

# Supervision Session 4

## Example Solution for Assignment 1

### Launch A1T2

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# Supervision Session 4 Topics

- Preliminary Feedback: Task 1, Assignment 1
- An example solution of Assignment 1
- Launch of Task 2 – Implementation

# Preliminary feedback on Assignment 1

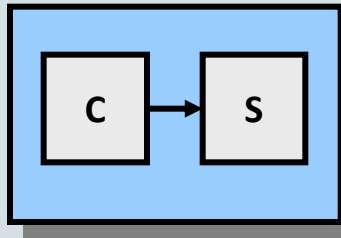
I have seen:

- Lack of consistency:
  - Between structural view and sequence diagram and deployment diagram.
- Too abstract/coarse grained components
  - If someone reads the architecture (documents), but not the requirements, they must be able to understand what the system does.

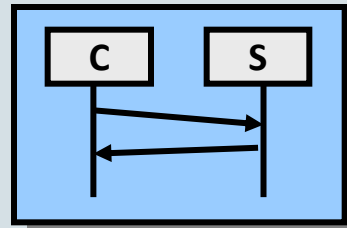
# Regular Client-Server

## Structure Diagram

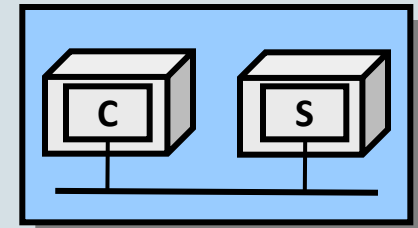
Component/Package/Class



## Sequence Diagram



## Deployment Diagram

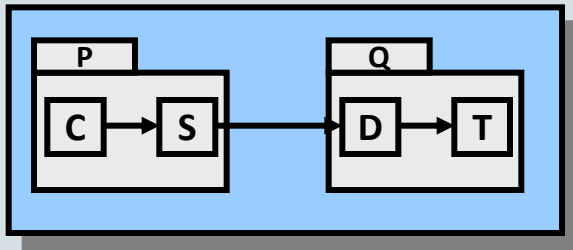




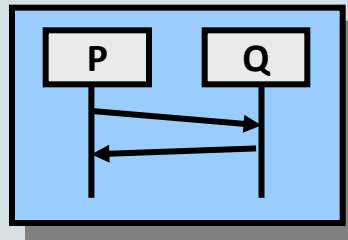
# Regular Client-Server

You can use packages as a unit of communication and deployment

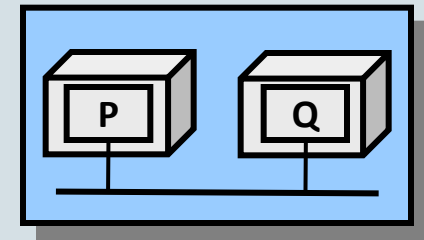
**Structure Diagram**



**Sequence Diagram**

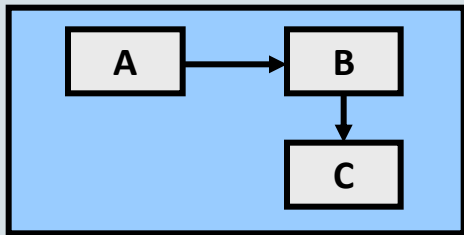


**Deployment Diagram**

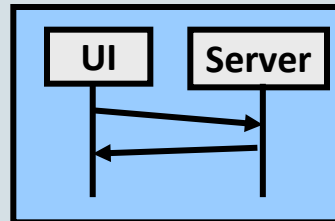


# Not Consistent:

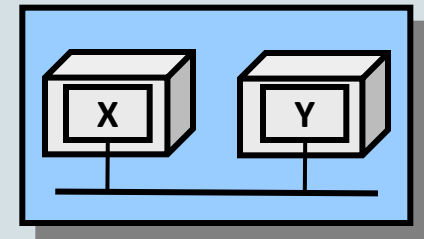
Structure Diagram



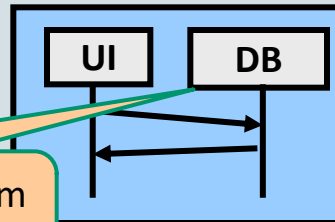
Sequence Diagram



Deployment Diagram

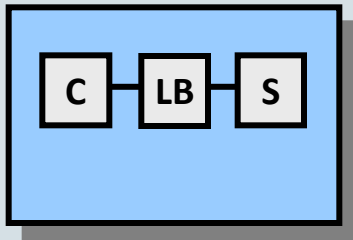


DB is not in the Structure diagram  
Also, naming too general!

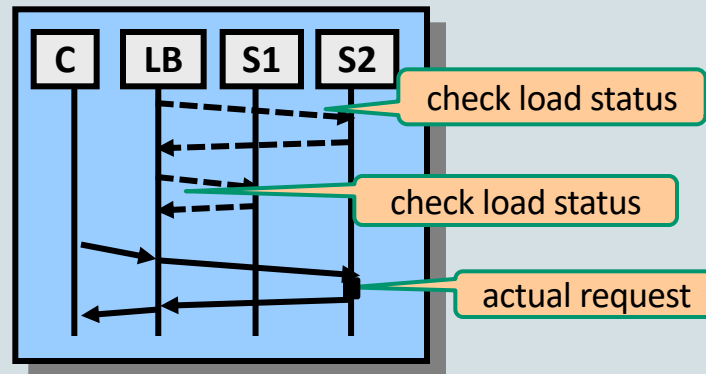


# Client-Server with load balancer

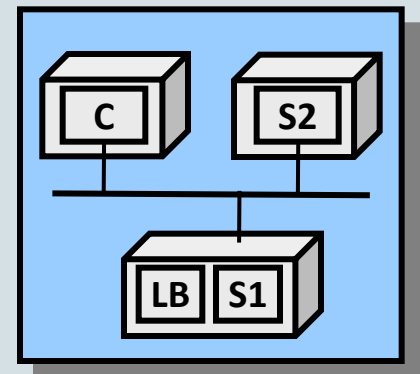
Structure Diagram



Sequence Diagram



Deployment Diagram



Many variations are possible

(Almost) the same tactic can also be used for improving availability

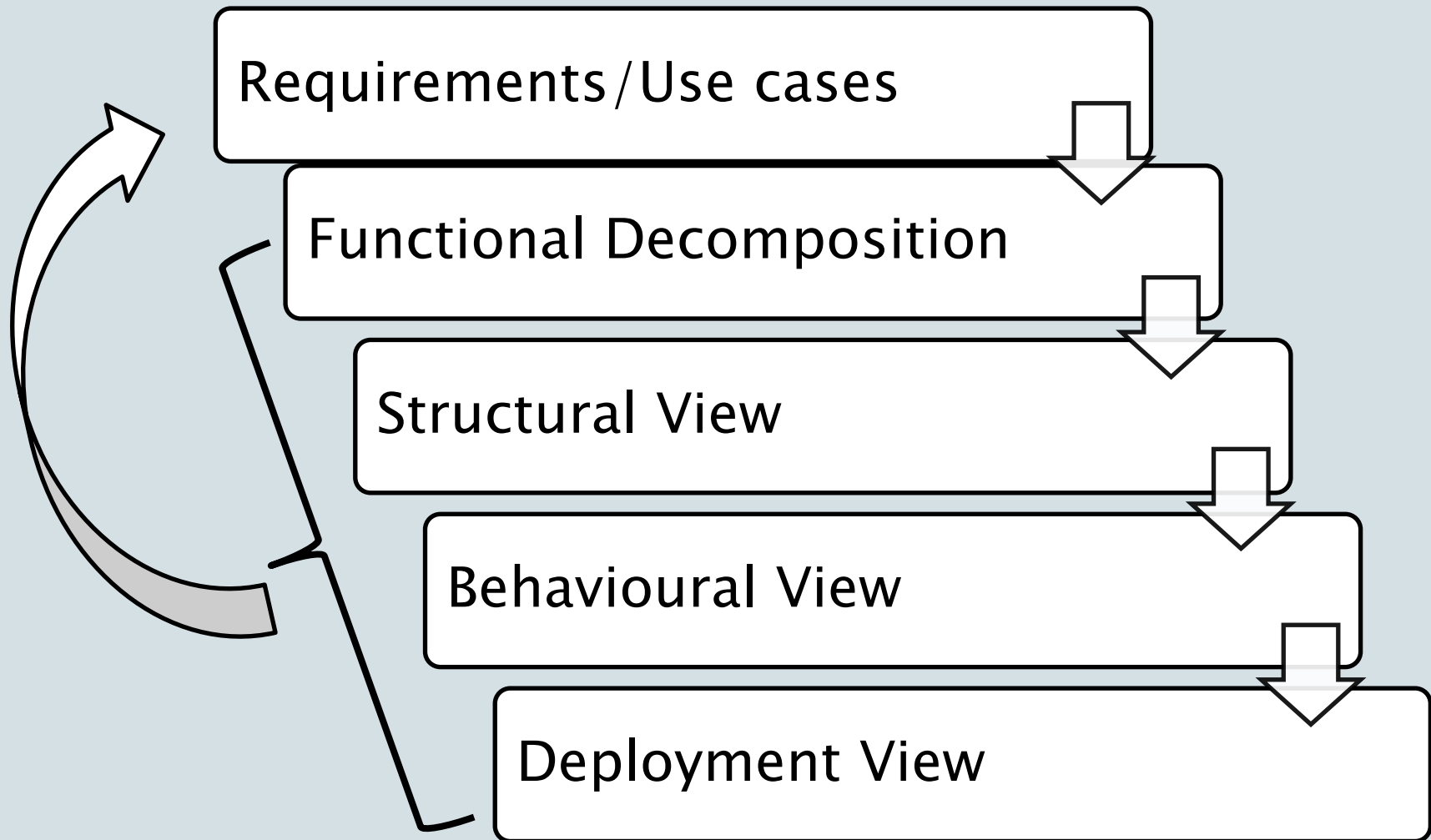
# EXAMPLE SOLUTION FOR ASSIGNMENT 1



# General Approach

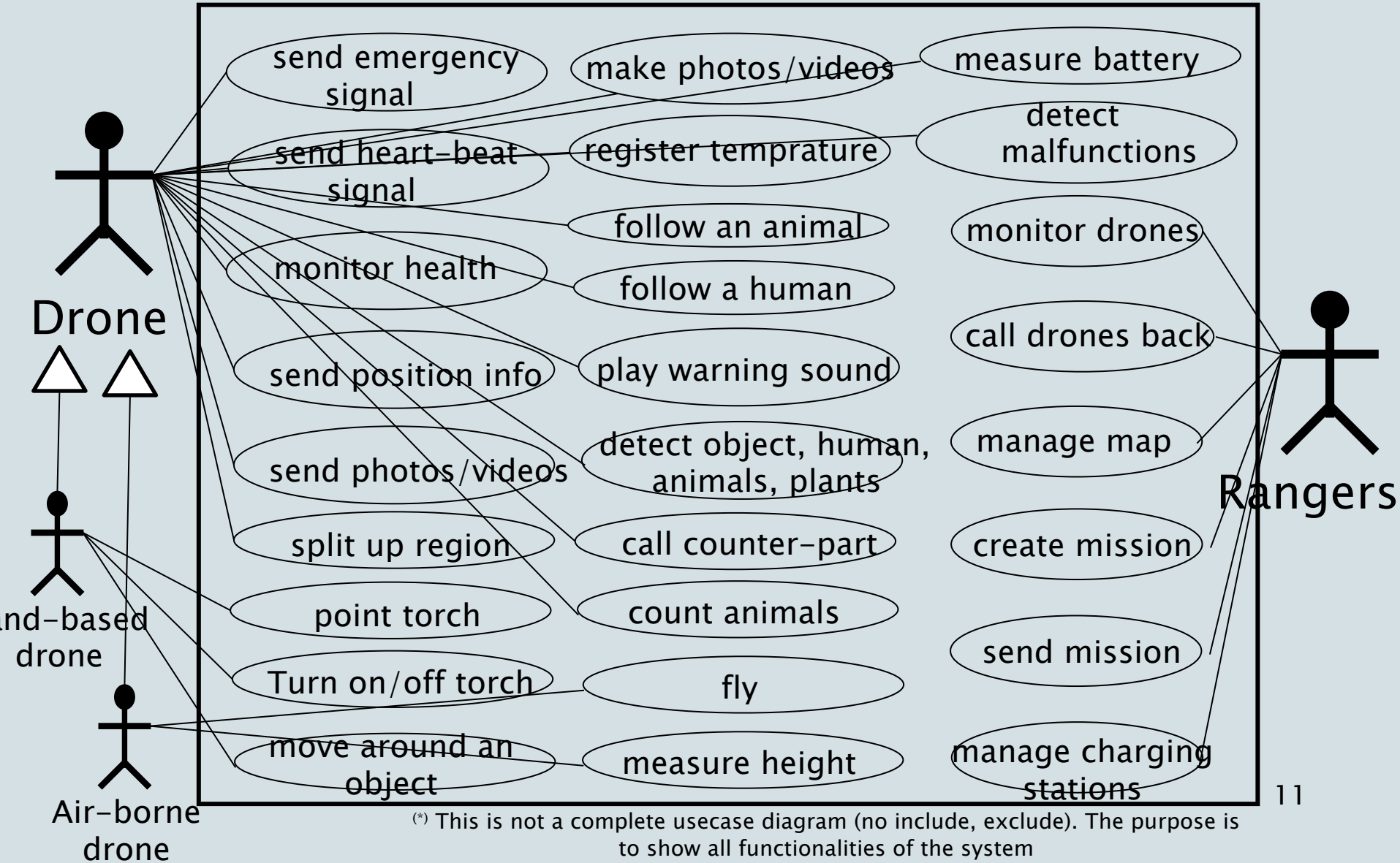
- Physical units on which software runs
  - Unmanned Drones
  - System at the Ground Station
  - Servers, Network, AI, ... } Depends on solutions
  - Charging Stations } Less important
  - Heart-beat Tags }

# Approach



# Usecases(\*)

# WASPP

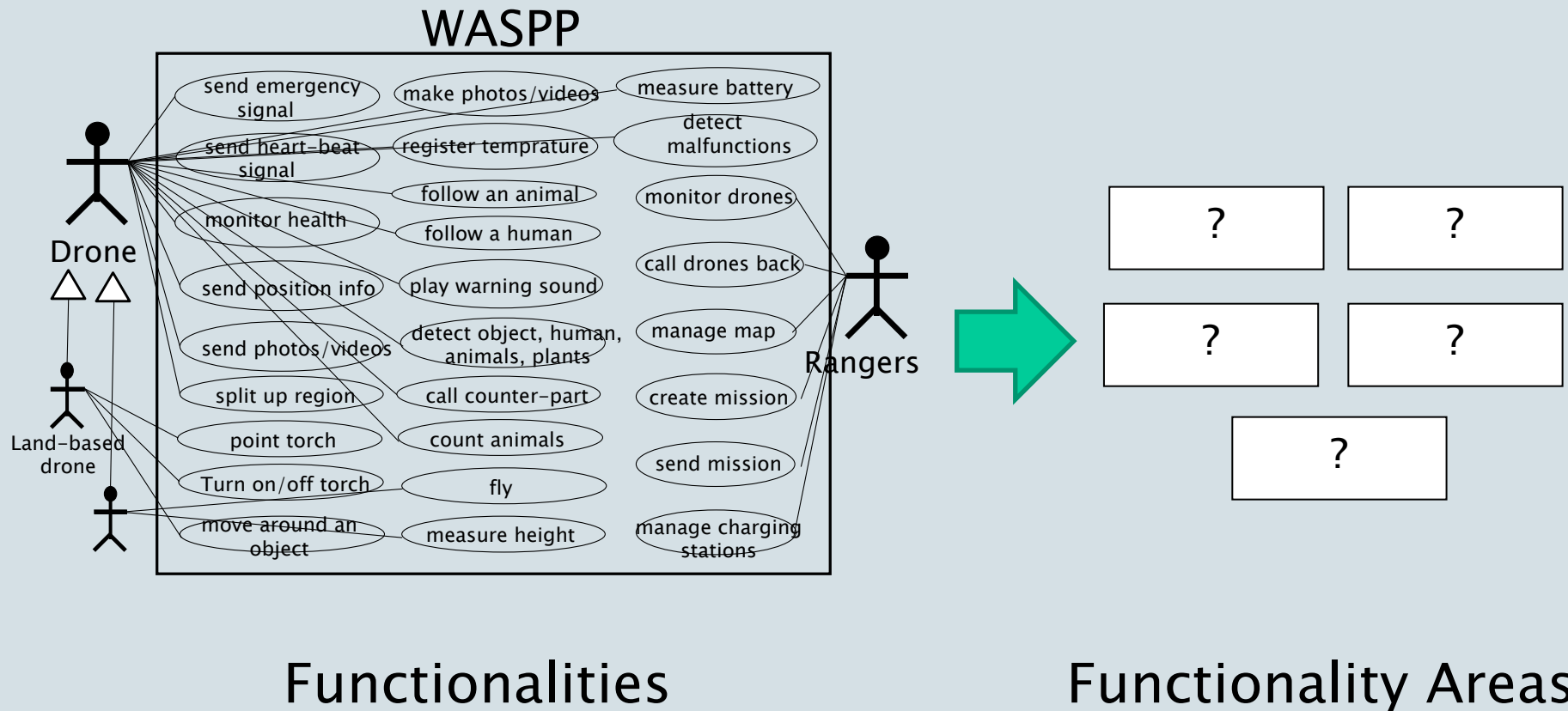


# Functional Decomposition

- Input: Func. Requirments, Usecases
- Output: Functional Decomp. Diagram
- Approach
  - Think of system's functionality
  - Show 'what' system does
- Common mistakes
  - Think too much about solutions
  - Show 'how' system does that



# Functional Decomposition Diagram – How to?



# A Functional Decomposition Approach

- **My approach**
  - Consider Drone and Ground Station as two main **functional sub-systems**
  - Aims: To achieve better separation of functionalities between the two sub-systems
- Other approaches (also correct)
  - Do NOT view Drone and Ground Station as **functional sub-systems**
  - Pitfalls:
    - Be careful with “same” functions
    - E.g. (Ground Station) monitors drone’s health <> (drone) measures its health. Both can be categorized under “Drone Management”.

