

Solutions to exercises MMG800

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Week 1

53. Let $B = \{x \in \mathbb{R}^2 : |x| < 1\}$ be the unit disc in $\mathbb{R}^2$. Find condition on α for which $|x|^\alpha \in H^1(B)$ but $|x|^s \notin H^1(B)$ for any $s < \alpha$.

Solution. We have that $u = |x|^\alpha \in H^1(B)$ if

$$\underbrace{\int_B |x|^{2\alpha}}_{(1)} + \underbrace{\sum_{i=1}^2 \int_B \left(\frac{\partial u}{\partial x_i} \right)^2 dx_1 dx_2}_{(2)} < \infty.$$

With polar coordinates, we have

$$\begin{aligned} x &= r \cos \theta, \\ y &= r \sin \theta \text{ and} \\ dx &= r dr d\theta, \end{aligned}$$

giving us

$$\begin{aligned} (1) &= 2\pi \int_0^1 r^{2\alpha} \cdot r dr = 2\pi \int_0^1 r^{2\alpha+1} dr < \infty \text{ if} \\ 2\alpha + 1 &> -1 \\ 2\alpha &> -2 \\ \alpha &> -1. \end{aligned}$$

Further, we have that $(2) < \infty$ if $\int_B \left(\frac{\partial u}{\partial x_1} \right)^2 < \infty$ due to symmetry reasons.

$$\begin{aligned}
\int_B \left(\frac{\partial u}{\partial x_1} \right)^2 dx_1 dx_2 &= \left\{ \begin{array}{l} \text{Assume } \alpha \neq 0. \\ \frac{\partial}{\partial x_1} |x|^\alpha = \\ \frac{\partial}{\partial x_1} (x_1^2 + x_2^2)^{\alpha/2} = \\ \frac{\alpha}{2} (x_1^2 + x_2^2)^{\alpha/2-1} \cdot 2x_1 = \\ \frac{\alpha}{2} r^{\alpha-2} \cdot 2r \cos \theta = \\ \alpha r^{\alpha-1} \cdot \cos \theta \end{array} \right\} = \\
&= \underbrace{\int_0^{2\pi} \cos^2 \theta d\theta}_{< \infty} \cdot \underbrace{\int_0^1 (r^{\alpha-1})^2 \cdot r dr}_{= \int_0^1 r^{2\alpha-1} dr < \infty \text{ if } \begin{array}{l} 2\alpha-1 > -1 \\ 2\alpha > 0 \\ \alpha > 0 \end{array}}
\end{aligned}$$

And likewise (2) diverges if $\alpha < 0$. If $\alpha = 0$,

$$u = |x|^0 = 1, \quad \frac{\partial}{\partial x_1}(1) = 0, \quad \int_B 0 dx = 0.$$

We obtain that $|x|^\alpha \in H^1(B)$ if $\alpha \geq 0$ and $|x|^\alpha \notin H^1(B)$ if $\alpha < 0$.

54. Define $H^2(B)$ and find a function that is in $H^1(B)$ but not in $H^2(B)$, where B is the unit disc.

Solution. The definition of $H^2(B)$ is

$$H^2(B) = \left\{ u \in L_2(B) : \frac{\partial u}{\partial x_i} \in L_2(B), \frac{\partial^2 u}{\partial x_i \partial x_j} \in L_2(B), \quad i, j = 1, 2 \right\}.$$

Inspired by the last exercise, we choose $u = |x|^{\frac{1}{2}} = (x_1^2 + x_2^2)^{1/4}$. We then have

$$\begin{aligned}
\frac{\partial u}{\partial x_1} &= \frac{x_1}{2} (x_1^2 + x_2^2)^{-3/4} \\
\frac{\partial^2 u}{\partial x_1^2} &= \frac{1}{2} (x_1^2 + x_2^2)^{-3/4} - \frac{3}{4} x_1^2 (x_1^2 + x_2^2)^{-7/4} = \\
&= \frac{2(x_1^2 + x_2^2) - 3x_1^2}{4(x_1^2 + x_2^2)^{7/4}}
\end{aligned}$$

