

Gram-Schmidt Orthogonalization Process

Lay Page 372 §6.4

Theorem 11 page 373

Given a basis $B = \{\vec{x}_1, \vec{x}_2, \dots, \vec{x}_n\}$ for a nonzero subspace $W \subseteq \mathbb{R}^n$

Define

$$\vec{v}_1 \leftarrow \vec{x}_1$$

$$\vec{v}_2 = \vec{x}_2 - \text{proj}_{\vec{v}_1} \vec{x}_2 = \vec{x}_2 - \frac{\vec{x}_2 \cdot \vec{v}_1}{\vec{v}_1 \cdot \vec{v}_1} \vec{v}_1$$

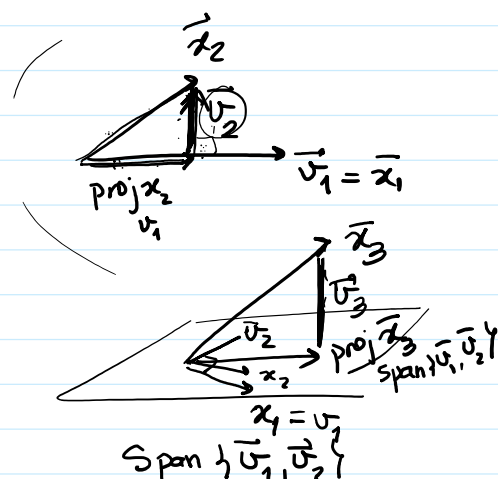
$$\vec{v}_3 = \vec{x}_3 - \text{proj}_{\text{span}\{\vec{v}_1, \vec{v}_2\}} \vec{x}_3 =$$

$$\vec{x}_3 - \left(\text{proj}_{\vec{v}_1} \vec{x}_3 + \text{proj}_{\vec{v}_2} \vec{x}_3 \right)$$

$$\vec{v}_4 = \vec{x}_4 - \text{proj}_{\text{span}\{\vec{v}_1, \vec{v}_2, \vec{v}_3\}} \vec{x}_4 =$$

$$\vec{x}_4 - \left(\text{proj}_{\vec{v}_1} \vec{x}_4 + \text{proj}_{\vec{v}_2} \vec{x}_4 + \text{proj}_{\vec{v}_3} \vec{x}_4 \right)$$

$$\vec{v}_n = \vec{x}_n - \text{proj}_{\text{span}\{\vec{v}_1, \dots, \vec{v}_{n-1}\}} \vec{x}_n$$

Then $\mathcal{O} = \{\vec{v}_1, \dots, \vec{v}_n\}$ is an orthogonal basis of $W \subseteq \mathbb{R}^n$

$$\& \text{Span}\{\vec{v}_1, \dots, \vec{v}_k\} = \text{Span}\{\vec{x}_1, \dots, \vec{x}_k\} \quad 1 \leq k \leq n.$$

Example. Consider $B = \{(1,1,1), (0,2,1), (0,0,1)\}$ basis for $W \subseteq \mathbb{R}^3$.

- Obtain $\mathcal{O}$ orthogonal basis via Gram-Schmidt having B as the starting point
- Obtain $\mathcal{O}'$ orthonormal basis related to $\mathcal{O}$.

moving Q as the starting point

- Obtain Q' orthonormal basis related to Q .

Gram-Schmidt

$$B = \{\bar{x}_1, \bar{x}_2, \bar{x}_3\} \quad \bar{x}_1 = (1, 1, 1) \quad \bar{x}_2 = (0, 2, 1) \quad \bar{x}_3 = (0, 0, 1)$$

$$1) \bar{v}_1 = \bar{x}_1 = (1, 1, 1) \quad \checkmark$$

$$\bar{v}_2 = \bar{x}_2 - \text{proj}_{\bar{v}_1} \bar{x}_2 = (0, 2, 1) - \frac{(0, 2, 1) \cdot (1, 1, 1)}{(1, 1, 1) \cdot (1, 1, 1)} (1, 1, 1)$$

