

Recall:

• Wave eq.

$$\begin{cases} u_{tt} - \Delta u = f & \text{in } \Omega \subset \mathbb{R}^d \\ u = 0 & \text{on } \partial\Omega \\ u(\cdot, 0) = u_0, u_t(\cdot, 0) = v_0 & \text{in } \Omega \end{cases}$$

• (VF) Find u s.t. $(u_{tt}, v) + (\nabla u, \nabla v) = (f, v) \quad \forall v$

• (FE) Find u_h s.t. $(u_{h,tt}, \chi) + (\nabla u_h, \nabla \chi) = (f, \chi) \quad \forall \chi$

Th: $\|u_h(t) - u(t)\|_{L^2(\Omega)} \leq C \cdot \left(\|\pi_h u_0 - R_h u_0\|_1 + \|\pi_h v_0 - R_h v_0\|_{L^2} \right) + C h^2 \left(\|u(t)\|_{H^2} + \int_0^t \|u_{tt}(s)\|_{H^2} ds \right).$

Proof:

$$\bullet u_h - u = \underbrace{(u_h - R_h u)}_{\theta} + \underbrace{(R_h u - u)}_{\xi}$$

$$\bullet \|g(t)\|_{L^2} + h \|g(t)\|_1 \leq C h^2 \|u(t)\|_{H^2}$$

$$\|g_t(t)\|_{L^2} \leq C h^2 \|u_t(t)\|_{H^2}, \quad \|g_{tt}(t)\|_{L^2} \leq C h^2 \|u_{tt}(t)\|_{H^2}.$$

$$\bullet \underbrace{\|\theta_t(t)\|_{L^2}^2}_{\geq 0} + \underbrace{|\theta(t)|_1^2}_{\geq 0} \leq \|\theta_t(0)\|_{L^2}^2 + |\theta(0)|_1^2 + 2 \int_0^t \|g_{tt}(s)\|_{L^2} \underbrace{\|\theta_t(s)\|_{L^2}}_{\leq \max_{0 \leq s \leq t} \|\theta_t(s)\|_{L^2}} ds$$

$$\begin{aligned} & \stackrel{t \leq T}{\leq} \|\theta_t(0)\|_{L^2}^2 + |\theta(0)|_1^2 + 2 \left(\int_0^T \|g_{tt}(s)\|_{L^2} ds \right)^2 \\ & \quad + \frac{1}{2} \left(\underbrace{\max_{0 \leq s \leq t} \|\theta_t(s)\|_{L^2}}_{\text{to left}} \right)^2 \quad \forall t \in [0, T] \end{aligned}$$

This gives:

$$\begin{aligned} \frac{1}{2} \left(\max_{0 \leq s \leq t} \|\theta_t(s)\|_{L^2} \right)^2 & \leq \|\theta_t(0)\|_{L^2}^2 + |\theta(0)|_1^2 + \\ & \quad + 2 \left(\int_0^T \|g_{tt}(s)\|_{L^2} ds \right)^2 \end{aligned}$$

All together, we obtain:

$$\underbrace{\|\Theta_t(t)\|_{L^2}^2}_{\geq 0} + \underbrace{\|\Theta(t)\|_1^2}_{\leq 4\|\nabla\Theta(t)\|_{L^2}^2} \leq 2\|\Theta_t(0)\|_{L^2}^2 + 2\|\Theta(0)\|_1^2 + 4\left(\int_0^T \|\mathcal{S}_{t,t}(s)\|_{L^2} ds\right)^2$$

This is valid for all $t \in [0, T]$, in particular $t=T$, arbitrary.

• Finally, we can bound the error of the FCH as follows:

$$\|u_h(t) - u(t)\|_{L^2} \stackrel{\Delta}{\leq} \|\Theta(t)\|_{L^2} + \|\mathcal{S}(t)\|_{L^2} \stackrel{\text{Poincaré ineq.}}{\leq} C \cdot \|\Theta(t)\|_1 + \|\mathcal{S}(t)\|_{L^2} \leq$$

$$\stackrel{\uparrow \text{above second point}}{\leq} C \cdot \left(\|\Theta_t(0)\|_{L^2} + \|\Theta(0)\|_1 + \int_0^t \|\mathcal{S}_{t,t}(s)\|_{L^2} ds \right) + \|\mathcal{S}(t)\|_{L^2} \leq$$

