - 3\lambda + 2 = 0 \quad \text{Characteristic polynomial}$$

Observe that this is the same equation we had before to compute r .

$$\lambda_{1,2} = \frac{3 \pm \sqrt{9 - 4 \cdot 1 \cdot 2}}{2 \cdot 1} \quad \lambda_1 = \frac{3+1}{2} = \frac{4}{2} = 2$$

$$\lambda_2 = \frac{3-1}{2} = \frac{2}{2} = 1$$

λ_1 & λ_2 are eigenvalues of A .

3^{ra}) Let's compute the eigenvectors associated to each λ_i .

$$\lambda_1 = 2 \quad \begin{pmatrix} 0-2 & 1 \\ -2 & 3-2 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} -2 & 1 \\ -2 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \Rightarrow \begin{pmatrix} -2 & 1 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \Rightarrow$$

$$-2x + 1y = 0 \Rightarrow 2x = y \Rightarrow x = \frac{1}{2}y$$

$$\vec{v} = \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} \frac{1}{2}y \\ y \end{pmatrix} = y \begin{pmatrix} \frac{1}{2} \\ 1 \end{pmatrix} \Rightarrow \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 1 \\ 2 \end{pmatrix} \text{ is one possible eigenvector associated to } \lambda_1 = 2.$$

$$\lambda_2 = 1 \quad \begin{pmatrix} 0-1 & 1 \\ -2 & 3-1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \Rightarrow$$

$$\div -2 \quad \begin{pmatrix} -1 & 1 \\ -2 & 2 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \Rightarrow$$

$$\begin{pmatrix} -1 & 1 & | & 0 \\ +1 & -1 & | & 0 \end{pmatrix} \Rightarrow \begin{pmatrix} -1 & 1 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \Rightarrow$$

$$-x + y = 0 \Rightarrow x = y \Rightarrow \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} y \\ y \end{pmatrix} = y \begin{pmatrix} 1 \\ 1 \end{pmatrix} \quad \alpha \in \mathbb{R}$$

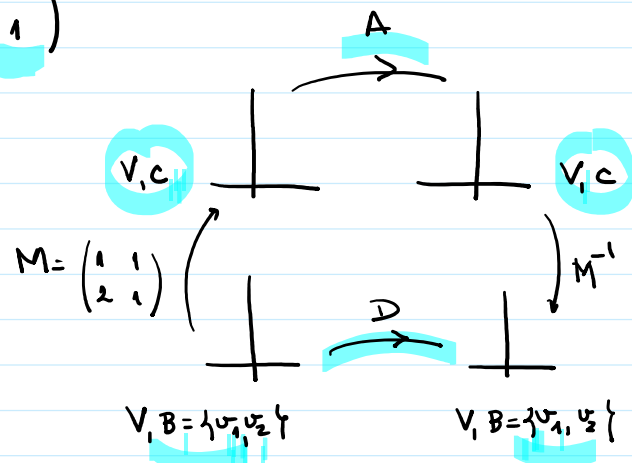
so one eigenvector could be $\vec{v}_2 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$

$$\mathcal{B} = \left\{ \vec{v}_1 = \begin{pmatrix} 1 \\ 2 \end{pmatrix}, \vec{v}_2 = \begin{pmatrix} 1 \\ 1 \end{pmatrix} \right\} \text{ base of eigenvectors}$$

$$M_{\mathcal{C}}^{\mathcal{B}} = \begin{pmatrix} 1 & 1 \\ 2 & 1 \end{pmatrix} \quad D = \begin{pmatrix} 2 & 0 \\ 0 & 1 \end{pmatrix}$$

$$\text{So } \mathcal{X}' = A\mathcal{X}$$

$$M = \begin{pmatrix} \vec{v}_1 & \vec{v}_2 \\ 1 & 1 \end{pmatrix} \text{ Matrix of Change of Basis from } \mathcal{B} \text{ to Canonical}$$



1 1 1 / of basis from
B to Canonical

$$V, B = \{v_1, v_2\}$$

$$V, B = \{v_1, v_2\}$$

$$X = M_c^B y$$

$$[D]_B^B = M_c^{-1} A_c^c M_c^B$$

y is the solution
given on the Basis of Eigenvectors

$$M^{-1} X = y$$

So the change of variables is given by

$$X'(t) = A X(t)$$

$$M^{-1} X'(t) = M^{-1} A (M M^{-1}) X$$

$$P^{-1} X'(t) = (M^{-1} A M) (M^{-1} X)$$

$$y'(t) = \underbrace{\begin{pmatrix} 2 & 0 \\ 0 & 1 \end{pmatrix}}_D y(t) \leftarrow$$

$$\Rightarrow \begin{pmatrix} y_1'(t) \\ y_2'(t) \end{pmatrix} = \begin{pmatrix} 2 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} y_1(t) \\ y_2(t) \end{pmatrix} \Rightarrow$$

$$\Rightarrow y_1'(t) = 2 y_1(t) \Rightarrow y_1(t) = c_1 e^{2t}$$

$$\Rightarrow y_2'(t) = 1 y_2(t) \Rightarrow y_2(t) = c_2 e^{1t}$$

So

$$\begin{pmatrix} y_1 \\ y_2 \end{pmatrix} = \begin{pmatrix} c_1 e^{2t} \\ c_2 e^{1t} \end{pmatrix}$$

$$X = M_c^B y \Rightarrow \begin{pmatrix} x_1(t) \\ x_2(t) \end{pmatrix} = \begin{pmatrix} 1 & 1 \\ 2 & 1 \end{pmatrix} \begin{pmatrix} c_1 e^{2t} \\ c_2 e^{1t} \end{pmatrix} =$$

$$X(t) = \begin{pmatrix} x_1(t) \\ x_2(t) \end{pmatrix} = c_1 e^{2t} \begin{pmatrix} 1 \\ 2 \end{pmatrix} + c_2 e^{1t} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$\chi(t) = \begin{pmatrix} x_1(t) \\ x_2(t) \end{pmatrix} = c_1 e^{2t} \begin{pmatrix} 1 \\ 2 \end{pmatrix} + c_2 e^{1t} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$= \begin{pmatrix} c_1 e^{2t} + c_2 e^{1t} \\ 2c_1 e^{2t} + c_2 e^{1t} \end{pmatrix} = \begin{pmatrix} x(t) \\ x'(t) \end{pmatrix}$$

$x(t) = c_1 e^{2t} + c_2 e^{1t}$ is exactly what we have obtained with the methodology given by Adams. !

The link for the webpage where Non-homogeneous ODE are treated by the matrixial formulation is given directly on the Canvas web-page.