# Functionality pool

send emergency  
signal

send heart-beat  
signal

monitor health

listen to incoming  
request

send position info

send photos/videos

split up region

point torch

Turn on/off torch

move around an  
object

make photos/videos

register temprature

follow an animal

follow a human

play warning sound

detect object, human,  
animals, plants

call counter-part

count animals

fly

measure height

measure battery

detect  
malfunctions

monitor drones

call drones back

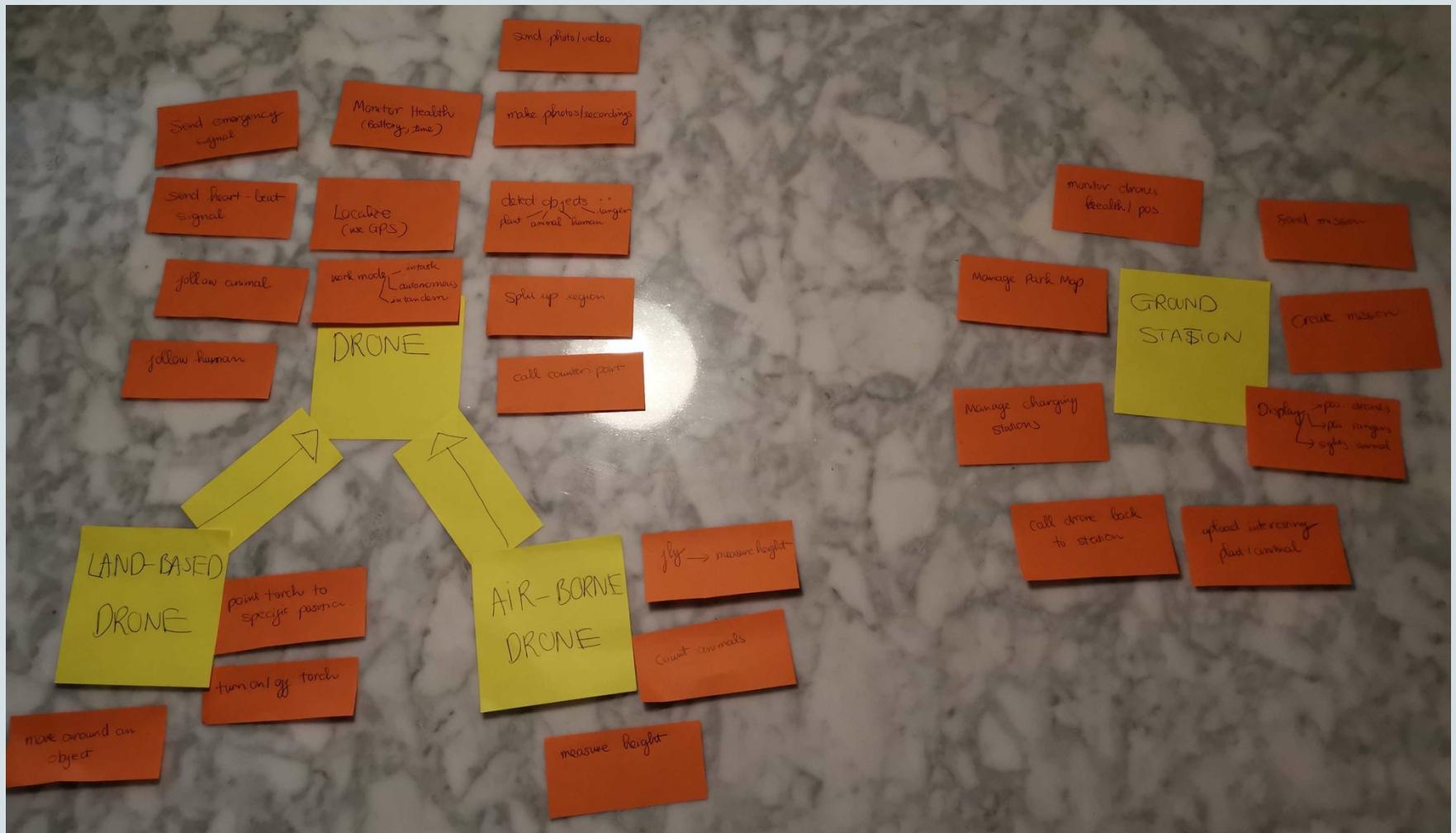
manage map

create mission

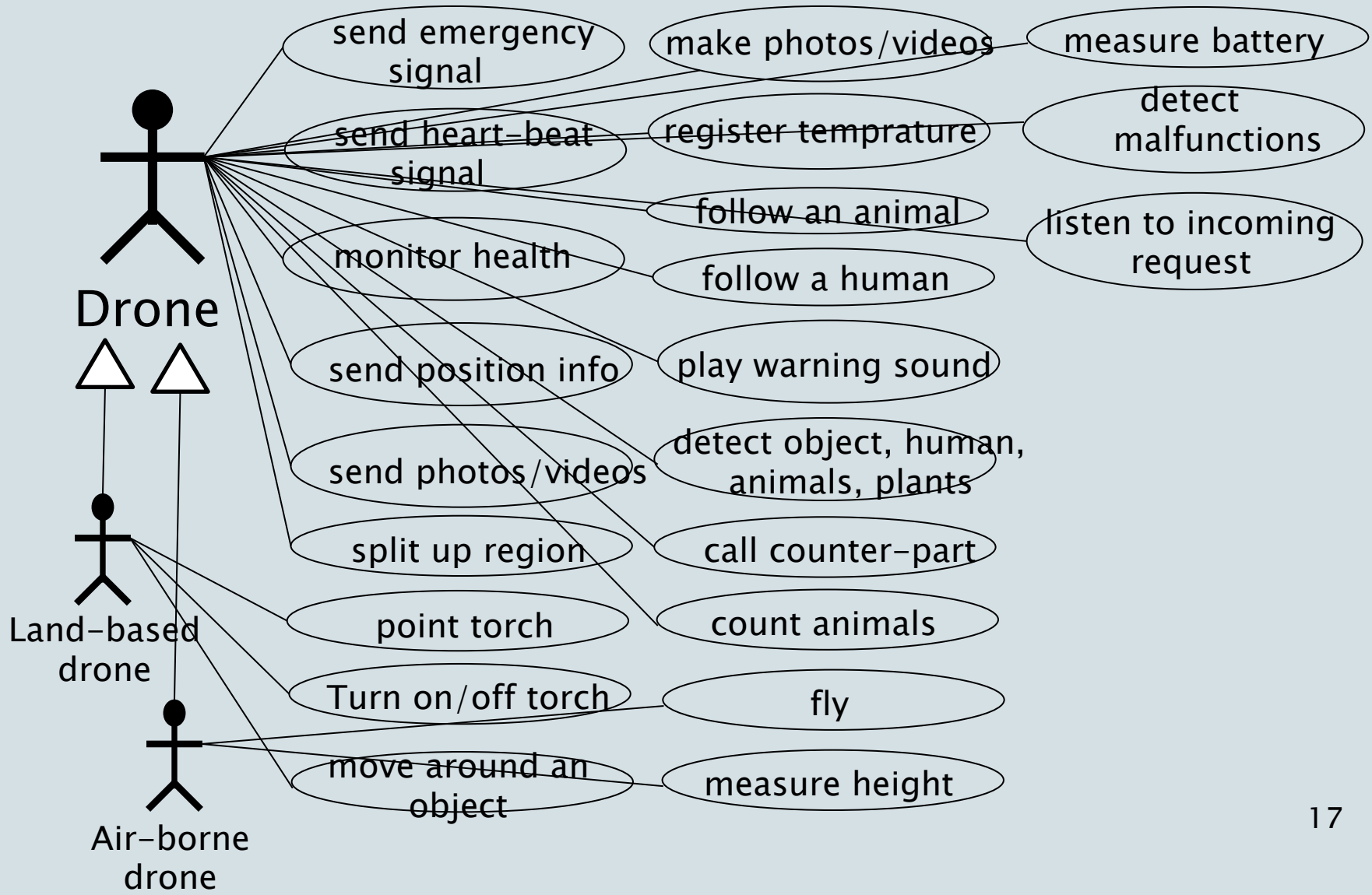
send mission

manage charging  
stations

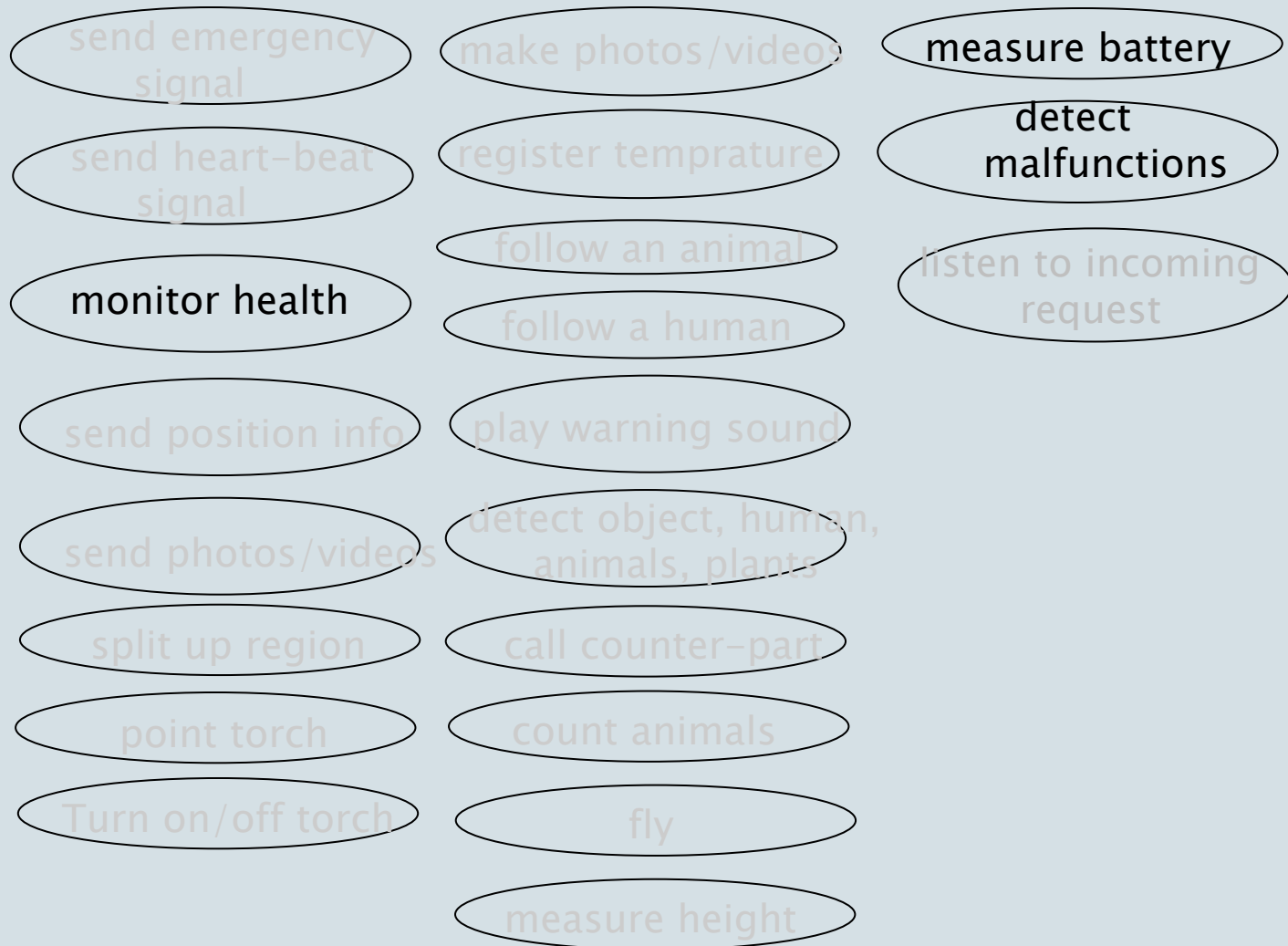
# Group work: Use post-it notes



# Drone Sub-system's Functionality



# Drone SS: Health Monitor



# Drone SS: Communication

send emergency  
signal

send heart-beat  
signal

listen to incoming  
request

send position info

send photos/videos

split up region

point torch

Turn on/off torch

make photos/videos

register temprature

follow an animal

follow a human

play warning sound

detect object, human,  
