

The backward difference formula provides

Backward Euler scheme: $y_{e+1} = y_e + k f(y_{e+1})$

Similar to above, one could consider

(P) Crank-Nicolson schemes $y_{e+1} = y_e + \frac{k}{2} (f(y_e) + f(y_{e+1}))$
average of f

Ex: Consider

IVP $\begin{cases} \dot{y} = 5y(t), & 0 \leq t \leq T \\ y(0) = 1 \end{cases}$

Define stepsize $k = \frac{T}{N}$ for some large N . (ex. $N = 100$)

(i) One step of forward Euler reads

(S) $\underbrace{y_1}_{\text{Def Euler}} = \underbrace{y_0}_{\text{Def IVP}} + k \cdot \underbrace{f(y_0)}_{\text{Def FC}} = y_0 + k \cdot 5 \cdot y_0 = 1 + k \cdot 5 \cdot 1 = 1 + 5k \approx \underline{y(k)}$

(ii) One step of backward Euler reads

$$y_1 = y_0 + k \cdot f(y_1) \approx 1 + 5k y_1 \quad \text{or} \quad y_1 = \frac{1}{1 - 5k} \approx y(k)$$

(iii) One step of Crank-Nicolson reads;

$$y_1 = y_0 + \frac{k}{2} (f(y_0) + f(y_1)) = 1 + \frac{k}{2} \cdot 5 (y_0 + y_1) \quad \text{or} \quad y_1 = \frac{1 + 5k/2 y_0}{1 - 5k/2 y_1}$$

Ex: (Application to PDE, see also lab)

Consider the following system of linear IVP

$$\begin{cases} M \cdot \dot{z}(t) + S' z(t) = F(t), & 0 \leq t \leq T \\ z(0) = z_0 \end{cases}$$

where M is an $n \times n$ matrix (ex. mass matrix)
 S' " " " " (ex. stiffness matrix)
 $F(t) = \begin{pmatrix} f_1(t) \\ \vdots \\ f_m(t) \end{pmatrix}$ is a vector (ex. load vector)
 $z(t) = \begin{pmatrix} z_1(t) \\ \vdots \\ z_n(t) \end{pmatrix}$ is the unknown vector

(i) Euler scheme applied to above IVP gives

$$M \left(\frac{\tilde{z}^{(l+1)} - \tilde{z}^{(l)}}{k} \right) + \tilde{z}^{(l)} = F(t_l) \text{ or } M \tilde{z}^{(l+1)} = (M - k S') \tilde{z}^{(l)} + k F(t_l)$$

or $\tilde{z}^{(0)} = \tilde{z}(0)$

$$t_{l+1} = t_l + k$$

$$M \tilde{z}^{(l+1)} = (M - k S') \tilde{z}^{(l)} + k F(t_l)$$

for $l = 0, 1, 2, \dots$

where $\tilde{z}^{(l)} \approx \tilde{z}(t_l)$

(ii) Backward Euler reads

$$M \left(\frac{\tilde{z}^{(l+1)} - \tilde{z}^{(l)}}{k} \right) + \tilde{z}^{(l+1)} = F(t_{l+1}) \text{ or } (M + k S') \tilde{z}^{(l+1)} = M \tilde{z}^{(l)} + k F(t_{l+1})$$

That is the recursion

$$\tilde{z}^{(0)} = \tilde{z}(0)$$

$$(M + k S') \tilde{z}^{(l+1)} = M \tilde{z}^{(l)} + k F(t_{l+1})$$

(iii) CN reads

$$\tilde{z}^{(0)} = \tilde{z}(0)$$

$$(M + \frac{k}{2} S') \tilde{z}^{(l+1)} = (M - \frac{k}{2} S') \tilde{z}^{(l)} + \frac{k}{2} (F(t_{l+1}) + F(t_l))$$

Chapter VII: PDE in 1D

Goal: Use FEM and above time integrators to numerically discretise heat and wave equation in 1D ($u(x, t)$)

FEM $\rightarrow$ Euler/CN

1) Heat equation in 1D:

Model problem to describe heat flow along a thin wire/metal rod of length 1;

$$(M) \begin{cases} u_t(x, t) - u_{xx}(x, t) = f(x, t) & 0 < x < 1, t > 0 & \text{DE} \\ u(0, t) = u_x(1, t) = 0 & t > 0 & \text{BC} \\ u(x, 0) = u_0(x) & 0 < x < 1, & \text{IC} \end{cases}$$

where $u(x, t) \rightarrow$ temperature at point x , time t (unknown)

$u_0(x) \rightarrow$ initial temperature profile

(18)

$u(0,t) = 0 \rightarrow$ fixed temperature 0 at $x=0$ (hom. Dirichlet BC)

$u_x(1,t) = 0 \rightarrow$ insulated boundary at $x=1$ (no heat flux)
(hom. Neumann BC)

Offline!

