

Error analysis

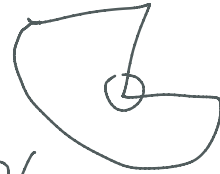
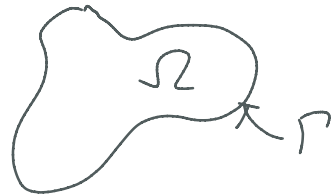
$$\begin{cases} Au := -\nabla \cdot a \nabla u + b \cdot \nabla u + cu = f & \text{in } \Omega \\ u = 0 & \text{on } \Gamma \end{cases}$$

FEM: $u_h \in V_h$:

$$a(u_h, v) = (a \nabla u_h, \nabla v)$$

$$+ (b \cdot \nabla u_h, v) + (c u_h, v)$$

$$= (f, v) \quad \forall v \in V_h.$$



Thm 5.3 & 5.4

$$\|u - u_h\|_{H^1(\Omega)} \leq C \min_{\chi \in V_h} \|u - \chi\|_{H^1(\Omega)}$$

$$\|u - u_h\|_{H^1(\Omega)} \leq C h \|u\|_{H^2(\Omega)}$$

Assuming $b = c = 0$ and

$$\|v\|_{H^2(\Omega)} \leq C \|-\nabla \cdot a \nabla u\|_{L^2(\Omega)} \quad v \in H^2 \cap H_0^1$$

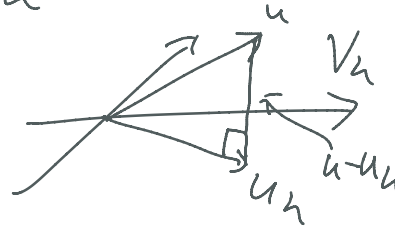
Elliptic regularity

$$\|u - u_h\|_{L^2(\Omega)} \leq C h^2 \|u\|_{H^2(\Omega)} \leq C h^2 \|f\|_{L^2(\Omega)}$$

Proof: Recall $a(u, v) = L(v) \quad \forall v \in H_0^1$
 $a(u_h, v) = L(v) \quad \forall v \in V_h \subset H_0^1$

$$a(u - u_h, v) = 0 \quad \forall v \in V_h$$

Galerkin orthogonality



$$\begin{aligned} & \overset{\text{Coercivity}}{a_0 \|u - u_h\|_{H^1(\Omega)}^2} \leq a(u - u_h, u - u_h) = a(u - u_h, u - \chi) \\ & \overset{\text{Boundedness}}{\leq} M \|u - u_h\|_{H^1(\Omega)} \|u - \chi\|_{H^1(\Omega)} \quad \chi \in V_h \end{aligned}$$

$$\therefore \|u - u_h\|_{H^1(\Omega)} \leq C \|u - \chi\|_{H^1(\Omega)} \quad \forall \chi \in V_h$$

Consider $\chi = I_h u$ Int. bound

$$\begin{aligned} \|u - u_h\|_{H^1(\Omega)} &\leq C \|u - I_h u\|_{H^1(\Omega)} \leq \\ &\leq C' h \|u\|_{H^2(\Omega)} \end{aligned}$$

$Au = -\nabla \cdot a \nabla u$, $\|v\|_{H^2} \leq \|Av\|_{L^2}$
 Aubin-Nielsen trick $v \in H^2 \cap H_0^1$

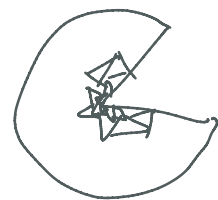
$$\begin{cases} A\phi = u - u_h \\ \phi = 0 \end{cases} \quad \text{adjoint problem}$$

$$\begin{aligned}
\|u - u_h\|_{L^2(\Omega)}^2 &= (A\phi, u - u_h) = (a \nabla \phi, \nabla u - \nabla u_h) \\
&= (a \nabla u - u_h, \nabla \phi) \stackrel{\text{G.O.}}{=} (a \nabla u - u_h, \nabla \phi - I_h \phi) \\
&\leq M \|u - u_h\|_{H^1(\Omega)} \cdot \|\phi - I_h \phi\|_{H^1(\Omega)} \\
&\leq C h \|u\|_{H^2(\Omega)} \cdot C h \|\phi\|_{H^2(\Omega)} \\
&\leq C h^2 \|A u\|_{L^2(\Omega)} \cdot \|A \phi\|_{L^2(\Omega)} \\
&\leq C h^2 \|f\|_{L^2(\Omega)} \cdot \|u - u_h\|_{L^2(\Omega)} \\
\|u - u_h\|_{L^2(\Omega)} &\leq C h^2 \|f\|_{L^2(\Omega)} \quad \square
\end{aligned}$$

$$\left(\begin{aligned} A &= -\nabla \cdot a \nabla \\ (A\phi, v) &= \int_{\Omega} -\nabla \cdot a \nabla \phi \cdot v \, dx = \int_{\Omega} a \nabla \phi \cdot \nabla v \, dx = a(\phi, v) \end{aligned} \right) \quad \text{Green's}$$

