MSA101/MVE187 2021 Lecture 13 Variational Bayes

Petter Mostad

Chalmers University

October 11, 2021

- Last time: The EM algorithm: Using Kullback-Leibler divergence to find a maximal posterior estimate.
- This time: Variational Bayes: Using Kullback-Leibler divergence to find an optimally fitting density to the posterior.

An extension of the KL notation

Let us define

$$\mathsf{KL}[q||p] = \mathsf{E}_q\left[-\log\frac{p(z)}{q(z)}\right] = -\int q(z)\log\frac{p(z)}{q(z)}\,dz$$

for any density q(z) and any function p(z) so that the integral exists. (For standard KL p must be a density).

• Consequence: If $p_2(z) = Cp_1(z)$ then for any q

$$\mathsf{KL}[q||p_2] = \mathsf{E}_q\left[-\log\frac{Cp_1(z)}{q(z)}\right] = -\log C + \mathsf{KL}[q||p_1].$$

• For example, if $\int p_2(z) dz = C$ then for any q

$$\mathsf{KL}[q||p_2] \ge -\log C$$

because $KL[q||p_2/C] \ge 0$, with minimum occurring when $q \propto_z p_2$. • We still have

$$\mathsf{KL}[q||p] = \mathsf{E}_q[-\log p(z)] - H_q[Z]$$

where $H_q[Z]$ is the entropy of a random variable Z with density q.

In the identity

$$\pi(\mathsf{data}, \theta) = \pi(\theta \mid \mathsf{data})\pi(\mathsf{data})$$

 π (data) is a constant as a function of θ .

• Thus for a density q for θ ,

$$\mathsf{KL}[q||\pi(\mathsf{data}, \cdot)] = -\log \pi(\mathsf{data}) + \mathsf{KL}[q||\pi(\cdot | \mathsf{data})].$$

We may try to find a q minimizing KL[q||π(· | data)] by finding a q minimizing KL[q||π(data, ·)]: This is part of the Variational Bayes idea.

Consider the identity

$$\pi(x, z \mid \theta) = \pi(x \mid \theta)\pi(z \mid x, \theta).$$

Considering this as a function of z, $\pi(x \mid \theta)$ is a constant.

For a density q for z we get

$$\mathsf{KL}[q||\pi(x,\cdot\mid\theta)] = -\log\pi(x\mid\theta) + \mathsf{KL}[q||\pi(\cdot\mid x,\theta)]$$

▶ The above equation is in the core of the proof of the EM algorithm:

- Set $q(z) = \pi(z \mid x, \theta^{OLD})$ for some θ^{OLD} . (E step)
- Find a θ^{NEW} that minimizes the left-hand side. (M step)
- Then, moving from θ^{OLD} to θ^{NEW}, the left-hand side will decrease, and KL(q||π(· | x, θ)] will increase. Thus − log π(x | θ) will decrease.

Approximations using Variational Bayes

- Idea: Finding an approximation to the posterior π(θ | data) in some family of densities Q that does not necessarily contain the posterior.
- ► More specifically find the q ∈ Q minimizing the Kullback Leibler divergence from q to the posterior.
- Writing as above

$$\mathsf{KL}[q||\pi(\mathsf{data}, \cdot)] = -\log \pi(\mathsf{data}) + \mathsf{KL}[q||\pi(\cdot | \mathsf{data})].$$

we instead find the \hat{q} minimizing $KL[q||\pi(data, \cdot)]$.

- As log π(data) ≥ − KL[q||π(data, ·)] the value − KL[ĝ||π(data, ·)] is called the *evidence lower bound*, or ELBO.
- Thus we want to maximize

$$egin{array}{rll} \mathcal{L}(q) &=& -\operatorname{\mathsf{KL}}[q||\pi(\operatorname{\mathsf{data}},\cdot)] = \int q(heta)\lograc{\pi(\operatorname{\mathsf{data}}, heta)}{q(heta)}\,d heta \ &=& \operatorname{\mathsf{E}}_q[\log\pi(\operatorname{\mathsf{data}}, heta)] + H_q[heta] \end{array}$$

where $H_q[\theta]$ is the entropy of a variable θ with density q.