animals, plants

call counter-part

count animals

fly

measure height

# Drone SS: Surrounding Monitor

make photos/videos

register temprature

follow an animal

follow a human

detect object, human,  
animals, plants

split up region

call counter-part

point torch

count animals

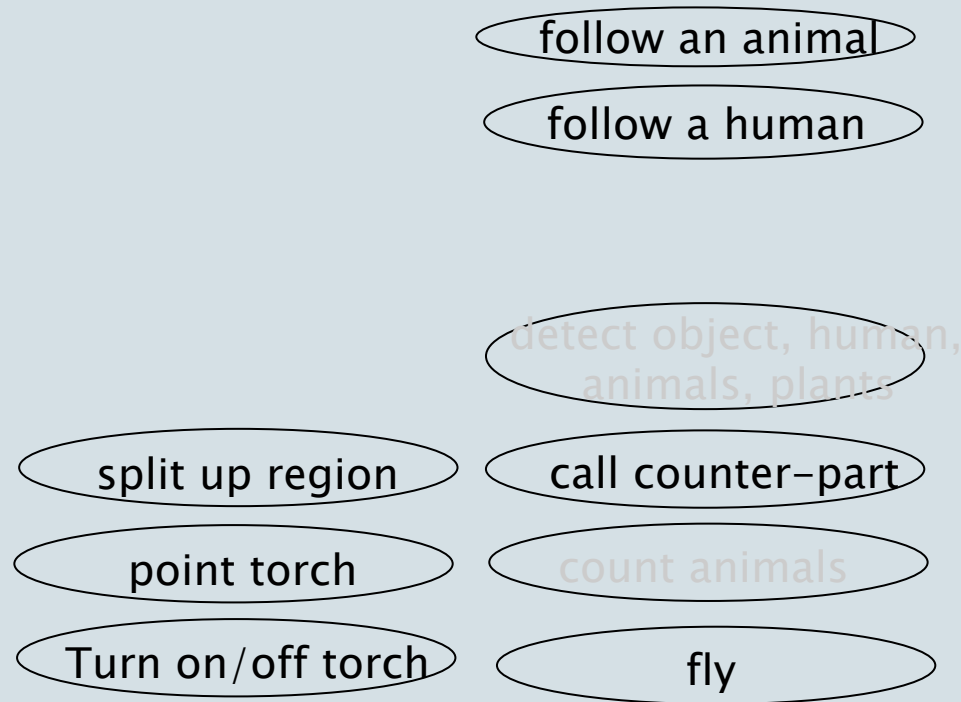
Turn on/off torch

fly

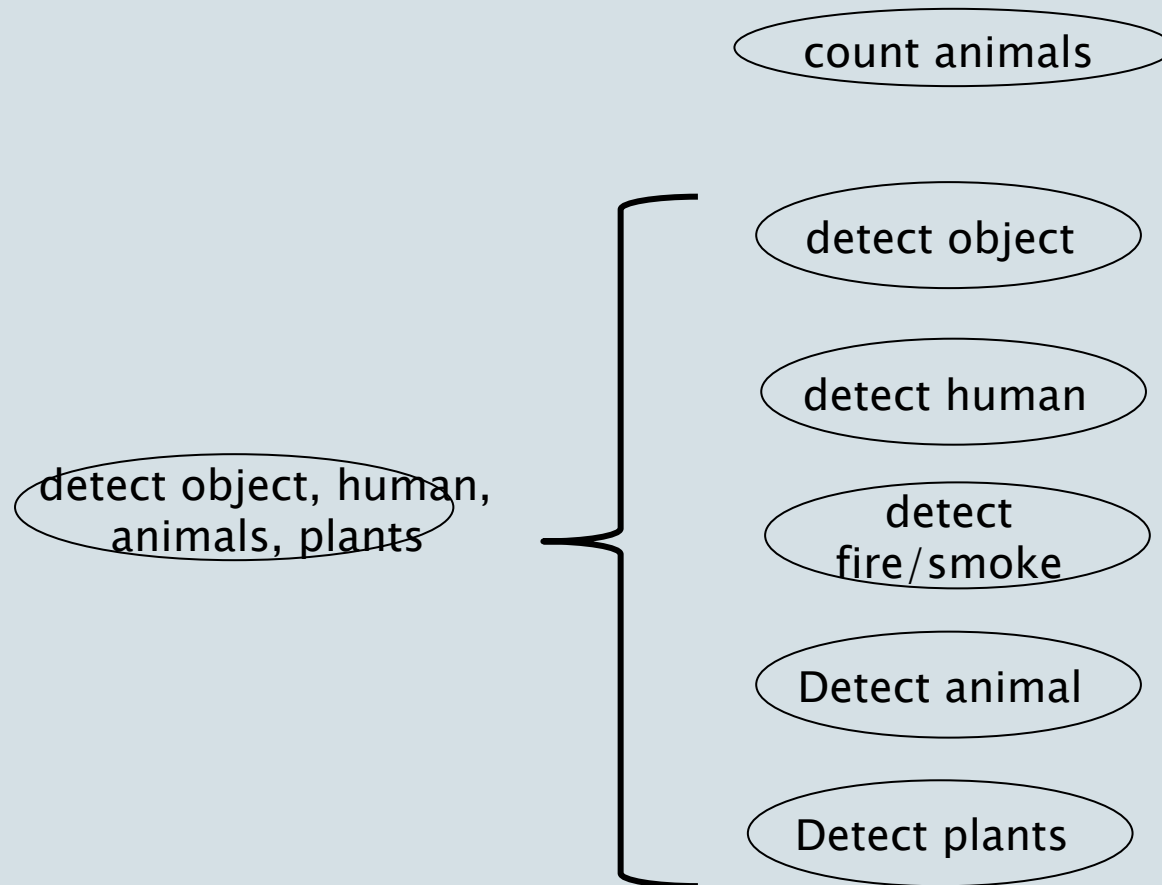
measure height



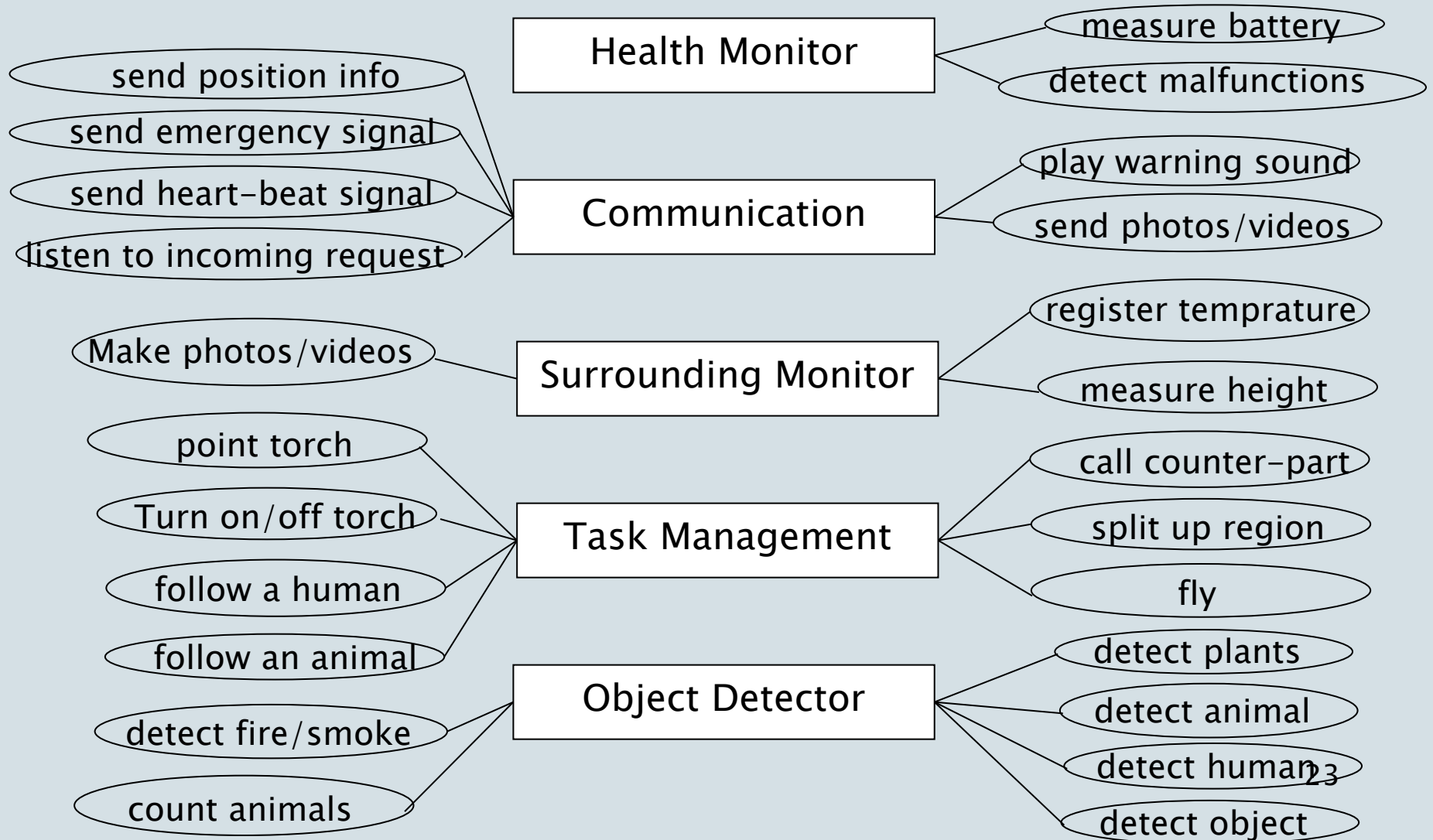
# Drone SS: Task Management



# Drone SS: Object Detector



# Drone Sub-system: Functionality Areas



# Drone Sub-system: Functionality Areas

Health Monitor

Monitor health (battery, operational time, fault) of the drone

Communication

Initiate and maintain communication between drones and other part of system

Surrounding Monitor

Monitor the condition of surrounding areas of the drones

Task Management

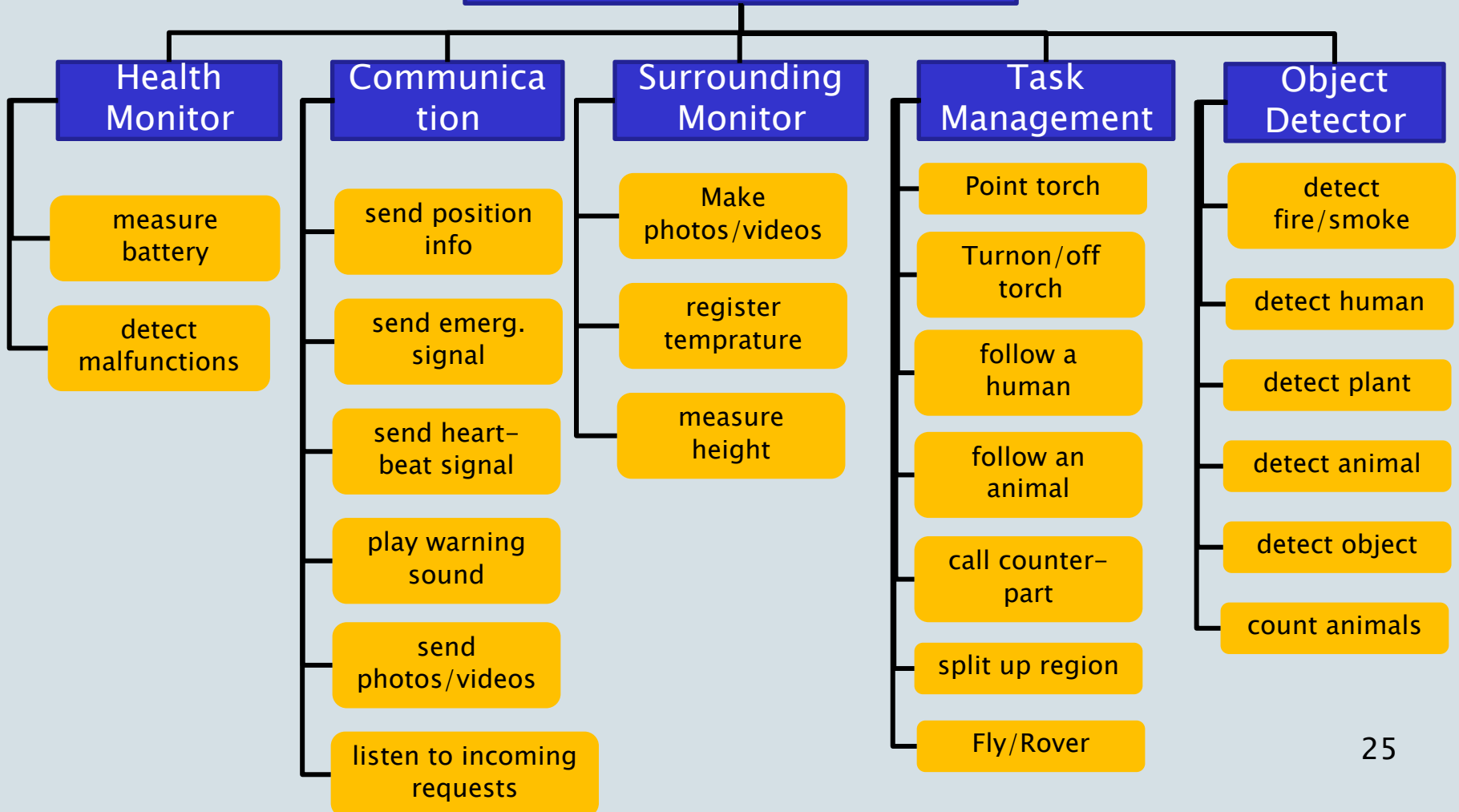
Manage and control drone operation. Switch between different working modes.

Object Detector

Detect and recognize objects appeared in drone's camera.  
(decoupled from Surrounding Monitor)