$$\stackrel{\uparrow \text{Def } \Theta(0), \Theta_t(0)}{\leq} C \cdot \left(\underbrace{\|\pi_h v_0 - R_h v_0\|_{L^2}}_{\geq 0} + \underbrace{\|u_h(0) - R_h u_0\|_1}_{\leq \|\pi_h u_0\|_1} + \int_0^t C h^2 \|u_{t,t}(s)\|_{H^2} ds \right) +$$

above first point

$$+ C h^2 \|u(t)\|_{H^2} \leq$$

$$\leq C \cdot \left(\|\pi_h v_0 - R_h v_0\|_{L^2} + \|\pi_h u_0 - R_h u_0\|_1 + h^2 \int_0^t \|u_{t,t}(s)\|_{H^2} ds + h^2 \|u(t)\|_{H^2} \right).$$

Chapter XIV: The finite element

Goal: Give formal definition of FEM

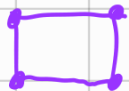
1) Formal definition of finite element:

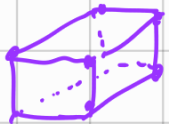
Def: (Ciarlet, 1978) A finite element consists of a triplet (K, P, Σ') , where

- $K \subset \mathbb{R}^d$ is polygon
- P is a polynomial function space (of finite dimension)
- Σ' is a ^(unisolvent) set of linear functionals on P
 $\Sigma' = \{L_1, L_2, \dots, L_n\}$, where $n = \dim(P)$.

Ex: • $K \rightsquigarrow$ element domain

1d  line, ...

2d  triangle,  quadrilateral, ...

3d  bricks, ...

...

- $P \rightsquigarrow$ space of shape functions

$P^{(1)}(K) \rightsquigarrow$ set of polynomials of degree ≤ 1 on K

$P^{(2)}(K) \rightsquigarrow$ polyn. degree ≤ 2 on K

...

- $\Sigma_i \rightsquigarrow$ set of nodal variables;

This uniquely specify the shape functions on each element K as well as the behaviour of these functions between adjacent elements.

Ex: 1d Lagrange $P^{(p)}$ elements:

Let $a < b$, consider distinct points

$a = x_0 < x_1 < x_2 < \dots < x_p = b$, hat functions

Let $K = [a, b]$



[only ~~x~~ a]
 $l=1$

Let $P = P^{(p)}(K) \rightsquigarrow$ set of polynomials of degree $\leq p$ defined on $K = [a, b]$.

Let $\Sigma_i = \{L_0, L_1, L_2, \dots, L_p\}$, where $L_j: P \rightarrow \mathbb{R}$ are

defined by $L_j(f) = f(x_j) \quad \forall f \in P.$

Now, we know that Lagrange polynomials

$$\lambda_j(x) = \frac{1}{\prod_{\substack{j=0 \\ j \neq i}}^l \frac{x - x_j}{x_i - x_j}}$$

satisfy $\lambda_i(x_j) = \delta_{ij} = \begin{cases} 0 & \text{if } i \neq j \\ 1 & \text{if } i = j \end{cases}$

Observe then, that $L_j(\lambda_i) = \lambda_i(x_j) = \delta_{ij}$

$\leadsto \dots \leadsto$ this tells us that λ_j can be taken as

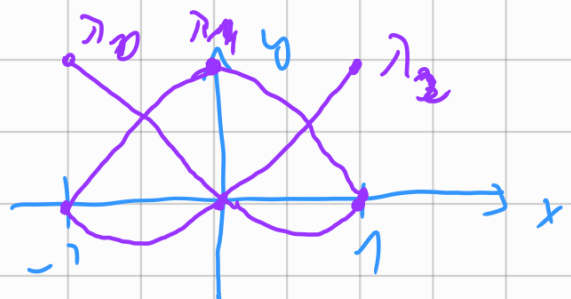
a basis for P and this exactly the

hat functions in the case $l=1$:



$l=1$

2 shape functions

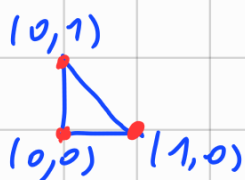


$l=2$

3 shape functions

Ex: 2d linear Lagrange elements:

Consider the reference triangle K



The space $P = P^{(1)}(K) \leadsto$ polyn. of degree ≤ 1 on K .