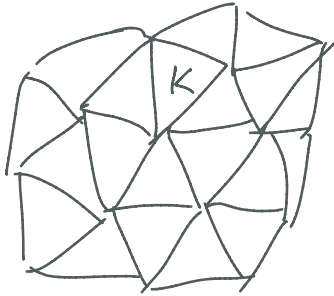
Thm: Variation of Thm 5.6

Let $A = -\nabla \cdot a \nabla + b \cdot \nabla + c$
and $a(u_h, v) = L(v) \quad \forall v \in V_h$



then $\|u - u_h\|_{H^1(\Omega)}^2 \leq C \sum_{K \in \tilde{T}_h} \mathcal{R}_K^2(u_h)$

where $\mathcal{R}_K^2(u_h) = h_K^2 \|Au_h - f\|_{L^2(K)}^2$



$+ h_K \| [u \cdot a \nabla u_h] \|_{L^2(\partial K \setminus \Gamma)}^2$



$[v] = v^+ - v^-$
jump.

Proof: Let $e = u - u_h$
 $a_0 \|e\|_{H^1(\Omega)}^2 \stackrel{\text{coercivity}}{\leq} a(e, e) \stackrel{\text{G.O.}}{=} a(e, e - \tilde{I}_h e) \stackrel{\text{Clement}}{\downarrow}$

$= \sum_{K \in \tilde{T}_h} \int_K a \nabla e \cdot \nabla (e - \tilde{I}_h e) + b \cdot \nabla e (e - \tilde{I}_h e) + c e (e - \tilde{I}_h e) dx$

$= \sum_{K \in \tilde{T}_h} \int_K (f - cu_h - b \cdot \nabla u_h)(e - \tilde{I}_h e) dx - \int_K a \nabla u_h \cdot \nabla (e - \tilde{I}_h e) dx \quad \left(a(u, v) = (f, v) \right)$

$= \sum_{K \in \tilde{T}_h} \int_K (f - cu_h - b \cdot \nabla u_h + \nabla \cdot a \nabla u_h)(e - \tilde{I}_h e) dx$

$$\begin{aligned}
 & - \sum_{K \in \mathcal{T}_h} \int_{\partial K \cap \Gamma} n \cdot a \nabla u_h \cdot (e - I_h e) ds \\
 & \left(\int_K a \nabla u_h \cdot \nabla v dx = \overset{\text{(Green)}}{\int_K -\nabla \cdot a \nabla u_h v dx} + \int_{\partial K} n \cdot a \nabla u_h v ds \right)
 \end{aligned}$$

$$= \sum_{K \in \mathcal{T}_h} \int_K (f - Au_h)(e - I_h e) dx$$

$$- \sum_{\xi \in \mathcal{E}} \int_{\xi \setminus \Gamma} [n \cdot a \nabla u_h](e - I_h e) ds$$


$$\leq \sum_{K \in \mathcal{T}_h} \|f - Au_h\|_{L^2(K)} \cdot \|e - I_h e\|_{L^2(K)}$$

$$+ \left| \sum_{K \in \mathcal{T}_h} \frac{1}{2} \int_{\partial K \cap \Gamma} [n \cdot a \nabla u_h](e - I_h e) ds \right|$$

$$\leq \sum_{K \in \mathcal{T}_h} C h_K \|f - Au_h\|_{L^2(K)} \cdot \|e\|_{H^1(\omega_K)}$$

$$+ \sum_{K \in \mathcal{T}_h} C \| [n \cdot a \nabla u_h] \|_{L^2(\partial K \cap \Gamma)} \cdot \|e - I_h e\|_{L^2(\partial K)}$$

$$\leq \sum_{K \in \mathcal{T}_h} \left(C h_K \|f - Au_h\|_{L^2(K)} + C h_K^{1/2} \| [n \cdot a \nabla u_h] \|_{L^2(\partial K \cap \Gamma)} \right)$$