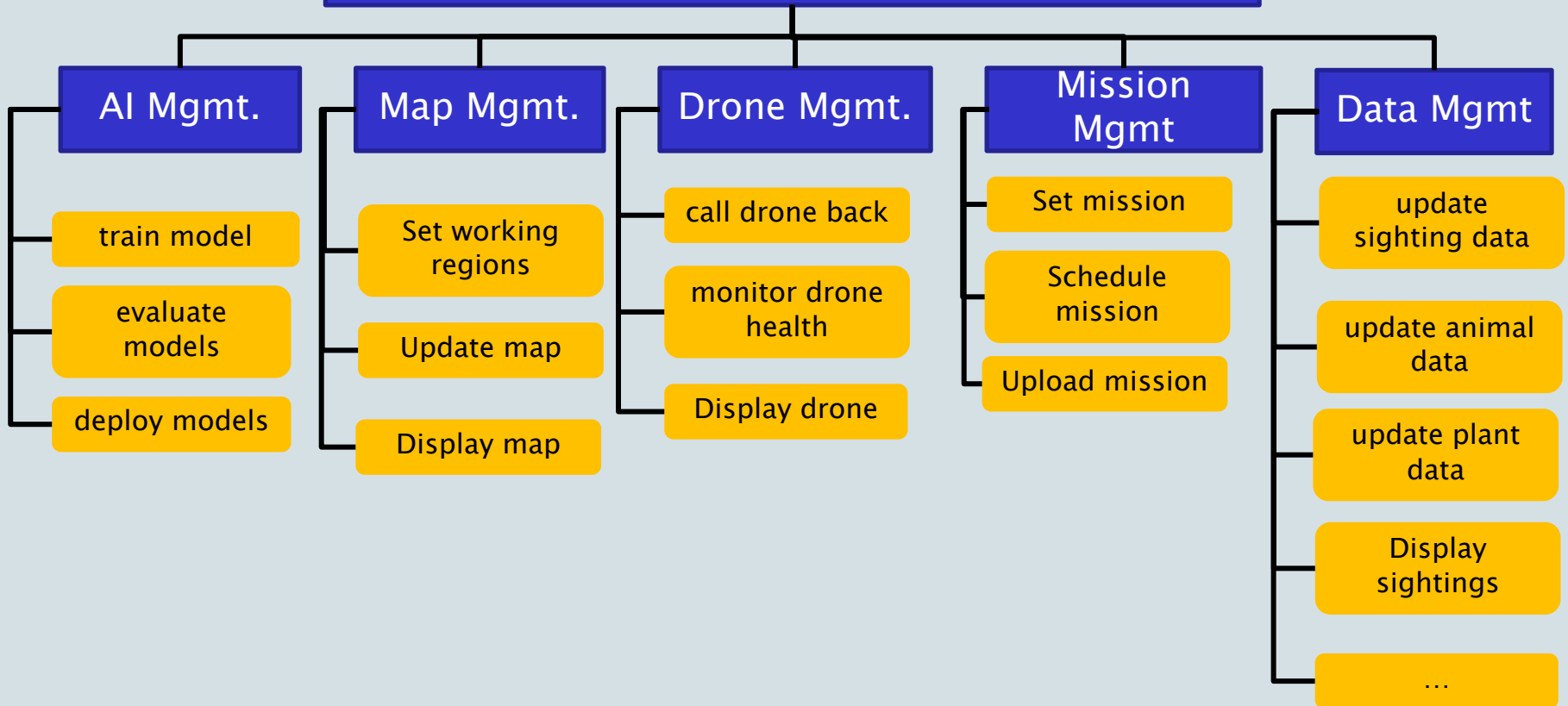
# Drone Sub-system: Func. Decomposition

## Drone Sub-system



# Ground Station Sub-system: Func. Decomposition (1<sup>st</sup> version)

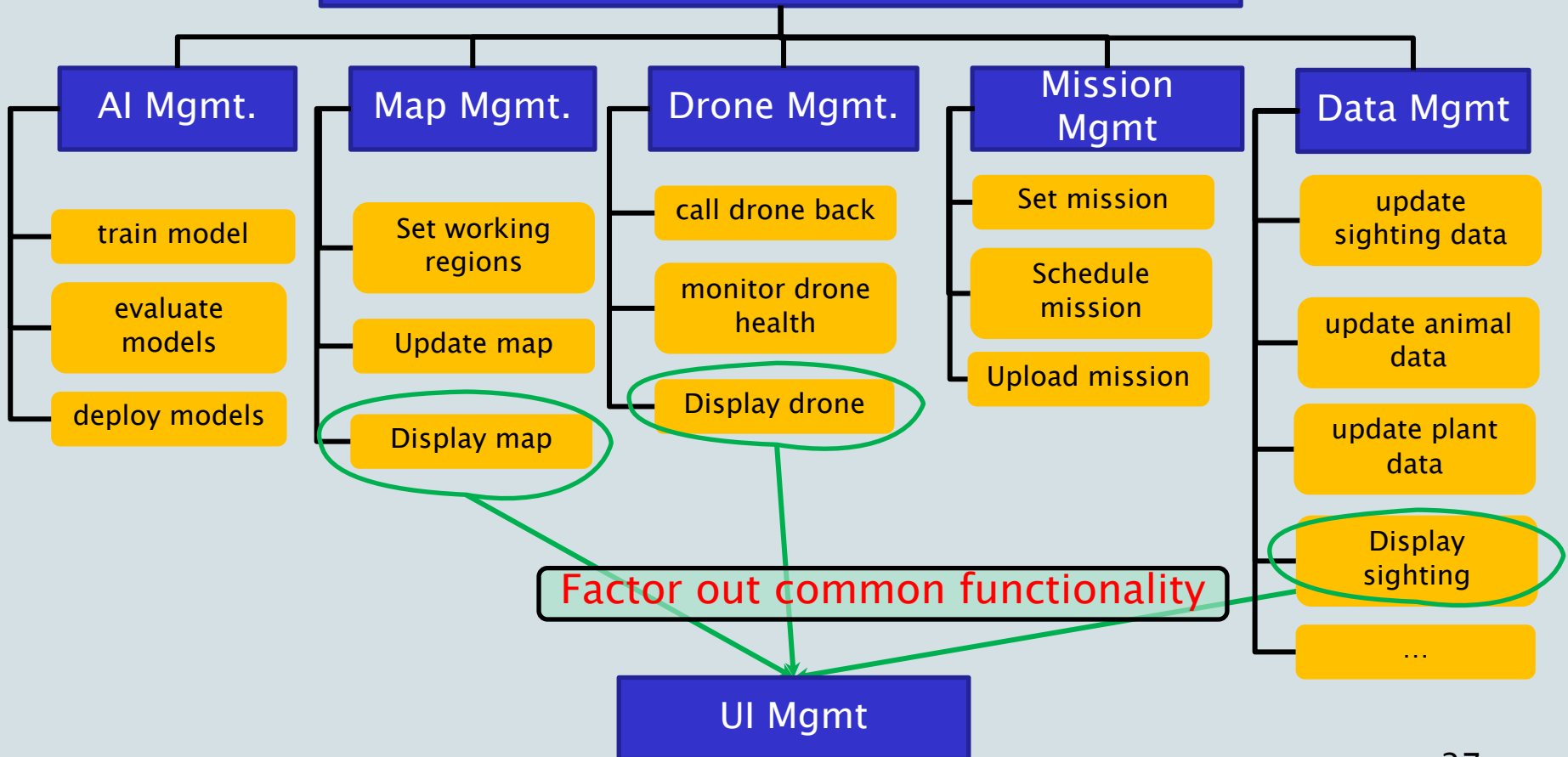
## Ground Station Sub-system



Charging Station  
Mgmt

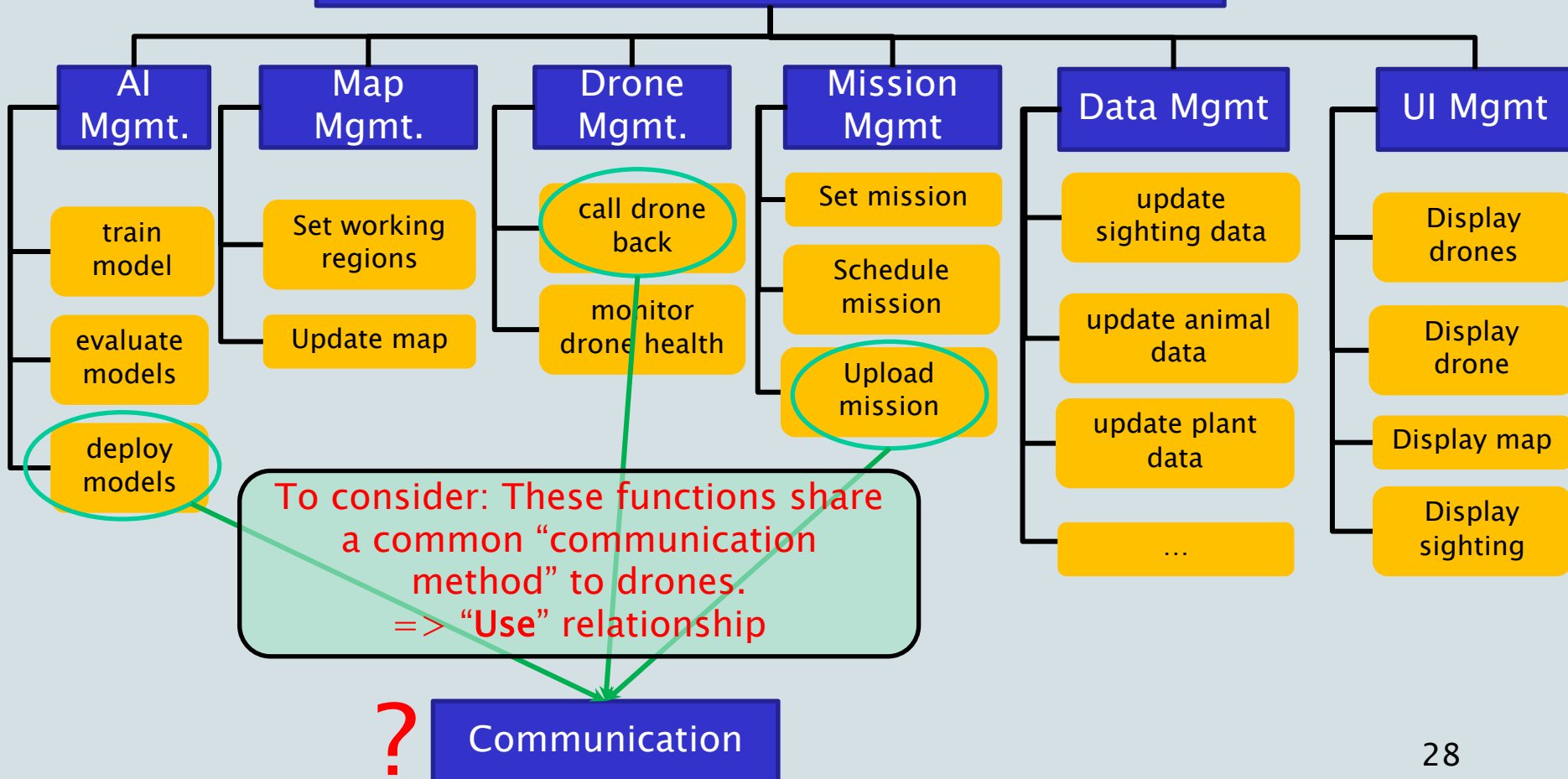
# Ground Station Sub-system: Func. Decomposition (1<sup>st</sup> version)

## Ground Station Sub-system



# Ground Station Sub-system: Func. Decomposition (updated)

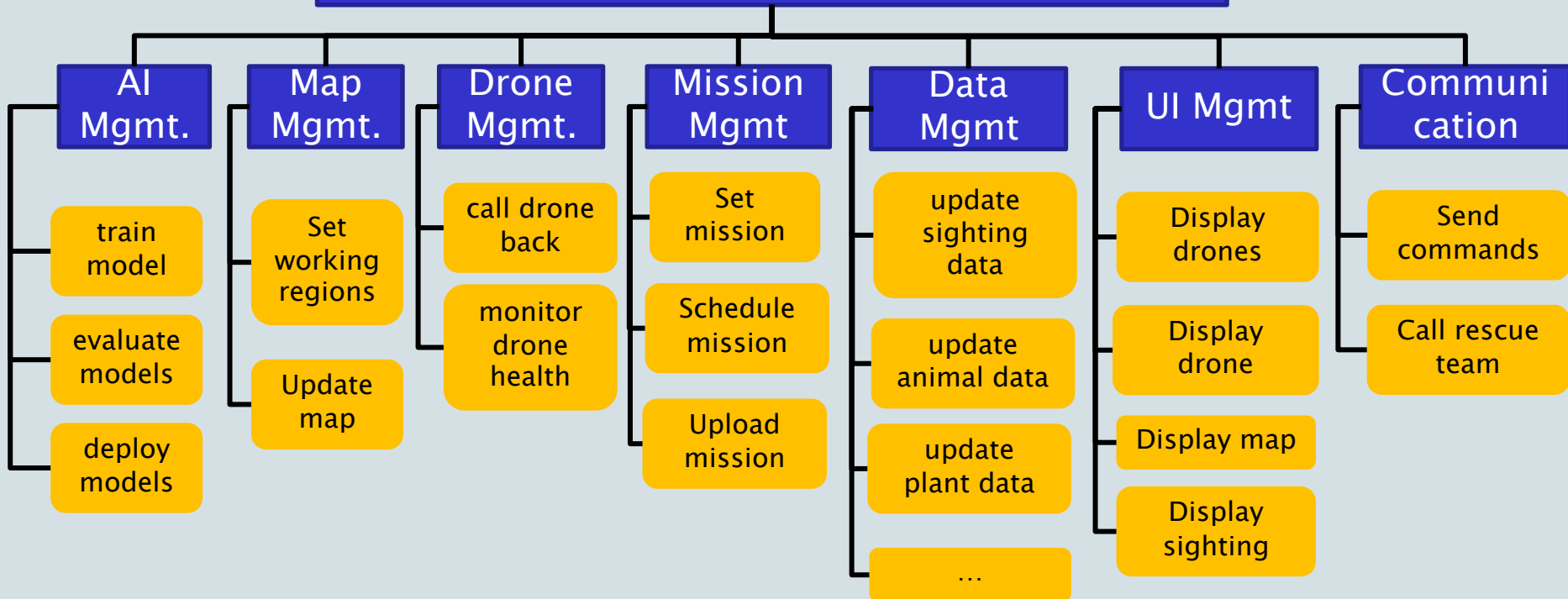
## Ground Station Sub-system



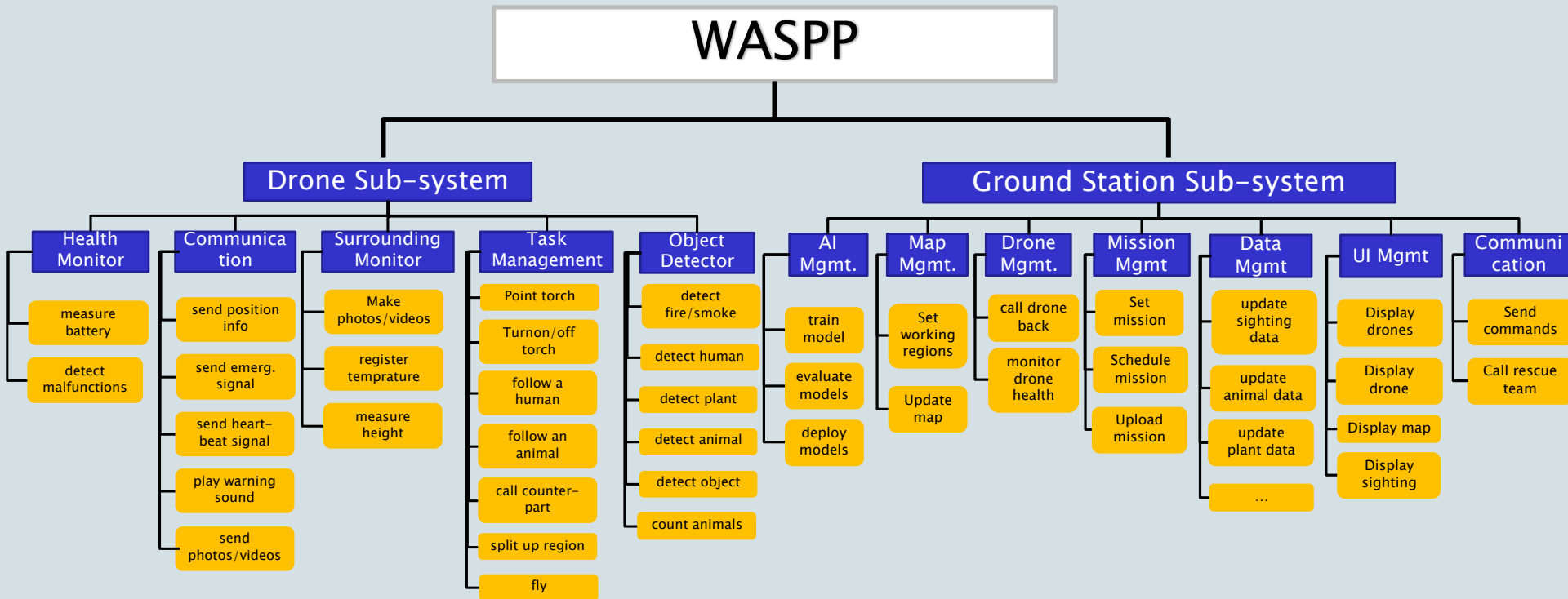


# Ground Station Sub-system: Func. Decomposition (final)

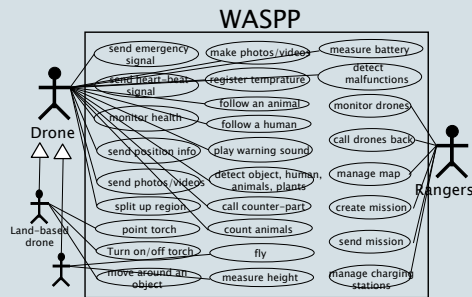
## Ground Station Sub-system



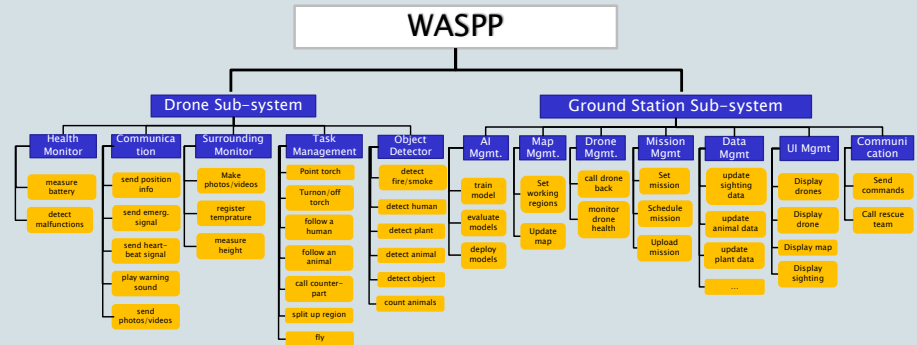
# WASPP – Functional Decomposition Diagram



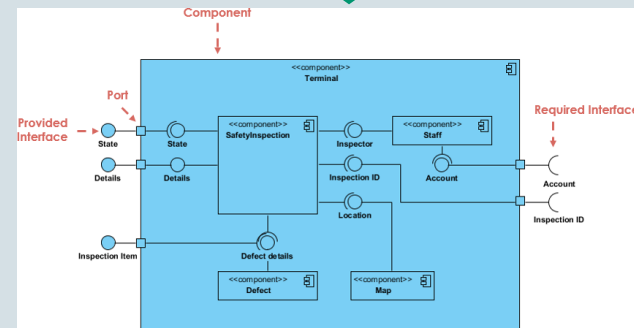
# Structural View



Functionalities

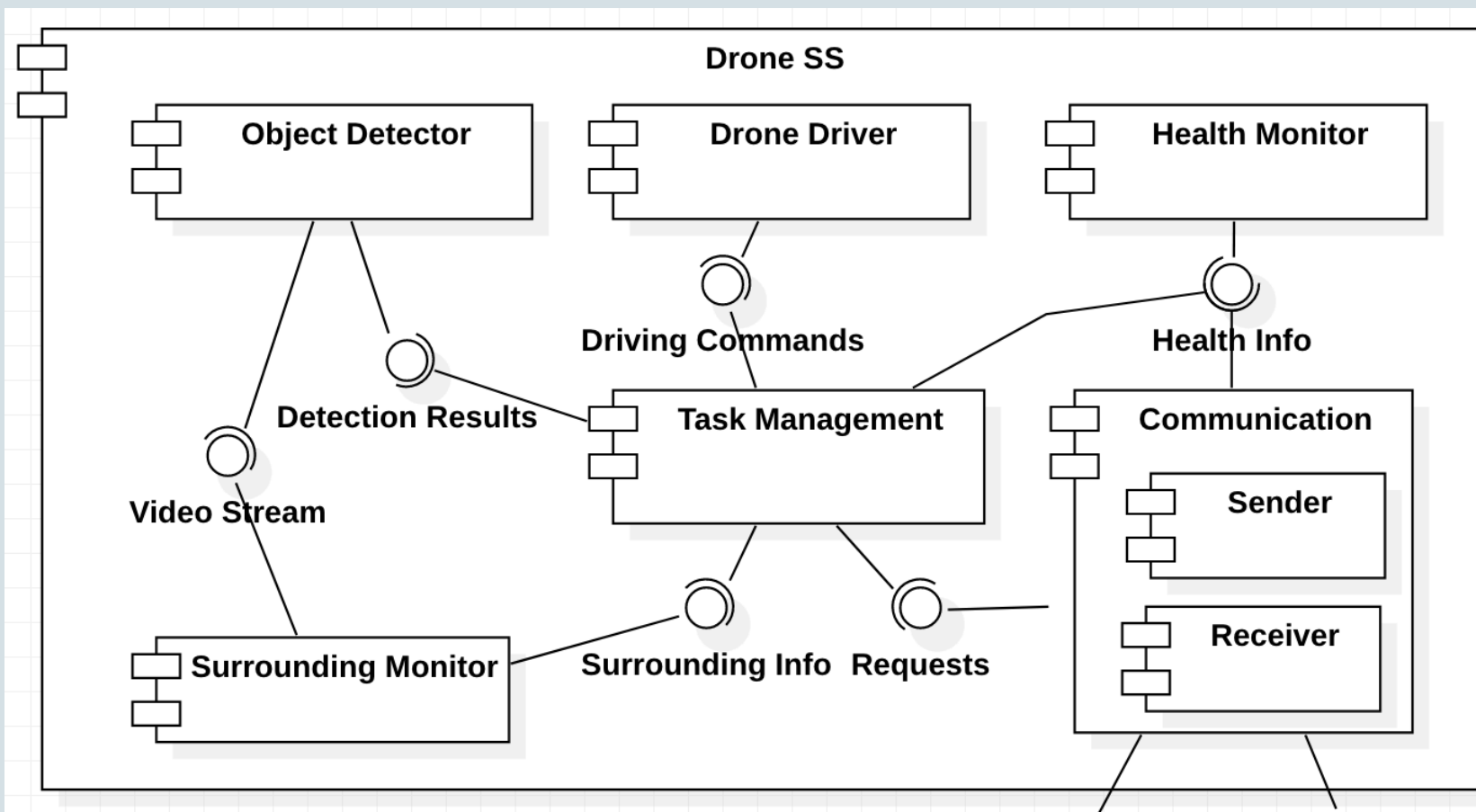


Functional Decomp.