We then have

$$\begin{aligned}
\int_B \left(\frac{\partial^2 u}{\partial x_1^2} \right)^2 dx &= \int_B \frac{(2(x_1^2 + x_2^2) - 3x_1^2)^2}{16(x_1^2 + x_2^2)^{7/2}} dx = \int_0^{2\pi} \int_0^1 \frac{(2r^2 - 3r^2 \cos^2 \theta)^2}{16r^7} r dr d\theta = \\
&= \int_0^{2\pi} \int_0^1 \frac{r^5 (2 - 3 \cos^2 \theta)^2}{16r^7} dr d\theta = \underbrace{\int_0^1 \frac{1}{r^2} dr}_{\left[\frac{-1}{r} \right]_0^1 \text{ diverges}} \cdot \underbrace{\int_0^{2\pi} \frac{(2 - 3 \cos^2 \theta)^2}{16} d\theta}_{< \infty},
\end{aligned}$$

so u is not in $H^2(B)$. According to the last exercise, $\int_B \left(\frac{\partial u}{\partial x_1} \right)^2 dx$ converges. To see it again:

$$\begin{aligned}
\int_B \left(\frac{\partial u}{\partial x_1} \right)^2 dx &= \frac{1}{2} \int_B \left(\frac{x_1}{(x_1^2 + x_2^2)^{3/4}} \right)^2 dx = \frac{1}{2} \int_B \frac{x_1^2}{(x_1^2 + x_2^2)^{3/2}} dx = \\
&= \frac{1}{2} \int_0^{2\pi} \int_0^1 \frac{r^2 \cos^2 \theta}{r^3} r dr d\theta = \frac{1}{2} \int_0^{2\pi} \int_0^1 \cos^2 \theta dr d\theta < \infty.
\end{aligned}$$

55. Prove the Poincaré-Friedrich inequality:

$$\|v\|_{L_2(\Omega)}^2 \leq C_\Omega \left(\|v\|_{L_2(\Gamma)}^2 + \|\nabla v\|_{L_2(\Omega)}^2 \right), \quad \forall v \in H^1(\Omega),$$

where $\Omega \subset \mathbb{R}^n$ is bounded with smooth boundary Γ .

Solution. Take $\varphi \in C^2(\mathbb{R}^n)$ s.t. $\Delta \varphi = 1$, e.g. $\varphi = \frac{1}{4}(x^2 + y^2)$ in $\mathbb{R}^2$ or $\varphi = \frac{1}{2n}|x|^2$ in $\mathbb{R}^n$. Then

$$\begin{aligned}
\|u\|_{L_2(\Omega)}^2 &= \int_\Omega u^2 \Delta \varphi dx = \left\{ \begin{array}{l} \text{Green's formula:} \\ \int_\Omega (\Delta u) v = \int_{\partial\Omega} (\nabla u \cdot n) v - \int_\Omega \nabla u \cdot \nabla v \end{array} \right\} = \\
&= \int_\Gamma u^2 \nabla \varphi \cdot n - \int_\Omega 2u \nabla u \cdot \nabla \varphi \leq \left\{ \begin{array}{l} \varphi \in C^2(\mathbb{R}^n), \\ \Omega \text{ bounded} \end{array} \right\} \leq \\
&\leq c \|u\|_{L_2(\Gamma)}^2 + 2c \|u\|_{L_1(\Omega)} \|\nabla u\|_{L_1(\Omega)} = \\
&= c \|u\|_{L_2(\Gamma)}^2 + 2c \left\| \sqrt{\varepsilon} u \cdot \frac{1}{\sqrt{\varepsilon}} |\nabla u| \right\|_{L_1(\Omega)} \leq
\end{aligned}$$

$$\begin{aligned}
&\leq \{ 2ab \leq a^2 + b^2 \} \leq c \|u\|_{L_2(\Gamma)}^2 + c \left\| \varepsilon u^2 + \frac{1}{\varepsilon} |\nabla u|^2 \right\|_{L_1(\Omega)} \leq \\
&\leq \{ \int a^2 + b^2 dx = \int a^2 dx + \int b^2 dx \} \leq \\
&\leq c \|u\|_{L_2(\Gamma)}^2 + \underbrace{c\varepsilon \|u\|_{L_2(\Omega)}^2}_{*} + \frac{c}{\varepsilon} \|\nabla u\|_{L_2(\Omega)}^2.
\end{aligned}$$