Splitting θ into components (or subvectors)

Let us look for densities q that can be written as products

$$q(heta) = \prod_{i=1}^n q_i(heta_i)$$

where $\theta = (\theta_1, \theta_2, \dots, \theta_n)$ is split into (groups of) dimensions.

For the entropy term we get that

$$H_q[\theta] = \sum_{i=1}^n H_{q_i}[\theta_i]$$

where θ_i are variables with densities q_i .

▶ For any $i \in 1, ..., n$ the first term of $\mathcal{L}(q)$ may be rewritten

$$\mathsf{E}_{q}[\log \pi(\mathsf{data}, \theta)] = \mathsf{E}_{q_i}\left[\mathsf{E}_{q_j, j \neq i}\left[\log \pi(\mathsf{data}, \theta)\right]\right]$$

So if we fix all q_j with $j \neq i$, the optimal q_i maximizing $\mathcal{L}(q)$ is the q_i maximizing

$$\begin{split} & \mathsf{E}_{q_i}\left[\mathsf{E}_{q_i, j \neq i}\left[\log \pi(\mathsf{data}, \theta)\right]\right] + H_{q_i}[\theta_i] \\ &= -\mathsf{KL}\left[q_i||\exp\left(\mathsf{E}_{q_i, j \neq i}\left[\log \pi(\mathsf{data}, \cdot)\right]\right)\right] \end{split}$$

▶ We have seen that KL $[q_i|| \exp (E_{q_i, j \neq i} [\log \pi(\text{data}, \cdot)])]$ is minimized when

$$q_i(heta_i) \propto_{ heta_i} \exp\left(\mathsf{E}_{q_j, j
eq i}\left[\log \pi(\mathsf{data}, \cdot)
ight]
ight)$$

- ► If we write out these n equations for i = 1,..., n, they become n equations in the n unknowns q₁, q₂,..., q_n.
- Sometimes it is possible to simultaneously solve these equations.
- NOTE: The solution we get is the optimal using the assumption that the posterior splits as independent distributions over θ₁, θ₂,..., θ_n, but making no other assumptions, e.g., about parametric classes.

Variational Bayes: Toy example

Consider the following example:

$$egin{array}{rcl} y_1,\ldots,y_n&\sim& {\sf Normal}(\mu, au^{-1})\ \pi(\mu)&\propto& 1\ \pi(au)&\propto& 1/ au \end{array}$$

Using conjugacy, we get that the exact posterior is given by

$$\tau \mid y_1, \dots, y_n \sim \operatorname{Gamma}\left(\frac{n-1}{2}, \frac{n-1}{2}s^2\right)$$

 $\mu \mid \tau, y_1, \dots, y_n \sim \operatorname{Normal}\left(\overline{y}, (n\tau)^{-1}\right)$

where s^2 is the sample variance.

As an illustration, we find the Variational Bayes approximate posterior. Note:

$$\pi(y_1, \dots, y_n, \mu, \tau) \propto \frac{1}{\tau} \prod_{i=1}^n \frac{1}{\sqrt{2\pi/\tau}} \exp\left(-\frac{\tau}{2}(y_i - \mu)^2\right)$$
$$\log \pi(y_1, \dots, y_n, \mu, \tau) = C + \left(\frac{n}{2} - 1\right) \log \tau - \frac{\tau}{2}(n-1)s^2 - \frac{n\tau}{2}(\overline{y} - \mu)^2$$

Variational Bayes: Toy example continued

- We use as approximation for the posterior the family of densities q(μ, τ) = q₁(μ)q₂(τ), so that we assume μ and τ are independent, but we do not make additional restrictions on q₁ and q₂.
- ► We get

$$\begin{array}{l} \exp\left(\mathsf{E}_{\mu}\left[\log\pi(\mathsf{data},\mu,\tau)\right]\right]\right)\\ \propto_{\tau} \quad \exp\left(\left(\frac{n}{2}-1\right)\log\tau-\frac{\tau}{2}(n-1)s^2-\frac{n\tau}{2}\,\mathsf{E}_{\mu}\left[(\overline{y}-\mu)^2\right]\right)\end{array}$$