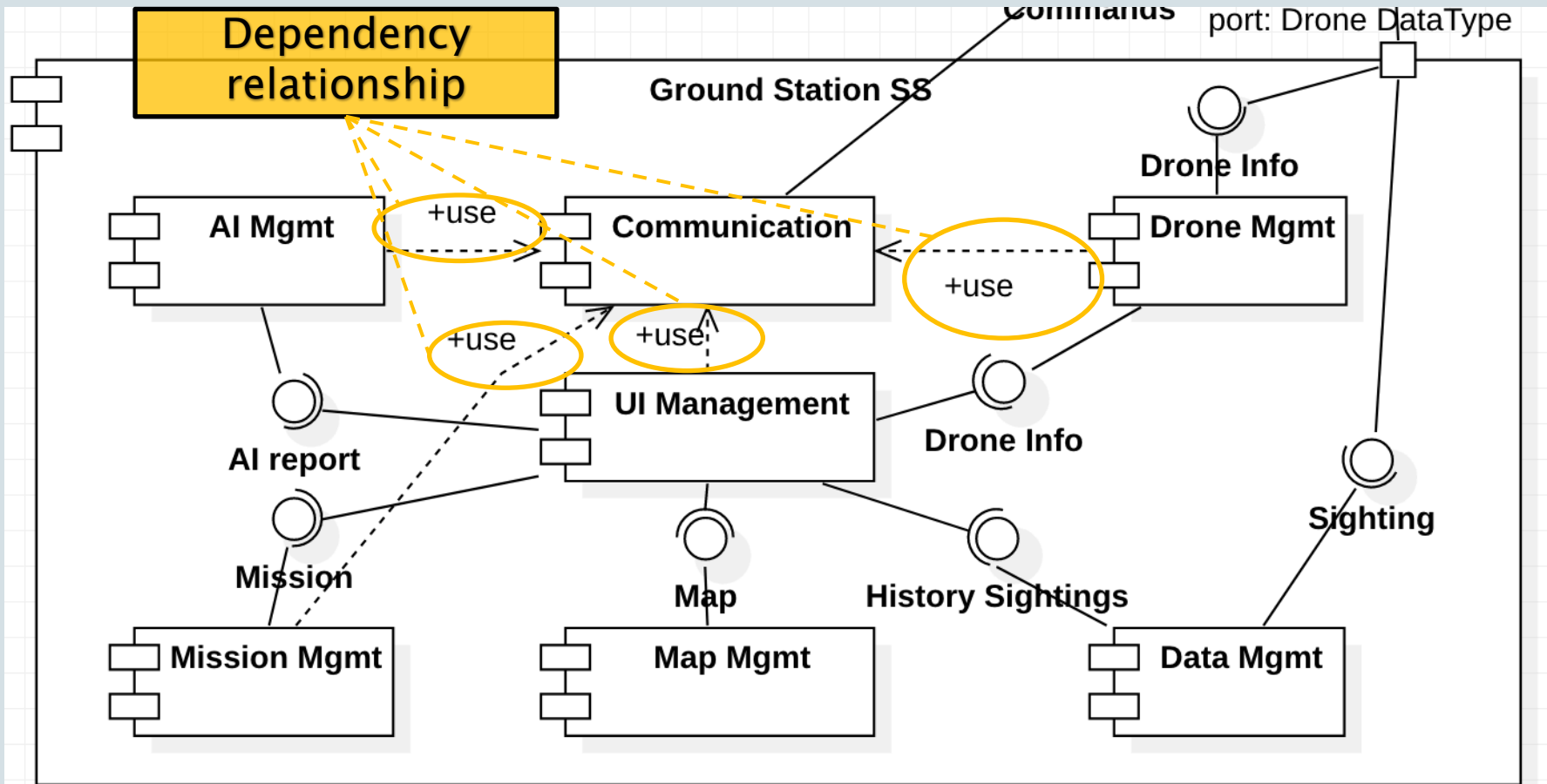
Structural View

# Structural View (1)



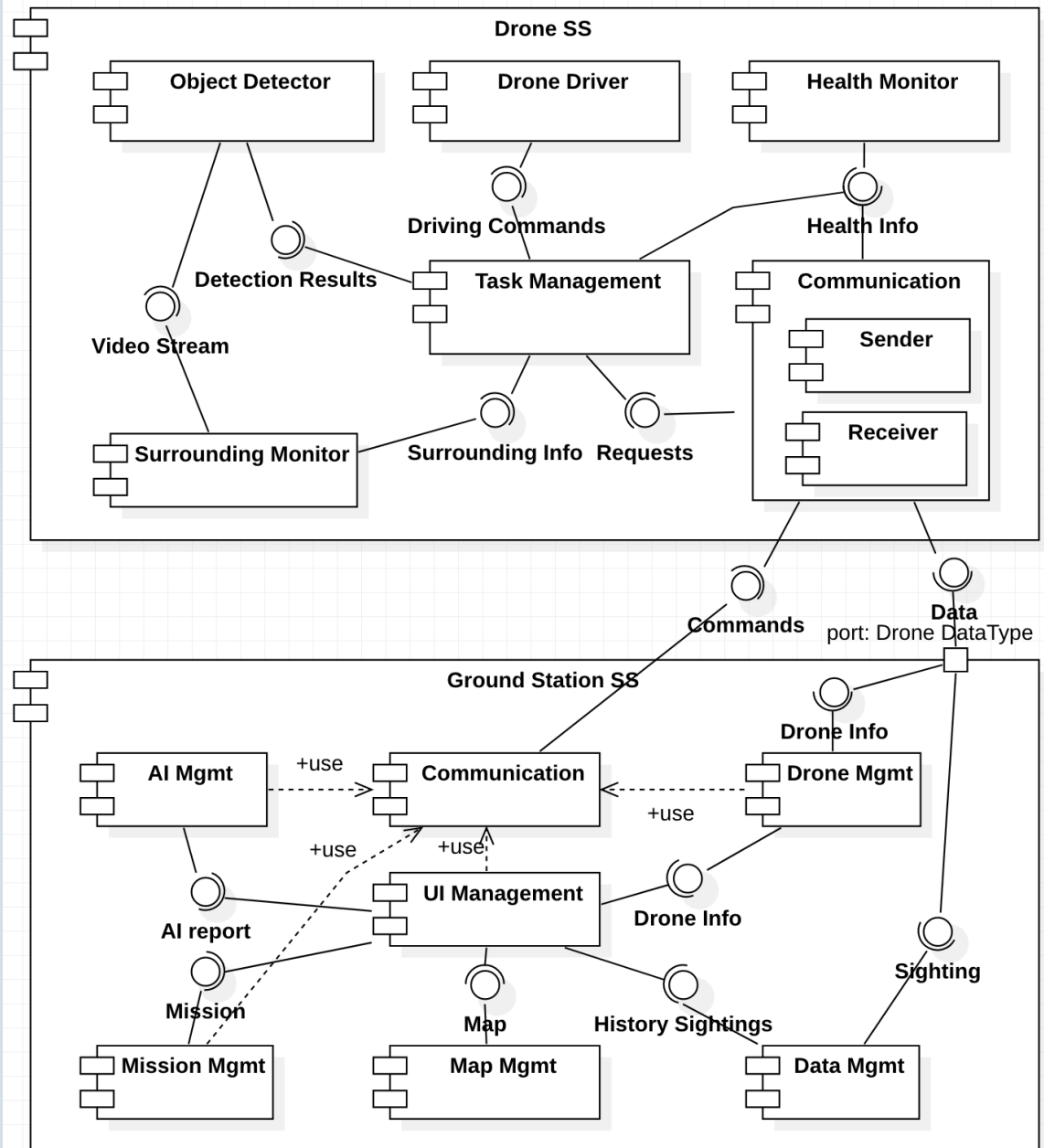
Drone SS

# Structural View (2)

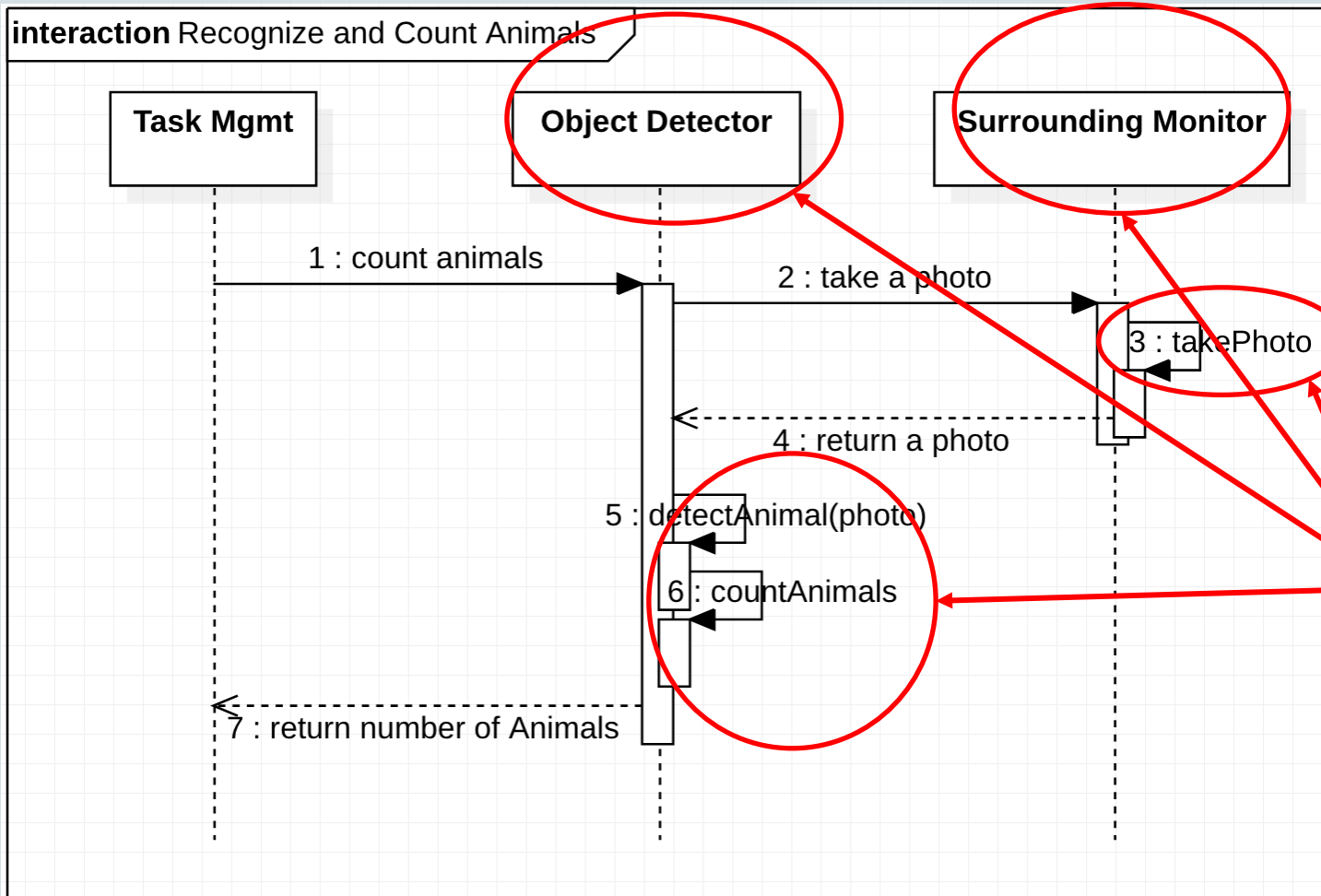


Ground Station SS

# Structural View (whole system)



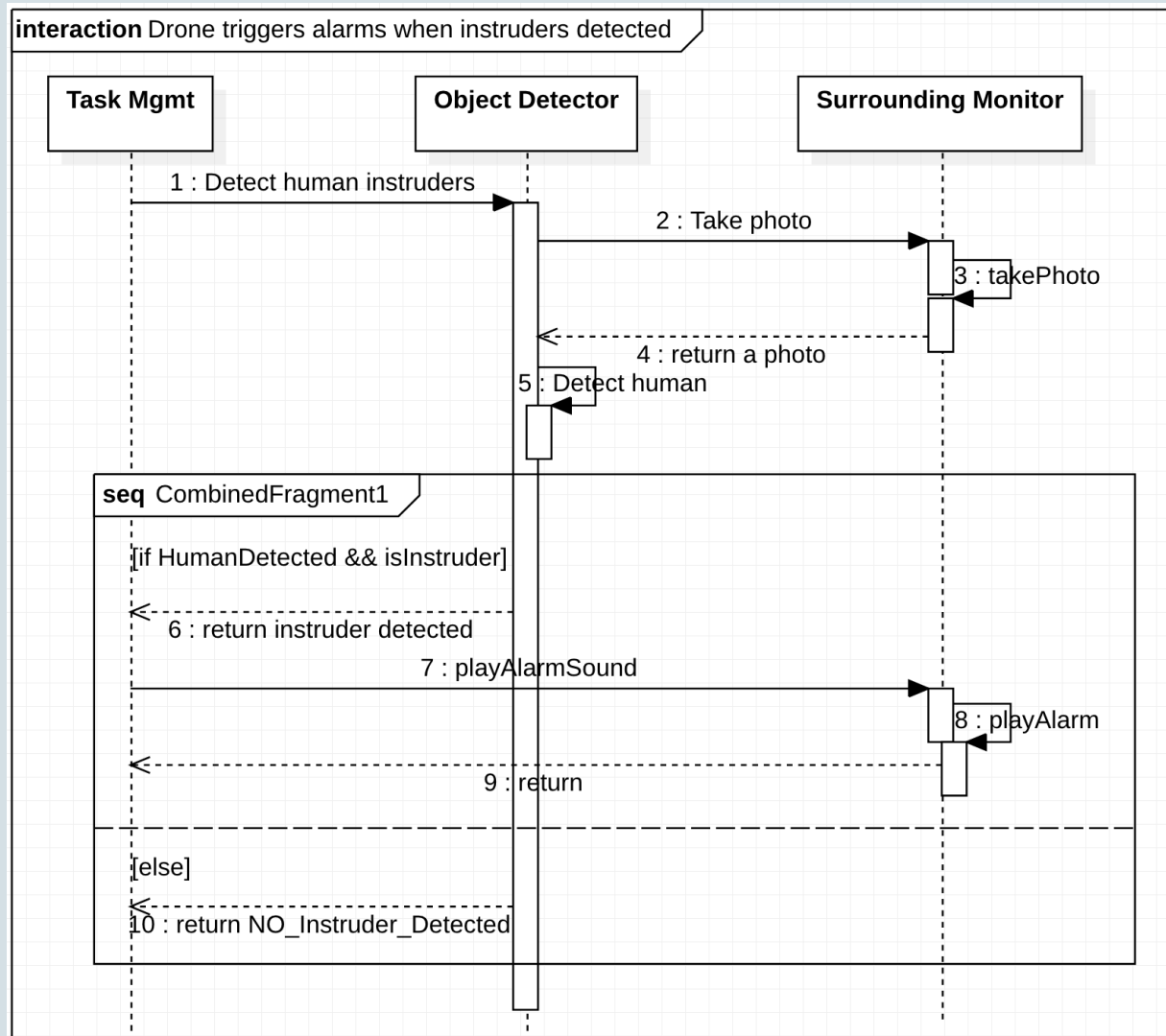
# Behavioral View



Should be  
consistent  
with  
structural &  
functional  
views

Assumption: The request of counting animals is initiated from the Task Management

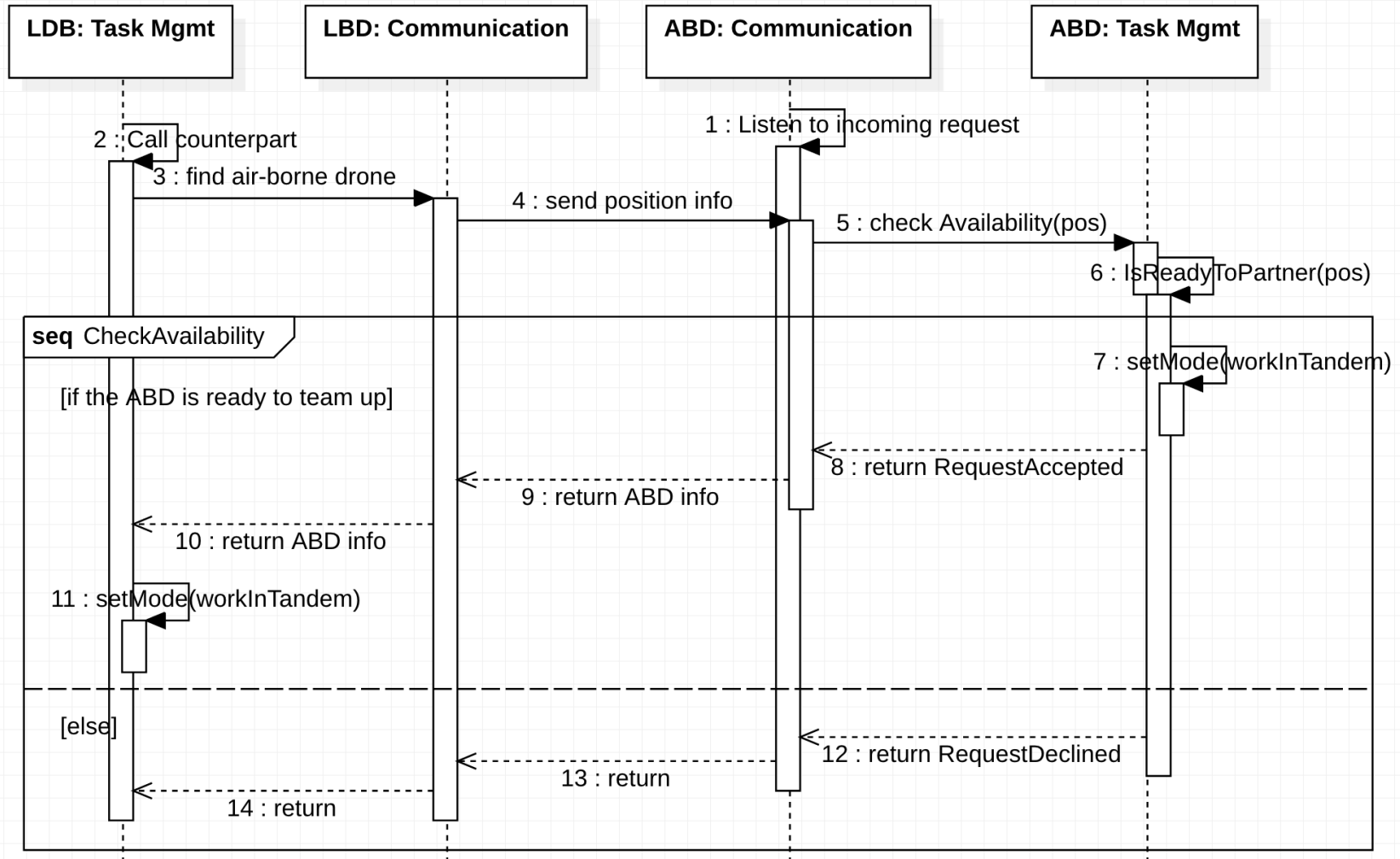
# Behavioral View (2)