Now, move (*) to the other side and choose $\varepsilon = \frac{1}{2c}$. We get

$$\|u\|_{L_2(\Omega)}^2 \leq C \left(\|u\|_{L_2(\Gamma)}^2 + \|\nabla u\|_{L_2(\Omega)}^2 \right).$$

56. Verify the trace theorem: If Ω is a bounded domain with boundary Γ , then there is a constant C such that

$$\|v\|_{L_2(\Gamma)} \leq C \|v\|_{H^1(\Omega)}, \quad \forall v \in H^1(\Omega).$$

Solution. Choose $\varphi \in C^2(\mathbb{R})$ s.t. $n \cdot \nabla \varphi = 1$ on $\partial\Omega$.

$$\begin{aligned}
\int_{\Omega} u^2 \Delta \varphi &= \left\{ \begin{array}{l} \text{Green's formula:} \\ \int_{\Omega} (\Delta u) v = \int_{\partial\Omega} (\nabla u \cdot n) v - \int_{\Omega} \nabla u \cdot \nabla v \end{array} \right\} = \\
&= \int_{\partial\Omega} u^2 \underbrace{\nabla \varphi \cdot n}_{=1} - \int_{\Omega} (2u \nabla u) \cdot \nabla \varphi \rightarrow \\
\int_{\partial\Omega} u^2 &\leq \int_{\Omega} u^2 |\Delta \varphi| + \int_{\Omega} 2|u| |\nabla u| |\nabla \varphi| \rightarrow \left\{ \begin{array}{l} \varphi \in C^2(\mathbb{R}), \\ \Omega \text{ bounded} \end{array} \right\} \\
\int_{\partial\Omega} u^2 &\leq c \int_{\Omega} u^2 + 2c \int_{\Omega} |u| |\nabla u| \rightarrow \\
&\{ 2ab \leq a^2 + b^2 \} \rightarrow \\
\|u\|_{L_2(\partial\Omega)}^2 &\leq C \left(\|u\|_{L_2(\Omega)}^2 + \|\nabla u\|_{L_2(\Omega)}^2 \right) = C \|u\|_{H^1(\Omega)}^2.
\end{aligned}$$

57. Show that there is no constant C s.t. $\|v\|_{L_2(\Gamma)} \leq C \|v\|_{L_2(\Omega)}, \forall v \in L_2(\Omega)$. **Solution.** We have to construct a counter example. Let Ω be the unit disc B in $\mathbb{R}^2$. We want to construct a series of functions that grow on the border but where the area under the functions converge to some number. We picture the function in figure 1.

Consider the function

$$f_{\varepsilon} = \frac{|x|}{(1 - |x| + \varepsilon)^{1/4}}.$$

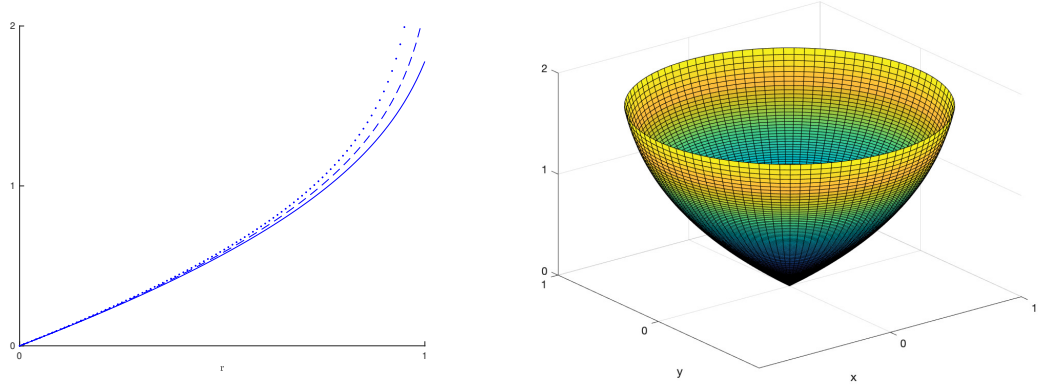


Figure 1: Picture this function.