From this we see that

$$q_2(\tau) = \operatorname{Gamma}\left(\tau; \frac{n}{2}, \frac{1}{2}(n-1)s^2 + \frac{n}{2}\operatorname{E}_{\mu}\left[(\overline{y} - \mu)^2\right]\right)$$

We get

$$\exp\left(\mathsf{E}_{\tau}\left[\log\pi(\mathsf{data},\mu,\tau)\right]\right) \propto_{\mu} \exp\left(-\frac{n}{2}\,\mathsf{E}_{\tau}[\tau](\overline{y}-\mu)^2\right)$$

From this we see that

$$q_1(\mu) = \operatorname{Normal}\left(\mu; \overline{y}, (n \operatorname{E}_{\tau}[\tau])^{-1}
ight).$$

Variational Bayes: Toy example continued

Taking expectations using these two densities leads to

$$\mathsf{E}_{\tau}[\tau] = \frac{n/2}{(n-1)s^2/2 + n/2 \cdot \mathsf{E}_{\mu}\left[(\overline{y}-\mu)^2\right]}$$

$$\mathsf{E}_{\mu}\left[(\overline{y}-\mu)^2\right] = (n \, \mathsf{E}_{\tau}[\tau])^{-1}$$

> This is two equations with two unknowns; solving gives

$$E_{\tau}[\tau] = \frac{1}{s^2}$$
$$E_{\mu}\left[(\overline{y} - \mu)^2\right] = \frac{s^2}{n}$$

The final solution is

$$q_{2}(\tau) = \operatorname{Gamma}\left(\tau; \frac{n}{2}, \frac{n}{2}s^{2}\right)$$
$$q_{1}(\mu) = \operatorname{Normal}\left(\mu; \overline{y}, \frac{s^{2}}{n}\right)$$

Presentation break for R illustration

Second option: Iterative solution

We would like to minimize

$$\mathsf{KL}\left[q_i||\exp\left(\mathsf{E}_{q_j,j\neq i}\left[\log\pi(\mathsf{data},\cdot)\right]\right)\right]$$

for i = 1, ..., n.

- ▶ If a simultaneous solution cannot be found, we can start with a reasonable solutions $q_1, q_2, ..., q_n$ and then repeatedly cycle through i = 1, ..., n minimizing the KL divergence above for q_i (keeping q_j , $j \neq i$ fixed).
- Generally this is done by assuming that q_i is in some parametric family for each i, so that one can optimize over the values of the parameters.
- In this case, we assume that the posterior is approximated as splitting in independent factors over the θ_i, we assume that the q_i are in particular parametric families, and we may get approximation errors.
- ▶ However, the method may scale well in very high dimensions.
- ► The *mean field* variational Bayes approximation of the posterior.

What if we minimize $KL[\pi(data | \cdot)||q]$ instead of $KL[q||\pi(data | \cdot)]$?

We have

$$\begin{aligned} \mathsf{KL}[\pi(\cdot \mid \mathsf{data})||q] &= -\int \pi(\theta \mid \mathsf{data}) \log \frac{q(\theta)}{\pi(\theta \mid \mathsf{data})} \, d\theta \\ &= \int \pi(\theta \mid \mathsf{data}) \log \pi(\theta \mid \mathsf{data}) \, d\theta - \int \pi(\theta \mid \mathsf{data}) \log q(\theta) \, d\theta \end{aligned}$$

so we only need to find the q maximizing the last term.