# Behavioral View (3)

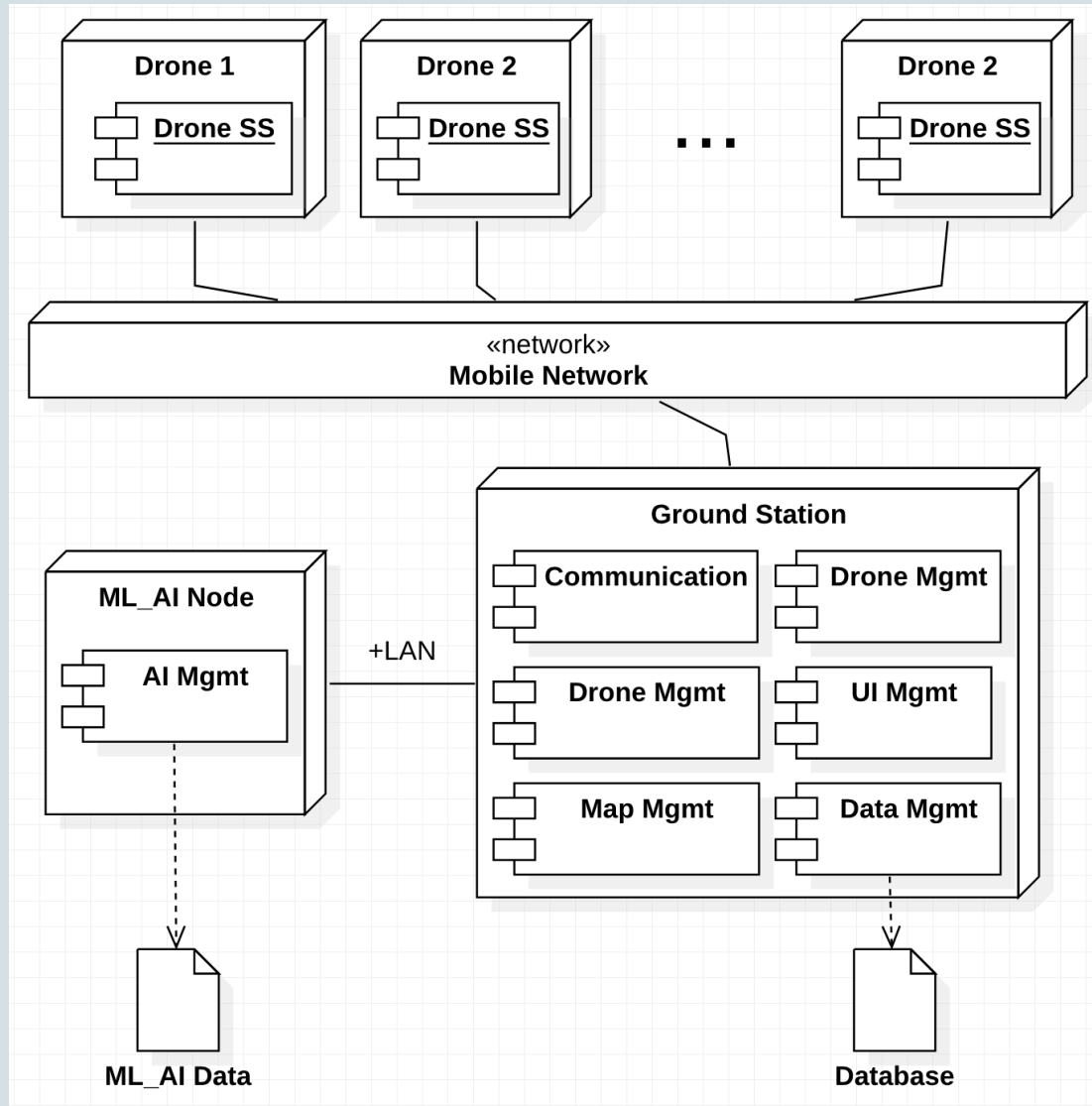
**interaction** Land-based drone asks air-borne drone to explore



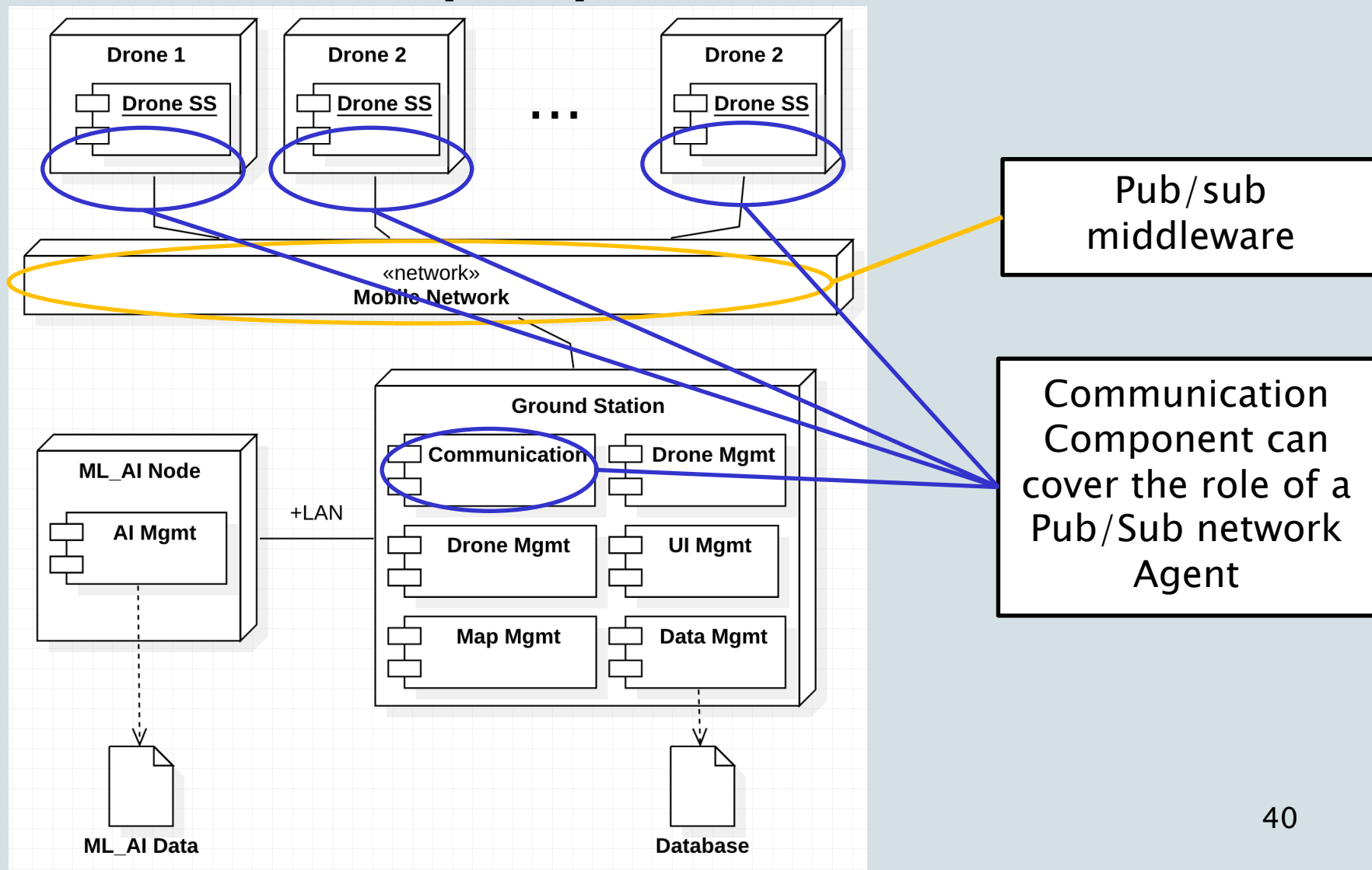
# Client/Server or Publish/Subscribe

- I chose Pub/Sub as the dominant style because:
  - Short-lived data
  - Multiple receiver (subscribers) of “specific” datatype
    - Example: A drone is interested in “position” but not “image/video stream” of other drones
  - Flexibility when adding/removing subscribers or publishers.
- I do not choose Client/Server because
  - Frequent communication between drones
  - Some requests should not primarily be made by drones
    - E.g. I don’t want drones (represent client-side) to send requests every N seconds to see if there is any update on the mission from the ground station (represents server-side).

# Deployment View



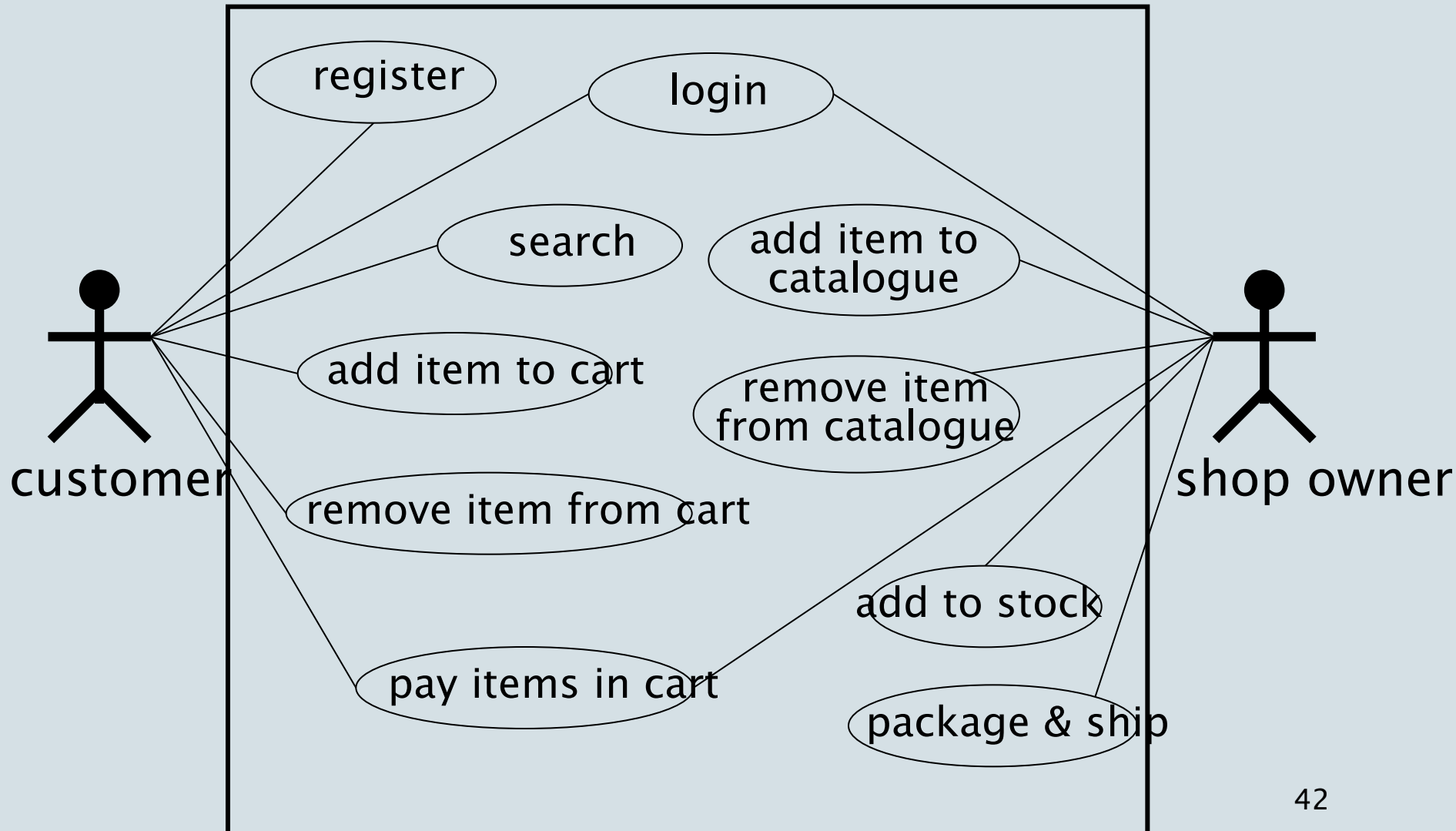
# Deployment View



## and... More to think of

- Don't forget architecture drivers
  - You should be able to answer: how were your design decisions driven by the drivers?
  - Where?
    - Chosen styles
    - Tactics
    - Additional components, deployment nodes ...
  - Use your SAD to document the decisions
- Level of details
  - Think of: Who are the readers? To do what?
- Consistency
  - Any adjudgement to be made to requirements?
  - Keep your design (via the views) consistent

# Case: Web shop



# Structure Diagram

- Defines subsystems of functionality
- Purpose
  - Define decomposition into subsystems
  - Provide support for use-cases
- Use Component (or Class) diagram