We then have

$$f_\varepsilon \Big|_{\partial\Omega} = \frac{1}{\varepsilon^{1/4}} \quad \Rightarrow \quad \int_{\partial\Omega} f_\varepsilon^2 = \frac{2\pi}{\varepsilon^{1/2}} \rightarrow \infty, \varepsilon \rightarrow 0^+,$$

but

$$\begin{aligned} \int_{\Omega} f_\varepsilon^2 &= \{ \text{pol. coord.} \} = \int_0^{2\pi} \int_0^1 \left(\frac{r}{(1-r+\varepsilon)^{1/4}} \right)^2 r dr d\theta = \\ &= 2\pi \int_0^1 \frac{r^3}{(1-r+\varepsilon)^{1/2}} dr = \dots = \\ &= \frac{4\pi}{35} \left(\underbrace{16(\varepsilon+1)^{7/2}}_{\rightarrow 1} - \underbrace{\sqrt{\varepsilon}(16\varepsilon^3 + 56\varepsilon^2 + 70\varepsilon + 35)}_{\rightarrow 0} \right) \rightarrow \frac{\pi}{140}, \varepsilon \rightarrow 0^+. \end{aligned}$$

58. Consider the convection-diffusion problem of finding $u \in H_0^1(\Omega)$ s.t.

$$\begin{aligned} -\nabla \cdot (\varepsilon \nabla u + \beta u) &= f, & \Omega \subset \mathbb{R}^2 \text{ bounded, convex, polygonal,} \\ u &= 0, & \text{on } \partial\Omega, \end{aligned}$$

where $\varepsilon > 0$, $\beta = (\beta_1(x), \beta_2(x))$, $f = f(x)$.

- Determine conditions in Lax-Milgram that guarantee existence and uniqueness of solution. This involves:
 - Boundedness of $F(v)$: show that $|F(v)| \leq C \|v\|_{H^1(\Omega)}$.

- Boundedness of $a(u, v)$: show that $|a(u, v)| \leq C \|u\|_{H^1(\Omega)} \|v\|_{H^1(\Omega)}$.
- Coercivity of $a(v, v)$: (see definition 2.21) show that $a(v, v) \geq C \|v\|_{H^1(\Omega)}^2$.

- Prove stability estimate for u in terms of $\|f\|_{L_2(\Omega)}$, ε , $\text{diam}(\Omega)$.

Solution. Weak formulation:

$$\begin{aligned}
& - \int_{\Omega} \nabla \cdot (\varepsilon \nabla u + \beta u) v = \int_{\Omega} f v \rightarrow \left\{ \begin{array}{l} \text{Green's formula:} \\ \int_{\Omega} (\Delta u) v = \int_{\partial\Omega} (\nabla u \cdot n) v - \int_{\Omega} \nabla u \cdot \nabla v \end{array} \right\} \rightarrow \\
& - \int_{\partial\Omega} (\varepsilon \nabla u + \beta u) \cdot n \underbrace{v}_{=0 \text{ on } \partial\Omega} + \underbrace{\int_{\Omega} (\varepsilon \nabla u + \beta u) \cdot \nabla v}_{:=a(u,v)} = \underbrace{\int_{\Omega} f v}_{:=F(v)} \\
& \int_{\Omega} (\varepsilon \nabla u + \beta u) \cdot \nabla v = \int_{\Omega} f v
\end{aligned}$$

- **Boundedness of $F(v)$:**

$$\begin{aligned}
& \int_{\Omega} f v \leq \{\text{Cauchy-Schwarz}\} \leq \|f\|_{L_2(\Omega)} \|v\|_{L_2(\Omega)} \leq \|f\|_{L_2(\Omega)} \|v\|_{H^1(\Omega)} < \infty \\
& \text{if } f \in L_2(\Omega).
\end{aligned}$$