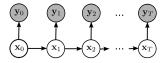
▶ If we assume that $q(\theta) = q(\theta \mid \eta) = \prod_{i=1}^{n} q_i(\theta_i \mid \eta_i)$ we get that

$$egin{aligned} &\int \pi(heta \mid \mathsf{data}) \log q(heta \mid \eta) \, d heta &= \sum_{i=1}^n \int \pi(heta \mid \mathsf{data}) \log q_i(heta_i \mid \eta_i) \, d heta \ &= \sum_{i=1}^n \int \pi(heta_i \mid \mathsf{data}) \log q_i(heta_i \mid \eta_i) \, d heta_i. \end{aligned}$$

So we optimize by setting $q_i(\theta_i | \eta_i)$ equal to the marginal posterior $\pi(\theta_i | \text{data})$ for each *i* (or choose η_i to minimize the KL divergence). Less useful approximations in practice.

From last time: The Baum-Welch algorithm (as EM example)

We consider an HMM where all the x_i have a finite state spaces



but where some of the parameters of the distributions $\pi(X_0)$, $\pi(X_i \mid X_{i-1})$, and $\pi(Y_i \mid X_i)$ are unknown. Objective: Given fixed values for the y_i , find maximum likelihood estimates for the parameters in the model.

- Note: If assuming flat priors the problem becomes that of computing the parameters maximizing the posterior, i.e., finding the MAP.
- Idea: Use the EM algorithm, with the values of the x_i as the augmented data.
- The E step of the EM algorithm is computed using (a small generalization of) the Forward-Backward algorithm.

The Baum-Welch algorithm: Simplified example

For simplicity we assume each X_i can have values 1,..., M, and we assume X₀ = 1. We assume there is one unknown parameter θ (with flat prior) with

$$\Pr(X_i = k \mid X_{i-1} = j) = \begin{cases} \theta/2 & |j - k| = 1 \text{ and } 1 < j < M \\ \theta & |j - k| = 1 \text{ and } j = 1 \text{ or } j = M \\ 1 - \theta & j = k \end{cases}$$

Assuming observed data is compatible with the model, the full loglikelihood given θ becomes

$$\begin{split} &\log \left(\pi(x_0, \dots, x_T, y_0, \dots, y_T \mid \theta) \right) \\ &= &\log \pi(x_0) + \sum_{i=1}^T \log \pi(x_i \mid x_{i-1}, \theta) + \sum_{i=0}^T \log \pi(y_i \mid x_i) \\ &= & C + c_1 \log \theta + c_2 \log(1 - \theta) \end{split}$$

where c_1, c_2 are counts of one-step transitions, and stays in the same value, respectively, while C is a constant not involving θ .

Example continued

- ▶ In the E step, we would like to compute the expectation of the full loglikelihood under the distribution $\pi(x_0, \ldots, x_T \mid y_0, \ldots, y_T, \theta^{old})$ for some parameter θ^{old} .
- ► Thus we need to compute the expectations of the counts c₁ and c₂ under this distribution.
- Fixing θ^{old} , we can use the Forward-Backward algorithm to compute the densities $\pi(x_i \mid y_0, \ldots, y_i)$ and $\pi(y_{i+1}, \ldots, y_T \mid x_i)$. Further we have that

$$\begin{aligned} &\pi(x_i, x_{i+1} \mid y_0, \dots, y_T) \\ &\propto & \pi(y_{i+1}, \dots, y_T \mid x_i, x_{i+1}) \pi(x_i, x_{i+1} \mid y_0, \dots, y_i) \\ &\propto & \pi(y_{i+2}, \dots, y_T \mid x_{i+1}) \pi(y_{i+1} \mid x_{i+1}) \pi(x_{i+1} \mid x_i) \pi(x_i \mid y_0, \dots, y_i) \end{aligned}$$

making it possible to compute the joint posterior for x_i and x_{i+1} from these densities.

The algorithm can now be summed up as

- Choose starting parameter θ^{old} .
- Run the Forward-Backward algorithm on the Markov model with parameter θ^{old} to compute the numbers E[c₁] and E[c₂].
- Find the θ maximizing the expected loglikelihood

$$\mathsf{E}[c_1]\log\theta + \mathsf{E}[c_2]\log(1-\theta).$$

In fact, we get

$$heta^{new} = rac{1}{T} \operatorname{\mathsf{E}}[c_1]$$

- Iterate until convergence.
- See implementation in R