# Web Shop: Functional Areas (V0.1)

**Customer  
Registration**

**Shop Owner  
Registration**

**Shop User Interface**

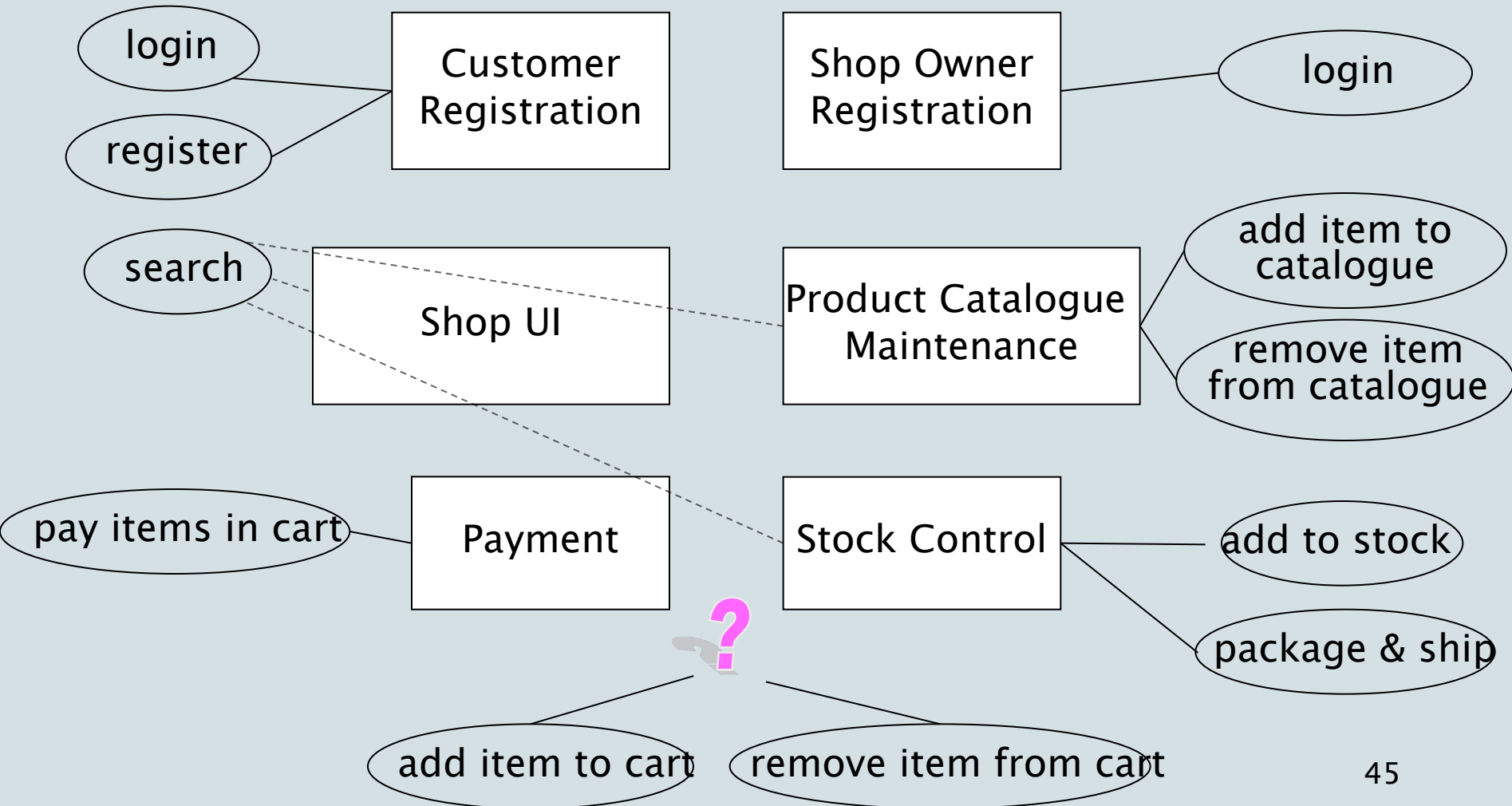
**Product Catalogue  
Maintenance**

**Payment**

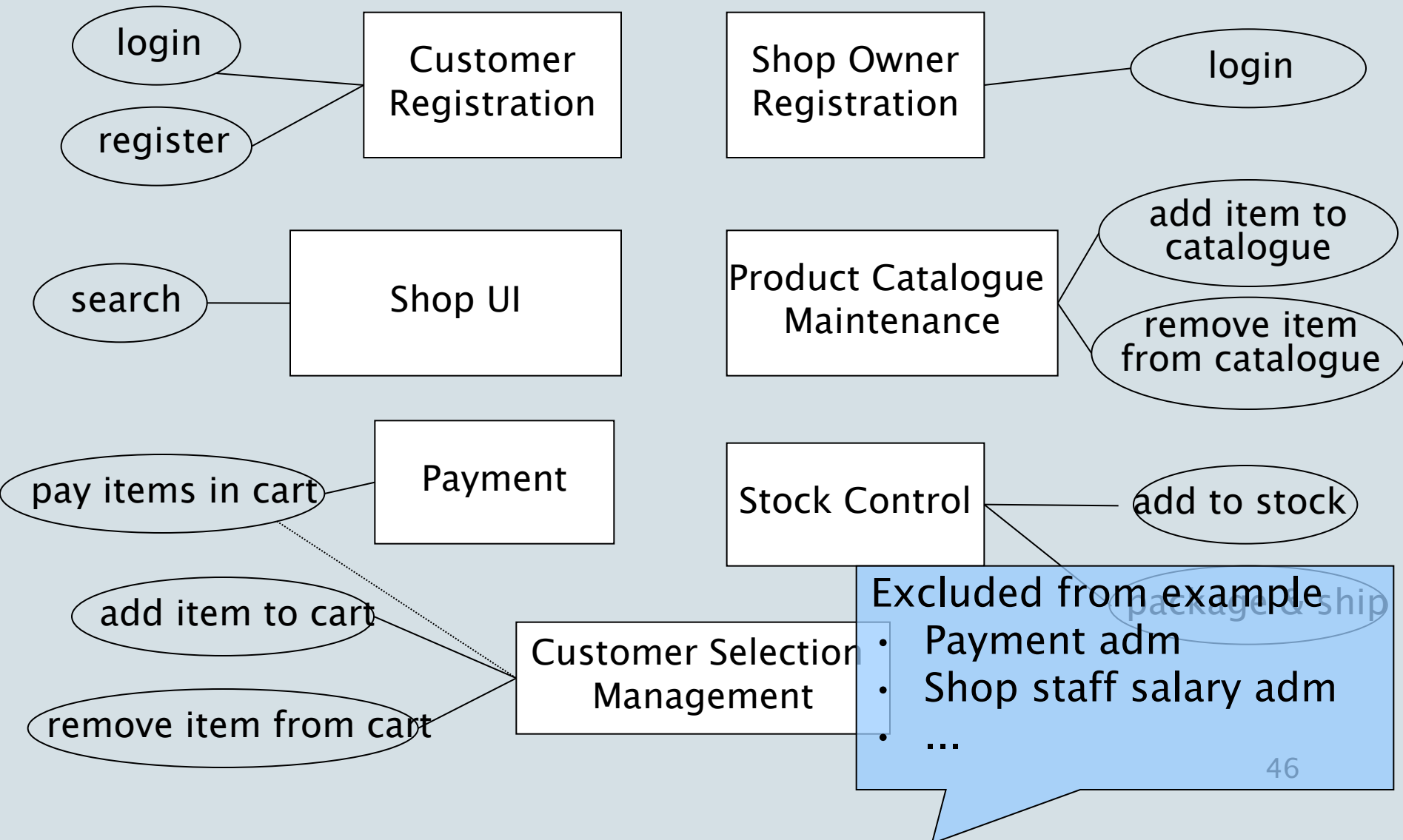
**Stock Control**



# Check Use Cases Against Functional Areas



# Web Shop: Functional Areas (V0.2)



# Web Shop: Responsibilities

Customer Registration

Entry, storage & retrieval of customers

Shop Owner Registration

Entry, storage & retrieval of shop staff

Shop UI

Provide customers access to product data

Prod. Cat. Maintenance

Entry, storage & retrieval of product data

Cust. Selection Mngmt.

Register customer product selection

Payment

Handle transaction between customer & shop

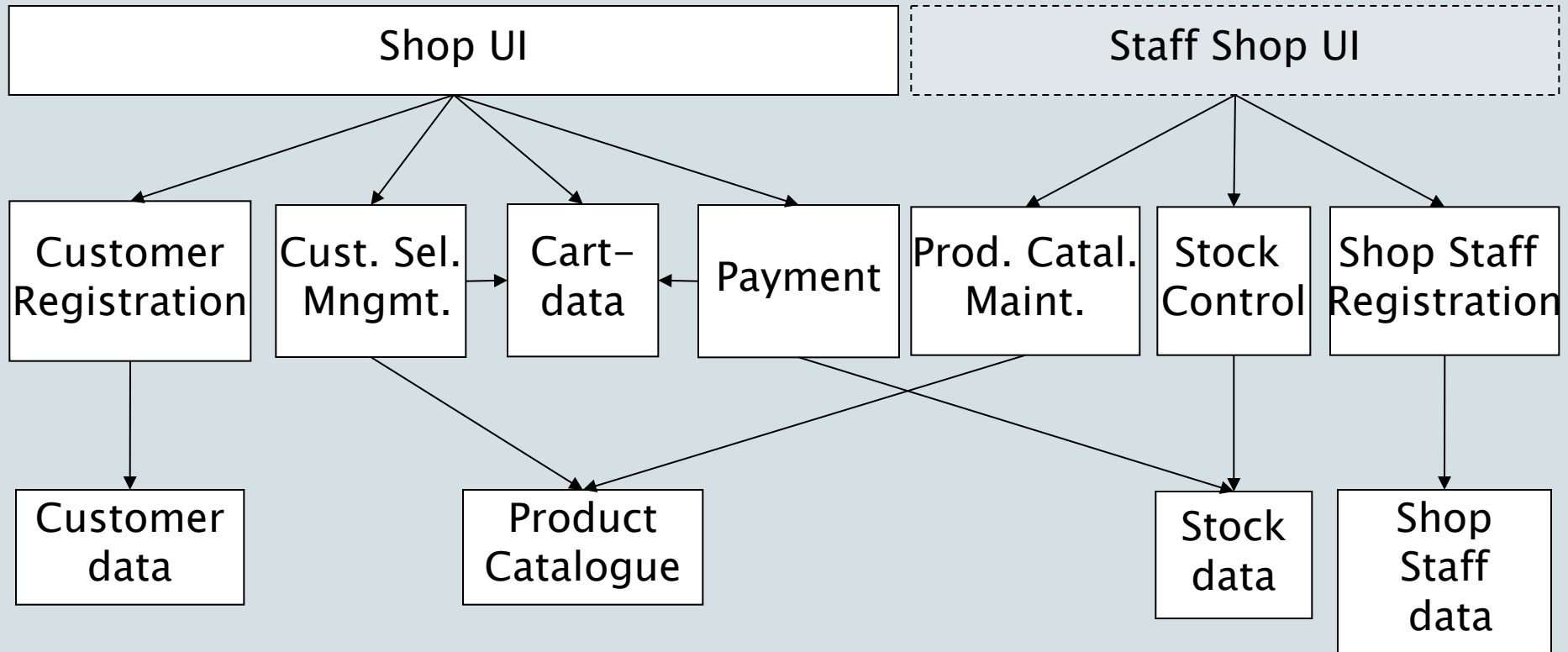
Stock Control

Register available products in stock

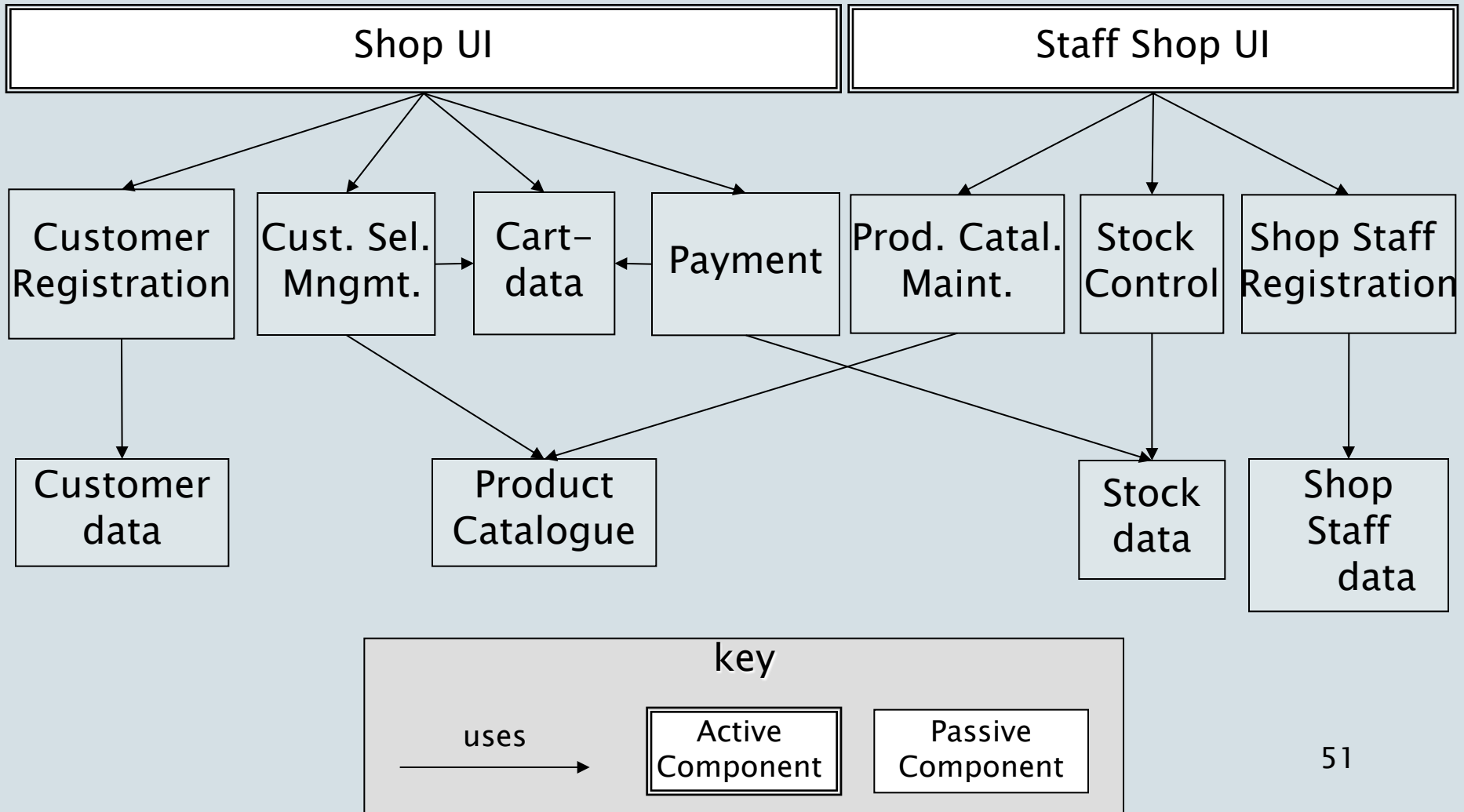
# Some Concrete Examples

- <http://www.nkictarchitectuur.nl/2006/index.htm>
  - Rabobank, Belastingdienst, Ahold, FEI, Schiphol, Elsevier, ...

# Identification of Dependencies



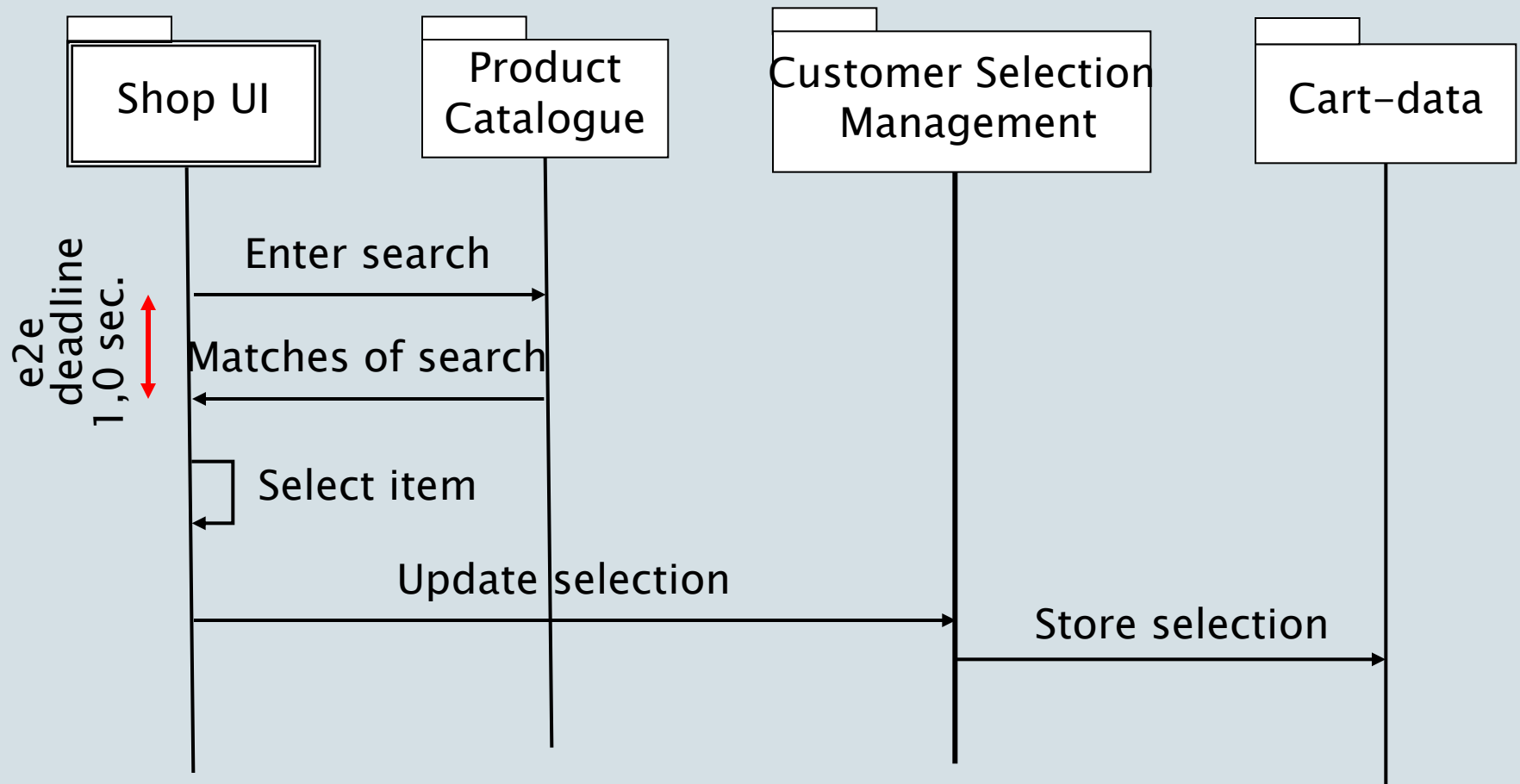
# Identification of Active Processes



# Sequence Diagram

- Captures interaction between components
- Purpose
  - Model flow of control
  - Identify synchronization
  - Illustrate typical scenarios

# Design System Dynamics: Scenario's

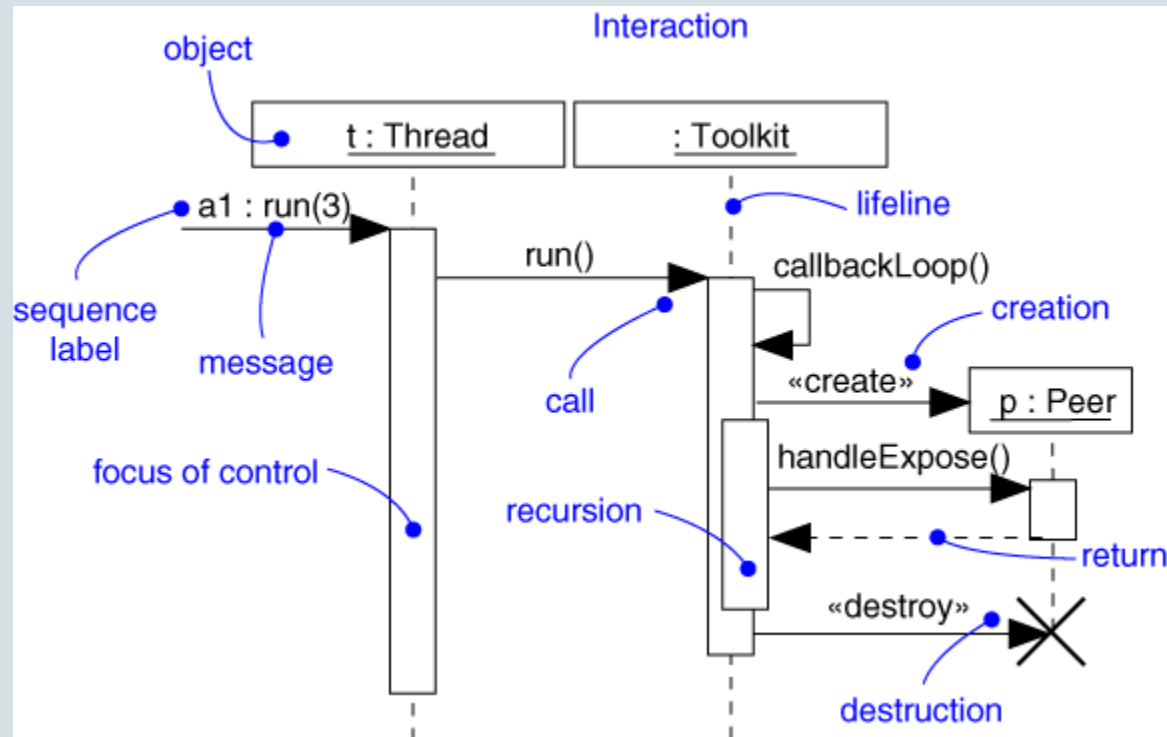


Scenario's describe the interaction between components



# Sequence Diagram

Captures interaction between components

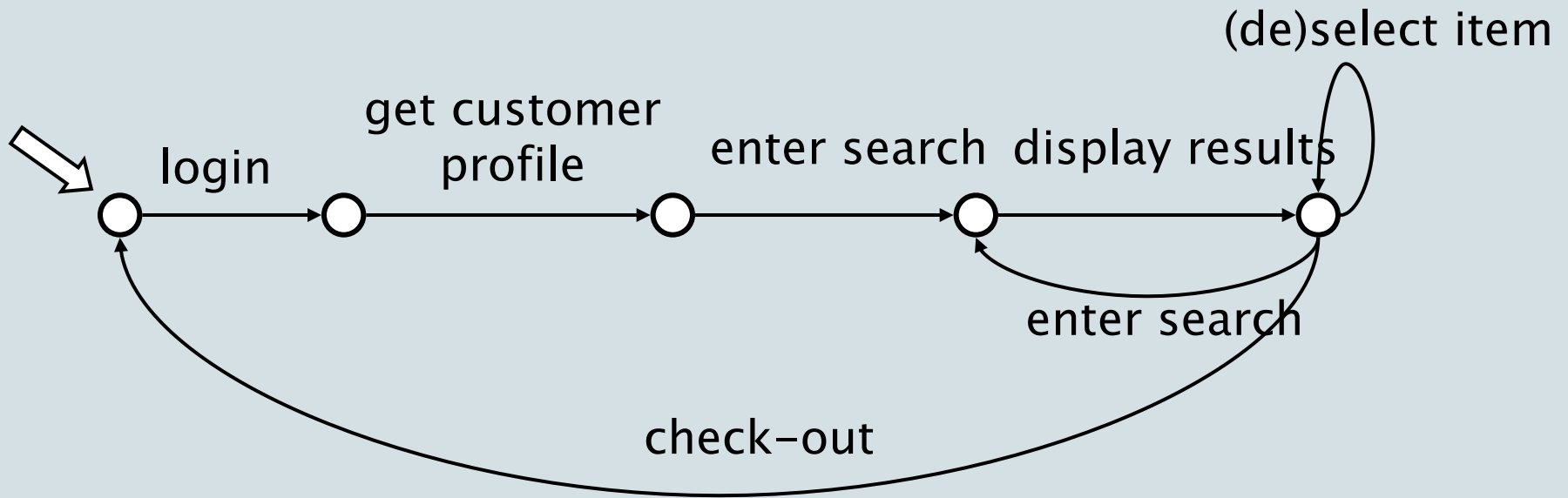


# Statechart Diagram

- Captures behaviour internal to individual components
- Purpose
  - Model reactive objects  
(user interfaces, devices, etc.)

