

Chapter 6: Scalar initial value problems (summary)

November 25, 2020

Goal: We study and approximate numerically solutions to IVP

$$\begin{cases} \dot{y}(t) = f(y(t)) & \text{for } t \in (0, T] \\ y(0) = y_0. \end{cases}$$

Here, T, y_0, f are given and $\dot{y}(t) = \frac{d}{dt}y(t)$.

- Let $f, a: [0, T] \rightarrow \mathbb{R}$ be continuous with $a \geq 0$ bounded for instance. Let $y_0 \in \mathbb{R}$. Consider the first order linear DE

$$\begin{cases} \dot{y}(t) + a(t)y(t) = f(t) & \text{for } t \in (0, T] \\ y(0) = y_0. \end{cases}$$

The exact solution to the above IVP is given by the **variation of constants formula** (voc)

$$y(t) = y_0 e^{-A(t)} + \int_0^t e^{-(A(t)-A(s))} f(s) ds,$$

where $A(t) = \int_0^t a(s) ds$.

If $a(t) \geq 0$ for all $t \in (0, T]$ (parabolic case), we have the following stability estimate

$$|y(t)| \leq |y_0| + \int_0^t |f(s)| ds.$$

If $a(t) \geq \alpha > 0$ for all $t \in (0, T]$ (dissipative case), we have the following stability estimate

$$|y(t)| \leq e^{-\alpha t} |y_0| + \frac{1}{\alpha} (1 - e^{-\alpha t}) \max_{0 \leq s \leq T} |f(s)|.$$

- For $y: \mathbb{R} \rightarrow \mathbb{R}$ differentiable at t_0 and a fixed $h > 0$, we define the following approximations of the derivative:

The **forward difference**

$$\dot{y}(t_0) \approx \frac{y(t_0 + h) - y(t_0)}{h}.$$

The **backward difference**

$$\dot{y}(t_0) \approx \frac{y(t_0) - y(t_0 - h)}{h}.$$

The **central difference** or **centered difference**

$$\dot{y}(t_0) \approx \frac{y(t_0 + h) - y(t_0 - h)}{2h}.$$

- Consider the IVP

$$\begin{cases} \dot{y}(t) = f(y(t)) & \text{for } t \in (0, T] \\ y(0) = y_0. \end{cases}$$

Let $N \in \mathbb{N}$ and define the **time step** $k = \frac{T}{N}$ as well as the grid $0 = t_0 < t_1 < \dots < t_N = T$, where $t_n = nk$ for $n = 0, 1, \dots, N$.

We define the following time integrators for the above IVP (starting with $y_0 = y(0)$):

The **(forward/explicit) Euler scheme**

$$y_{n+1} = y_n + kf(y_n).$$

The **backward/implicit Euler scheme**

$$y_{n+1} = y_n + kf(y_{n+1}).$$

The **Crank–Nicolson scheme**

$$y_{n+1} = y_n + \frac{k}{2} (f(y_n) + f(y_{n+1})).$$

These provide numerical approximations $y_n \approx y(t_n)$ to the exact solution of the IVP on the time grid $(t_n)_{n=0}^N$.

- One can apply the above time integrators to the following system of linear DE

$$\begin{cases} M\dot{\zeta}(t) + S\zeta(t) = F(t) & \text{for } t \in (0, T] \\ \zeta(0) & \text{given} \end{cases}$$

resulting from a full discretisation of the heat equation, see Studio II and the next chapter. In this case, M would be a mass matrix, S a stiffness matrix, and F would correspond to the load vector.

The Euler scheme then reads (with $\zeta^{(0)} = \zeta(0)$)

$$M\zeta^{(n+1)} = (M - kS)\zeta^{(n)} + kF(t_n).$$

The backward Euler scheme then reads (with $\zeta^{(0)} = \zeta(0)$)

$$(M + kS)\zeta^{(n+1)} = M\zeta^{(n)} + kF(t_{n+1}).$$

The Crank–Nicolson scheme then reads (with $\zeta^{(0)} = \zeta(0)$)

$$\left(M + \frac{k}{2}S\right)\zeta^{(n+1)} = \left(M - \frac{k}{2}S\right)\zeta^{(n)} + \frac{k}{2}(F(t_n) + F(t_{n+1})).$$

Observe that, for each of the above numerical schemes, one has to solve a linear system at each time step.

Further resources:

- www.wikipedia.org
- brown.edu
- ocw.mit.edu
- math.lamar.edu
- calcworkshop.com
- intmath.com