$f(x,t) \rightarrow$ heat sources/sinks

Th. The sol. to the heat eq. (H) satisfies the stability estimate:

$$(i) \|u(\cdot, t)\|_{L^2(0,1)} \leq \|u_0\|_{L^2(0,1)} + \int_0^t \|f(\cdot, s)\|_{L^2(0,1)} ds$$

$$(ii) \|u_x(\cdot, t)\|_{L^2(0,1)} \leq \|u'_0\|_{L^2(0,1)} + \int_0^t \|f(\cdot, s)\|_{L^2(0,1)} ds$$

$$(iii) \text{ When } f \equiv 0, \text{ one has } \|u(\cdot, t)\|_{L^2(0,1)} \leq \|u_0\|_{L^2(0,1)} e^{-t}$$

Rem. Notation $\|u(\cdot, t)\|_{L^2(0,1)}$ means integrate w.r. respect to x :
 $\left(\int_0^1 u(x,t)^2 dx \right)^{1/2}$
 $\xrightarrow{\text{integrate w.r. } x}$

• (i) is used to show uniqueness of sol. to (H)

• (iii) says: "mean temperature" $\searrow$ in time

2) Discretisation of the heat equation:

Consider model problem

$$(H) \begin{cases} u_t(x,t) - u_{xx}(x,t) = f(x,t) & 0 < x < 1, 0 < t \leq T \\ u(0,t) = u(1,t) = 0 & 0 < t \leq T \\ u(x,0) = u_0(x) & 0 < x < 1 \end{cases} \quad \begin{matrix} \text{(DE)} \\ \text{(BC)} \\ \text{(IC)} \end{matrix}$$

S Idea: FEM in space $\leadsto$ linear syst. of ODE $\leadsto$ backward Euler in time.

(i) To get a VF, consider the following test/trial space

$$H_0^1 = \{v: (0,1) \rightarrow \mathbb{R} : v, v' \in L^2(0,1), v(0) = v(1) = 0\}$$

Multiply DE with $v = v(x) \in H_0^1$, integrate over $(0,1)$, by parts:

$$\begin{aligned} \int_0^1 u_t(x,t) v(x) dx - \int_0^1 u_{xx}(x,t) v(x) dx &= \int_0^1 f(x,t) v(x) dx \\ &= \underbrace{\left[u_x(x,t) v(x) \right]_0^1}_{=0 \text{ since } v \in H_0^1} - \int_0^1 u_x(x,t) v_x(x) dx \end{aligned}$$

The VF reads: For all $t \in (0, T]$:

$$(VF) \text{ Find } u(\cdot, t) \in H_0^1 \text{ s.t. } (u_t(\cdot, t), v)_V + (u_x(\cdot, t), v_x)_V = (f(\cdot, t), v)_V \\ u(x, 0) = u_0(x) \quad \forall v \in H_0^1$$

(ii) Next, discretise in space using FEM,

Consider uniform partition of $[0, 1]$, $T_h: x_0 = 0 < x_1 < x_2 < \dots < x_{m+1} = 1$,
with mesh $h = x_j - x_{j-1} = \frac{1}{m+1}$.

Consider space $V_h^0 = \{v: [0, 1] \rightarrow \mathbb{R} : v \text{ cont. pw linear on } T_h, \\ v(0) = v(1) = 0\} = \text{span}(\varphi_1, \varphi_2, \dots, \varphi_m)$
with hat test φ_j .

The FE problem reads: For all $t \in (0, T]$,

$$(FE) \text{ Find } u_h(\cdot, t) \in V_h^0 \text{ s.t. } (u_{h,t}(\cdot, t), \chi)_V + (u_{h,x}(\cdot, t), \chi_x)_V = (f(\cdot, t), \chi)_V \\ u_h(x, 0) = \Pi_h u_0(x) \quad \forall \chi \in V_h^0$$

Here, $\Pi_h u_0$ is the cont. pw linear interpol. of u_0 .

(iii) We get a linear syst. of ODE by choosing

test $\chi = \varphi_i$, $i = 1, 2, \dots, m$, and writing

$$u_h(x, t) = \sum_{j=1}^m \underbrace{\zeta_j(t)}_{\text{time dependant unknowns}} \varphi_j(x)$$

time dependant unknowns

Insert above into (FE) to get:

$$\begin{cases} \sum_{j=1}^m \zeta_j(t) \underbrace{(\varphi_i, \varphi_j)}_{m_{ij}} + \sum_{j=1}^m \zeta_j(t) \underbrace{(\varphi_i', \varphi_j')}_s = \underbrace{(f(\cdot, t), \varphi_i)}_{F_i(t)} \quad \text{for } i=1, 2, \dots, m. \\ u_h(x, 0) = \Pi_h u_0(x) \Rightarrow \sum_{j=1}^m \zeta_j(0) \varphi_j(x) \stackrel{!}{=} \sum_{j=1}^m u_0(x_j) \varphi_j(x) \end{cases}$$

This gives

$$(ODE) \quad \begin{cases} M \dot{\zeta}(t) + S \zeta(t) = F(t) \\ \zeta(0) = \zeta_0 \end{cases}$$

where $M \rightarrow$ mass matrix, $S \rightarrow$ stiffness matrix