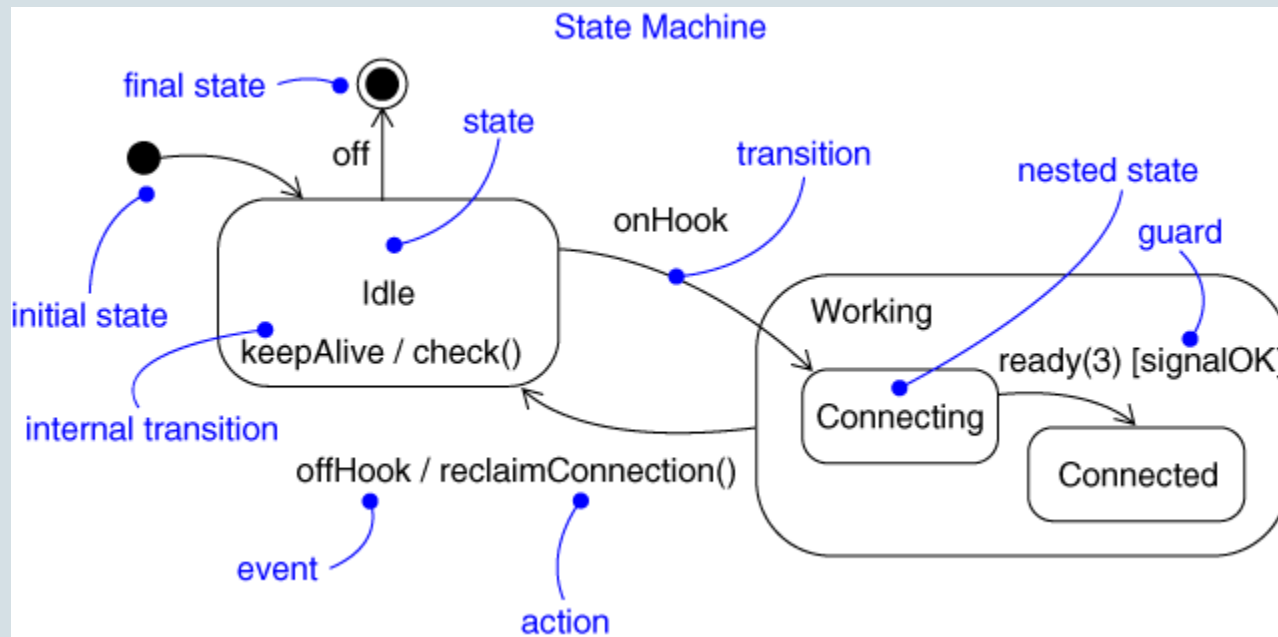
a.k.a. state–transition diagrams, finite–state–machines  
alternative: Petri–nets

# Web shop UI state-machine



# Statechart Diagram

Use a state-diagram to specify the internal behaviour of a component

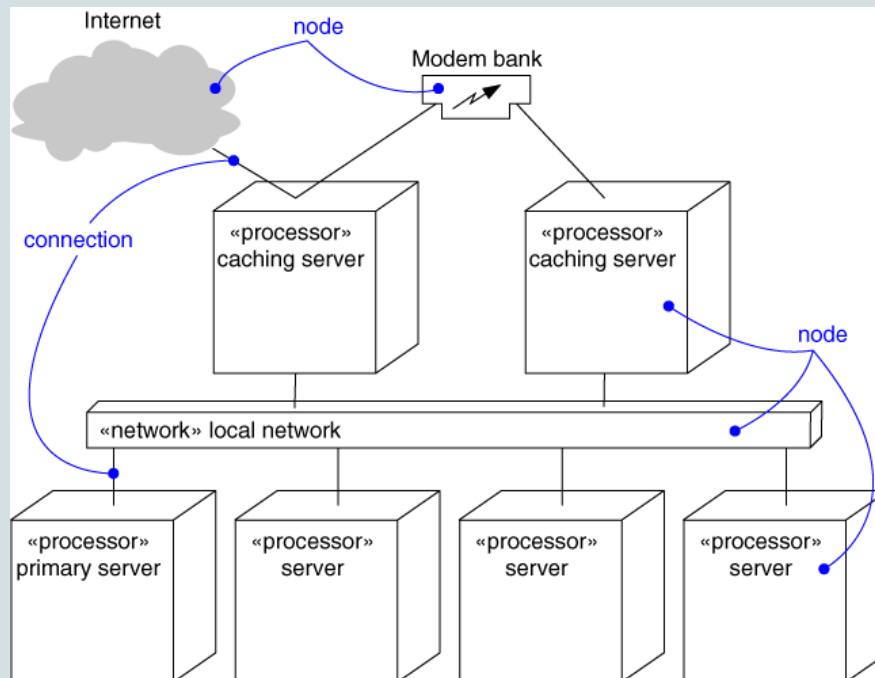


# Deployment Diagram

- Captures the topology of a system's hardware
- Purpose
  - Specify the distribution of components
  - Identify performance bottlenecks
- Developed by architects, networking engineers, and system engineers

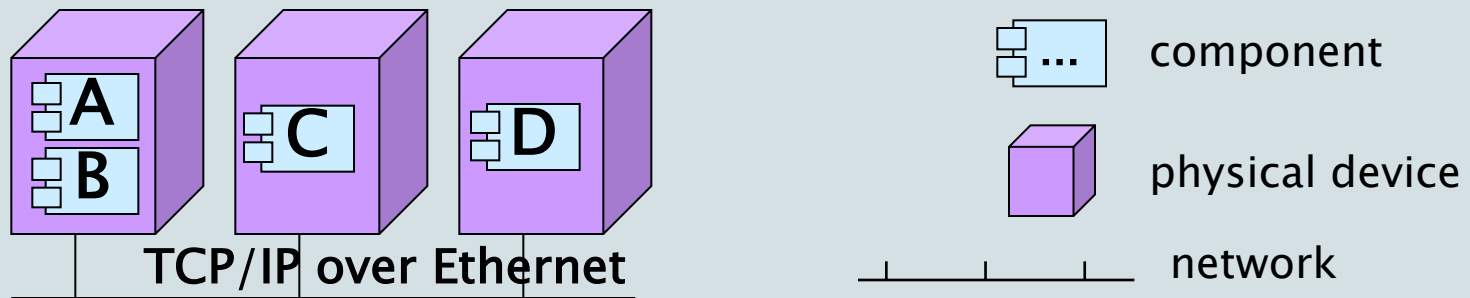
# Deployment Diagram

- topology of a system's hardware
- + (rules for) mapping of logical view to hardware



# Deployment Diagram

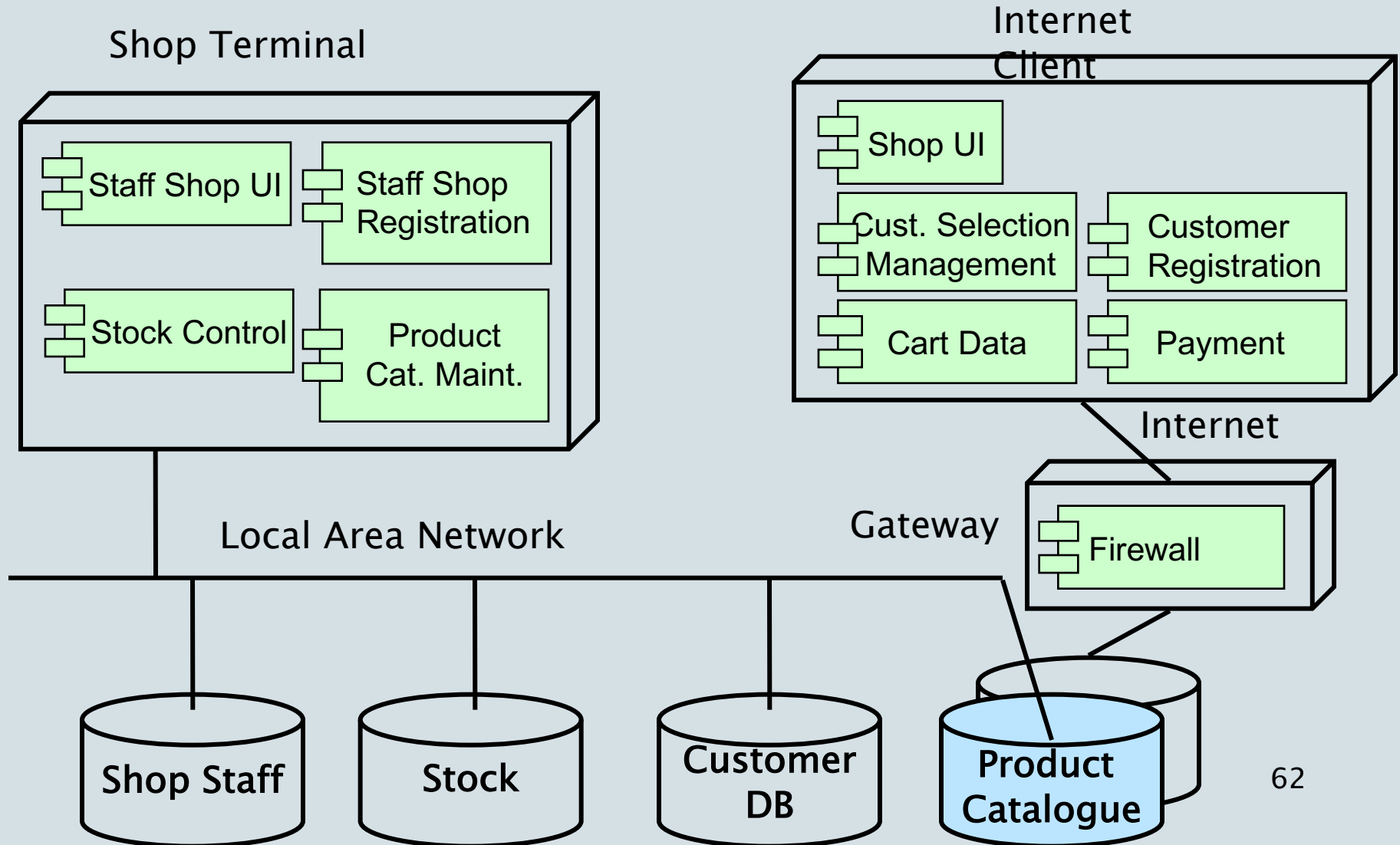
Deployment view: physical model + mapping



Basis for analyzing throughput, availability

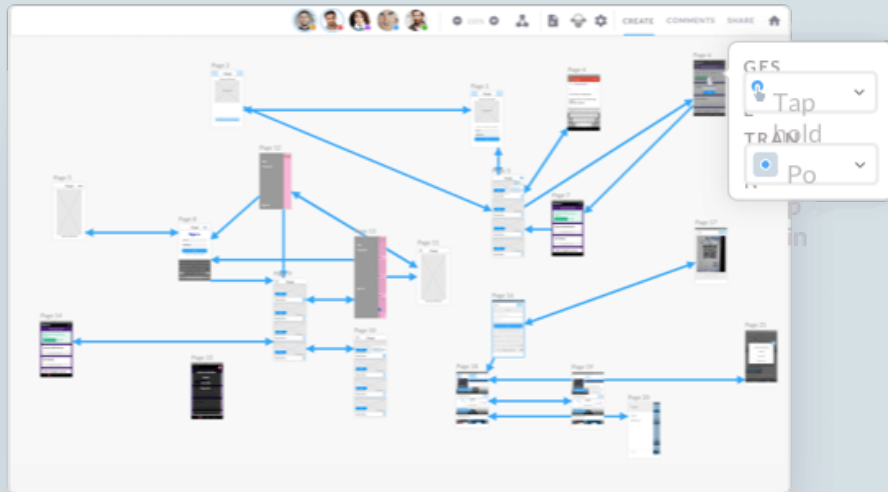
Separation of Concerns in diagrams: the deployment diagram does not show the dependencies between components

# Web Shop Deployment Diagram





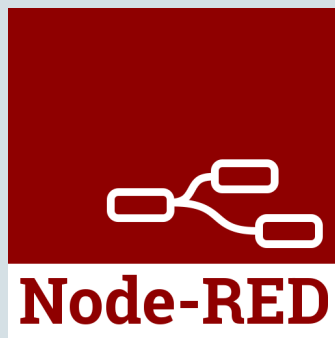
# Task 2 – Implementation



 MQTT

 mosquitto

 paho



# Task 2 – Objectives

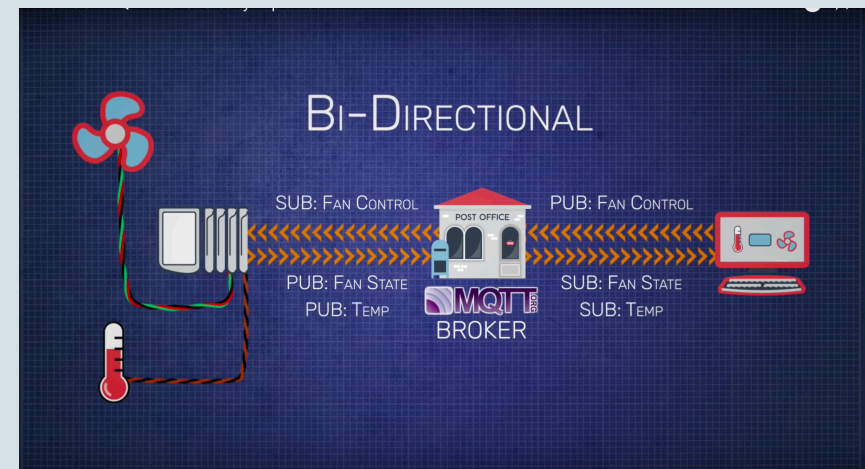
- To learn to use the architecture design as part of the implementation
- To learn to monitor that the implementation follows the architecture
- To keep the architecture description and the implementation consistent ('in sych') – while sometimes insight from the implementation require updates to the architecture description.
- To get practical experience in implementing architectural styles and patterns

# Task 2 – Tasks

- [Available on Canvas.](#)
- To build “mockups” of main components in your system
- Mockups <> Prototype | Balsamiq
  - Show communications
  - Show behaviours, not algorithms
- Some important components:
  - Human
  - Drone (generates signals, location; receives missions...)
  - Dashboard (at Ground Station)
  - Machine Learning

# Task 2 – Implementation

- Languages/Framework of your choice
- For communications between nodes, we recommend you to use MQTT
  - a lightweight (pub/sub) messaging protocol
  - avoid direct connection between devices
  - commonly used in many IoT applications



# Task 2 – Starting points

- About MQTT
  - Internet
  - Introduction presentations
- Think of implementation details
  - Data structures
  - Interfaces (API)
  - Performance bottle-necks

# Task 2 – Expected outcomes

- Final version of your SAD document (first version was submitted in A1T1). I expect updates:
  - based on the feedback you have from teachers and peer-reviews, and
  - based on what you learn from implementing the system.
- A presentation and demonstration (30 minutes/group) on March 5
  - the schedule will be decided later