$$\left(\sum_k a_k b_k \leq (\sum a_k^2)^{1/2} (\sum b_k^2)^{1/2} \right) \underbrace{\|e\|_{H'(\omega_\#)}}_{\left(\sum_{K \in \tilde{T}_h} h_K^2 \|f - A u_h\|_{L^2(K)}^2 + h_K \| [u \cdot \nu u_h] \|_{L^2(\partial K)}^2 \right)^{1/2}}$$

$$\cdot \left(\sum_{K \in \tilde{T}_h} \|e\|_{H'(\omega_\#)}^2 \right)^{1/2}$$

$$\left((a+b)^2 \leq 2a^2 + 2b^2 \right)$$

$$\leq C \left(\sum_{K \in \tilde{T}_h} R_K^2(u_h) \right)^{1/2} \cdot \|e\|_{H'(\Omega)}$$

$$\therefore \|e\|_{H'(\Omega)}^2 \leq C \sum_{K \in \tilde{T}_h} R_K^2(u_h) \quad \square$$

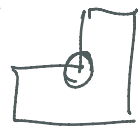
Error in a linear functional

$$q(u - u_h) \quad q: V \rightarrow \mathbb{R} \quad q(v) = \int_\omega v dx$$

We introduce the adjoint problem

$$a(w, \phi) = q(w), \quad \forall w \in V.$$

Thm: $q(u - u_h) \leq \sum_K R_K(u_h) \cdot W_K(\phi)$



where $R_k^2(u_n) = \|Au_n - f\|_{L^2(K)}^2 + h_k^{-1} \|[n \cdot a \nabla u_n]\|_{L^2(\partial K)}^2$

$$W_k^2(\phi) = \|\phi - I_h \phi\|_{L^2(K)}^2 + h_k \|\phi - I_h \phi\|_{L^2(\partial K)}^2$$

Proof: $q(e) = a(e, \phi) = a(e, \phi - I_h \phi)$

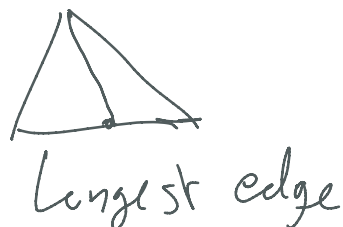
$$= \sum_K \int_K (f - cu_n - b \cdot \nabla u_n)(\phi - I_h \phi) dx - \sum_K \int_K a \nabla u_n \cdot \nabla \phi - I_h \phi dx$$

$$\leq \dots \leq \sum_{K \in T_h} \|f - Au_n\|_{L^2(K)} \|\phi - I_h \phi\|_{L^2(K)} + h_k^{-1/2} \|[n \cdot a \nabla u_n]\|_{L^2(\partial K)} h_k^{1/2} \|\phi - I_h \phi\|_{L^2(\partial K)}$$

$$\leq C \sum_{K \in T_h} R_k(u_n) W_k(\phi)$$

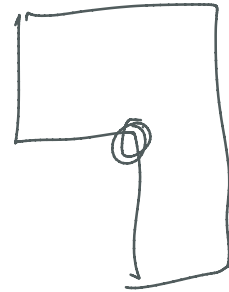
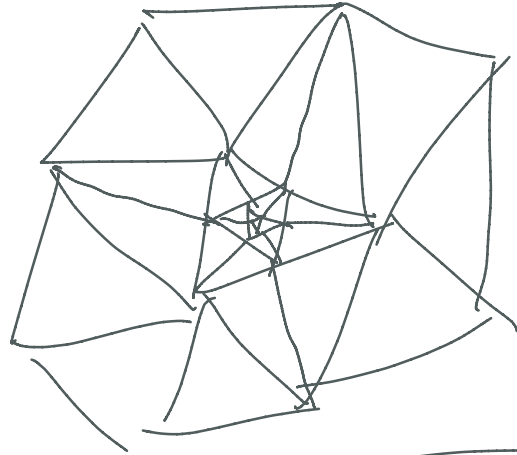
Called goal oriented adaptivity.

Mesh refinement



No hanging nodes

The a posteriori error
bound drives
mesh adaptivity



- 1) Compute U_h
- 2) Compute $P_k^2(U_h)$
- 3) Mark element for refinement
- 4) Refine mesh
- 5) Stop if $\text{error} < \text{TOL}$.