$$2) \bar{v}_2 = (0, 2, 1) - \frac{3}{3} (1, 1, 1) = (-1, 1, 0)$$

$$\begin{aligned} \bar{v}_3 &= \bar{x}_3 - \text{proj}_{\text{Span}\{\bar{v}_1, \bar{v}_2\}} \bar{x}_3 = \bar{x}_3 - \text{proj}_{\bar{v}_1} \bar{x}_3 - \text{proj}_{\bar{v}_2} \bar{x}_3 \\ &= (0, 0, 1) - \frac{(0, 0, 1) \cdot (1, 1, 1)}{(1, 1, 1) \cdot (1, 1, 1)} (1, 1, 1) - \frac{(0, 0, 1) \cdot (-1, 1, 0)}{(-1, 1, 0) \cdot (-1, 1, 0)} (-1, 1, 0) \\ &= (0, 0, 1) - \frac{1}{3} (1, 1, 1) - 0 (-1, 1, 0) \end{aligned}$$

$$\bar{v}_3 = \left(-\frac{1}{3}, -\frac{1}{3}, \frac{2}{3}\right)$$

$$\text{So } Q = \left\{ \underbrace{(1, 1, 1)}_{\bar{v}_1}, \underbrace{(-1, 1, 0)}_{\bar{v}_2}, \underbrace{\left(-\frac{1}{3}, -\frac{1}{3}, \frac{2}{3}\right)}_{\bar{v}_3} \right\}$$

Orthogonal Basis based on B.

Observe that

$$\|\bar{v}_1\| = \sqrt{1+1+1} = \sqrt{3} \neq 1$$

$\bar{v}_1$ is not an unitary vector.

$$\|\bar{v}_2\| = \sqrt{1^2+1^2+0} = \sqrt{2} \neq 1$$

$\bar{v}_2$ has size different from 1.

$$\|\bar{v}_3\| = \sqrt{\left(\frac{1}{9}\right) + \frac{1}{9} + \frac{4}{9}} = \sqrt{\frac{6}{9}} = \frac{\sqrt{6}}{3}$$

$\bar{v}_3$ is not normalized.

So the orthonormal basis $\mathcal{O}'$ obtained through $\mathcal{O}$ is

$$\mathcal{O}' = \left\{ \frac{\vec{v}_1}{\|\vec{v}_1\|}, \frac{\vec{v}_2}{\|\vec{v}_2\|}, \frac{\vec{v}_3}{\|\vec{v}_3\|} \right\}$$

$$= \left\{ \left(\frac{1}{\sqrt{3}}, \frac{1}{\sqrt{3}}, \frac{1}{\sqrt{3}} \right), \left(-\frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}}, 0 \right), \left(-\frac{1}{\sqrt{2}} \cdot \frac{\sqrt{2}}{\sqrt{6}}, -\frac{1}{\sqrt{2}} \cdot \frac{\sqrt{2}}{\sqrt{6}}, \frac{2}{\sqrt{2}} \cdot \frac{\sqrt{2}}{\sqrt{6}} \right) \right\}$$

$$\mathcal{O}' = \left\{ \underbrace{\left(\frac{1}{\sqrt{3}}, \frac{1}{\sqrt{3}}, \frac{1}{\sqrt{3}} \right)}_{\vec{w}_1}, \underbrace{\left(-\frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}}, 0 \right)}_{\vec{w}_2}, \underbrace{\left(-\frac{1}{\sqrt{6}}, -\frac{1}{\sqrt{6}}, \frac{2}{\sqrt{6}} \right)}_{\vec{w}_3} \right\}$$

Obs.

$$\vec{w}_1 = \frac{\vec{v}_1}{\|\vec{v}_1\|} \quad \|\vec{w}_1\| = \sqrt{\frac{1}{3} + \frac{1}{3} + \frac{1}{3}} = \sqrt{\frac{3}{3}} = 1$$

$$\vec{w}_2 = \frac{\vec{v}_2}{\|\vec{v}_2\|} \quad \|\vec{w}_2\| = \sqrt{\frac{1}{2} + \frac{1}{2}} = \sqrt{1} = 1$$

$$\vec{w}_3 = \frac{\vec{v}_3}{\|\vec{v}_3\|} \quad \|\vec{w}_3\| = \sqrt{\frac{1}{6} + \frac{1}{6} + \frac{4}{6}} = \sqrt{\frac{6}{6}} = 1$$

Actually $\vec{w} = \frac{\vec{u}}{\|\vec{u}\|}$ is always normal since

$$\|\vec{w}\| = \left\| \underbrace{\frac{\vec{u}}{\|\vec{u}\|}}_{\text{cte}} \right\| = \frac{1}{\|\vec{u}\|} \cdot \|\vec{u}\| = 1. \quad \text{for all } \vec{u} \neq \vec{0}. \quad (\forall \vec{u} \neq \vec{0})$$

□.