- **Boundedness of $a(u, v)$:**

$$\begin{aligned}
|a(u, v)| & \leq \int_{\Omega} |\varepsilon \nabla u + \beta u| |\nabla v| \, dx \leq \int_{\Omega} (\varepsilon |\nabla u| + |\beta| |u|) |\nabla v| \, dx \leq \\
& \leq \left(\int_{\Omega} (\varepsilon |\nabla u| + |\beta| |u|)^2 \, dx \right)^{1/2} \left(\int_{\Omega} |\nabla v|^2 \, dx \right)^{1/2} \leq \\
& \leq \max(\varepsilon, \|\beta\|_{L_{\infty}(\Omega)}) \left(\int_{\Omega} (|\nabla u| + |u|)^2 \, dx \right)^{1/2} \|v\|_{H^1(\Omega)} \leq \\
& \leq \{ (a+b)^2 \leq 2(a^2 + b^2) \} \leq \\
& \leq \max(\varepsilon, \|\beta\|_{L_{\infty}(\Omega)}) \left(\int_{\Omega} 2(|\nabla u|^2 + |u|^2) \, dx \right)^{1/2} \|v\|_{H^1(\Omega)} = \\
& = \max(\varepsilon, \|\beta\|_{L_{\infty}(\Omega)}) \sqrt{2} \|u\|_{H^1(\Omega)} \|v\|_{H^1(\Omega)}.
\end{aligned}$$

Thus, $\beta \in L_{\infty}(\Omega)$ gives us boundedness of $a(u, v)$.

- **Coercivity of $a(v, v)$:**

$$\begin{aligned}
a(v, v) &= \int_{\Omega} (\varepsilon |\nabla v|^2 + v\beta \cdot \nabla v) dx = \\
&= \int_{\Omega} (\varepsilon |\nabla v|^2 + v(\beta_1 \partial_x v + \beta_2 \partial_y v)) dx = \{ \partial_x(v^2) = 2v \partial_x v \} = \\
&= \int_{\Omega} (\varepsilon |\nabla v|^2 + \frac{1}{2}(\beta_1 \partial_x(v^2) + \beta_2 \partial_y(v^2))) dx = \\
&= \left\{ \begin{array}{l} \text{Partial integration:} \\ \int \int \beta_1 \partial_x(v^2) dx dy = \\ \int ([\beta_1 v^2] - \int \partial_x \beta_1 v^2 dx) dy = \\ = - \int \int \partial_x \beta_1 v^2 dx dy \\ \text{since } v \in H_0^1(\Omega) \end{array} \right\} = \\
&= \int_{\Omega} (\varepsilon |\nabla v|^2 - \frac{1}{2} \nabla \cdot \beta v^2) dx \geq \\
&\geq \{ \text{ if } -\frac{1}{2} \nabla \cdot \beta \geq c > 0 \} \geq \int_{\Omega} \varepsilon |\nabla v|^2 + cv^2 dx = \\
&= \varepsilon \|\nabla v\|_{H^1(\Omega)}^2 + c \|v\|_{L_2(\Omega)}^2 \geq \min(\varepsilon, c) \|v\|_{H^1(\Omega)}^2.
\end{aligned}$$

So $\nabla \cdot \beta \leq -2c$ for some $c > 0$ gives coercivity.

- **Stability estimate:** We have to bound u in some norm. We note that, from above, we have

$$\begin{aligned}
a(u, u) &= L(u) \leq c_1 \|u\|_{H_0^1(\Omega)}, & c_1 &= \|f\|_{L_2(\Omega)} \\
a(u, u) &\geq c_2 \|u\|_{H^1(\Omega)}^2, & c_2 &= \min(\varepsilon, c),
\end{aligned}$$

giving us

$$\begin{aligned}
c_2 \|u\|_{H^1(\Omega)}^2 &\leq c_1 \|u\|_{H^1(\Omega)} \Rightarrow \\
\|u\|_{H^1(\Omega)} &\leq \frac{c_1}{c_2} = \frac{\|f\|_{L_2(\Omega)}}{\min(\varepsilon, c)}.
\end{aligned}$$