$\Sigma_1 = \{L_1, L_2, L_3\}$, where $L_j: P \rightarrow \mathbb{R}$ are defined by

$$L_1(f) = f(\underline{0}, 0), \quad L_2(f) = f(\underline{1}, 0), \quad L_3(f) = f(\underline{0}, 1)$$

Next, we determine the shape functions as follows:

$$S_j(x, y) = a_j + b_j x + c_j y \quad \text{for } j=1, 2, 3, (x, y) \in K,$$

and

$$L_i(S_j) = \delta_{ij} = \begin{cases} 1 & i=j \\ 0 & \text{else} \end{cases} \quad \text{for } i, j=1, 2, 3$$

The above provides a linear system of equations with solutions

$$S_1(x, y) = 1 - x - y$$

$$S_2(x, y) = x$$

$$S_3(x, y) = y$$

Remember that functions / shape functions from previous chapters

For 2d elements, one can also consider the following FE:

Ex:



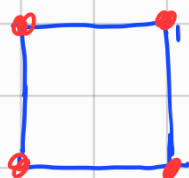
→ quadratic Lagrange elements

$$S_1(x, y) = 1 - 3x - 3y + 2x^2 + 4xy + 2y^2$$

$$S_2, S_3, S_4, S_5,$$

$$S_6(x, y) = 4x - 4x^2 - 4xy$$

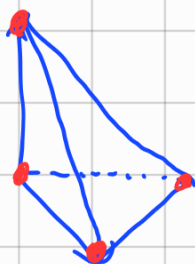
Ex:



→ bilinear quadrilateral elements

$$(a + bx)(c + dx)$$

Ex: In 3d:



→ linear Lagrange element on tetrahedron

Rem: • One can have other polynomials

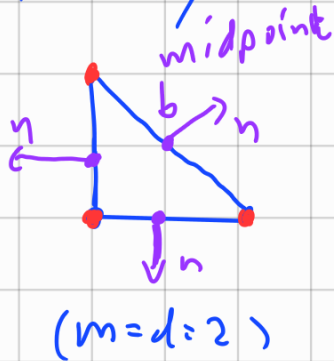
than Lagrange, for instance

Hermite polynomials (→ $C^1(\Omega)$ element

instead of $C^0(\Omega)$ element with Lagrange)

- One can get more exotic FE:

Morley elements / Morley-Wang-Xu / MWX



$$L_i(f) = f(\cdot)$$

$i = 1, 2, 3$

$$L_{i+3}(f) = n \cdot \nabla f(\cdot)$$

$i = 1, 2, 3$

$$(0, -1) \cdot \nabla f(1/2, 0)$$

$$f = 1 + x + y$$

$(m=d=2)$
 $\rightarrow$ get approximation in M^m in $\mathbb{R}^d$

$\rightarrow$ solid mechanics

2) Variational crimes:

In theory, we consider

$$(VF) \text{ Find } u \in U \text{ s.t. } a(u, v) = \ell(v) \quad \forall v \in U$$

In reality, one works with the problem

$$(FE) \text{ Find } u_h \in \underline{U}_h \text{ s.t. } \underline{a}_h(u_h, \chi) = \underline{\ell}_h(\chi) \quad \forall \chi \in \underline{V}_h,$$

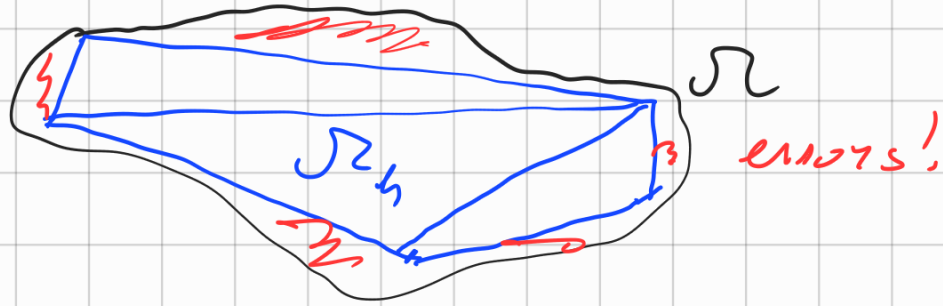
where the index h denotes, f.ex.,

$\rightarrow$ errors from approximations of integrals

$$\int_K f(x) dx \approx \underbrace{f(N_i)}_3 \quad |K|$$

errors !!

→ error in the mesh of Ω :



⇒

One has to deal with these

variational crimes (Strang, 1972) ...