

Recall:

• Wave eq.

$$(W) \begin{cases} u_{tt}(x,t) - u_{xx}(x,t) = f(x,t) & 0 < x < 1 \\ u(0,t) = u(1,t) = 0 & 0 < t \leq T \\ u(x,0) = u_0(x), u_t(x,0) = v_0(x) \end{cases}$$

$$u_t = v \quad \Leftrightarrow \quad \begin{pmatrix} u \\ v \end{pmatrix}_t = \begin{pmatrix} 0 & 1 \\ \partial_x^2 & 0 \end{pmatrix} \begin{pmatrix} u \\ v \end{pmatrix} + \begin{pmatrix} 0 \\ f \end{pmatrix}$$

• Conservation of energy ($f \equiv 0$)

$$\frac{1}{2} \|u_t(\cdot, t)\|_{L^2}^2 + \frac{1}{2} \|u(\cdot, t)\|_{L^2}^2 \equiv \text{const} \quad \forall t > 0$$

• Variational formulation:

(VF) Find $u(\cdot, t) \in H_0^1(0,1)$ for $0 < t \leq T$, s.t.

$$(u_{tt}(\cdot, t), v)_{L^2} + (u_x(\cdot, t), v')_{L^2} = (f(\cdot, t), v)_{L^2} \quad \forall v \in H_0^1$$

$$u(x,0) = u_0(x), u_t(x,0) = v_0(x)$$

(ii) To get a FE problem, consider the space $V_h^0 = \text{span}(\varphi_1, \varphi_2, \dots, \varphi_m)$, where φ_j are hat functions. We get

(FE) Find $U(\cdot, t) \in V_h^0$ for $0 < t \leq T$ s.t.

$$(U_{tt}(\cdot, t), \chi)_{L^2} + (U_x(\cdot, t), \chi')_{L^2} = (f(\cdot, t), \chi)_{L^2} \quad \forall \chi \in V_h^0$$

$$U(x, 0) = \Pi_h u_0(x)$$

$$U_t(x, t) = \Pi_h \downarrow v_0(x)$$

↓
interpolant of u_0, v_0 ($\in V_h^0$)

(iii) From (FE), we will find a system of linear differential equation by writing

$$U(x, t) = \sum_{j=1}^m \boxed{\tilde{z}_j(t)} \varphi_j(x) \quad \text{and take } \chi = \varphi_i \text{ for } i=1, \dots, m.$$

↑
time dependant

Into (FE) gives:

$$\sum_{j=1}^m \ddot{\tilde{z}}_j(t) \underbrace{(\varphi_j, \varphi_i)}_{m_{ij}} + \sum_{j=1}^m \tilde{z}_j(t) \underbrace{(\varphi_j', \varphi_i')}_{S_{ij}} = \underbrace{(f(\cdot, t), \varphi_i)}_{F_i(t)} \quad \forall i=1, 2, \dots, m.$$

The above is a system of linear DE:

$$M \ddot{z}(t) + S z(t) = F(t), \text{ where}$$

$M \rightarrow$ mass matrix ($m \times m$)

$S \rightarrow$ stiffness matrix ($m \times m$)

$F \rightarrow$ load vector ($m \times 1$)

$z(t) \rightarrow$ unknown ($m \times 1$)

With initial value $z(0) = z_0, \dot{z}(0) = v_0$,

where $z_0 = \begin{pmatrix} u_0(x_1) \\ u_0(x_2) \\ \vdots \\ u_0(x_m) \end{pmatrix}$ and $v_0 = \begin{pmatrix} v_0(x_1) \\ \vdots \\ v_0(x_m) \end{pmatrix}$.

Next, we rewrite the above DE as a system of first order DE:

$$\begin{cases} M \dot{z}(t) = M w(t) \\ M w(t) + S z(t) = F(t) \end{cases}$$

(iv) Apply a numerical method to the above system: C-N with stepsize h .

$$\begin{cases} M \left(\frac{z^{(n+1)} - z^{(n)}}{k} \right) = M \left(\frac{\dot{z}^{(n+1)} + \dot{z}^{(n)}}{2} \right) \\ M \left(\frac{\dot{z}^{(n+1)} - \dot{z}^{(n)}}{k} \right) + \dot{z} \left(\frac{z^{(n+1)} + z^{(n)}}{2} \right) = \frac{F(t_{n+1}) + F(t_n)}{2} \end{cases}$$

Or as block-matrix :

$$\begin{pmatrix} M & -\frac{k}{2}M \\ \frac{k}{2}\dot{z} & M \end{pmatrix} \begin{pmatrix} z^{(n+1)} \\ \dot{z}^{(n+1)} \end{pmatrix} = \begin{pmatrix} M & \frac{k}{2}M \\ -\frac{k}{2}\dot{z} & M \end{pmatrix} \begin{pmatrix} z^{(n)} \\ \dot{z}^{(n)} \end{pmatrix} + \begin{pmatrix} 0 \\ \frac{k}{2}(F(t_{n+1}) + F(t_n)) \end{pmatrix}.$$

This provides approximations

$$z^{(n)} \approx z(t_n)$$

$$\dot{z}^{(n)} \approx \dot{z}(t_n) \approx \dot{z}(t_n)$$

for $t_n = n \cdot k$.

Let us show

Th: If $f \equiv 0$ in (W) , then C-N preserves
a discrete energy!

Rem: Backward/forward Euler schemes do not !!

Proof:

• C-N reads:

$$M \left(\frac{z^{(n+1)} - z^{(n)}}{k} \right) - M \left(\frac{y^{(n+1)} + y^{(n)}}{2} \right) = 0 \quad | \cdot k (z^{(n+1)} + z^{(n)})^T S' M^{-1}$$

$$M \left(\frac{y^{(n+1)} - y^{(n)}}{k} \right) + S' \left(\frac{z^{(n+1)} + z^{(n)}}{2} \right) = 0 \quad | \cdot k (y^{(n+1)} + y^{(n)})^T$$

+ add

$$\begin{aligned} & (z^{(n+1)} + z^{(n)})^T S' (z^{(n+1)} - z^{(n)}) - \frac{k}{2} (z^{(n+1)} + z^{(n)})^T S' (y^{(n+1)} + y^{(n)}) \\ & + (y^{(n+1)} + y^{(n)})^T M (y^{(n+1)} - y^{(n)}) + \frac{k}{2} (y^{(n+1)} + y^{(n)})^T S' (z^{(n+1)} + z^{(n)}) = \\ & = 0. \end{aligned}$$

= 0 since S' symmetric

Since S' and M are symmetric, the above reduces to:

$$\begin{aligned} & (z^{(n+1)})^T S' (z^{(n+1)}) + (y^{(n+1)})^T M (y^{(n+1)}) = \\ & = (z^{(n)})^T S' (z^{(n)}) + (y^{(n)})^T M (y^{(n)}) \end{aligned}$$

$$\|u_x^{(n)}\|_{L^2}^2 + \|u_\epsilon^{(n)}\|_{L^2}^2$$

potential kinetic

$$\begin{aligned} \|u_x^{(n)}\|_{L^2}^2 &= \left(\sum_{j=1}^n z_j^{(n)} \varphi_j'(x), \sum_{i=1}^n z_i^{(n)} \varphi_i'(x) \right)_{L^2} = \\ &= \sum_{j,i} z_j^{(n)} z_i^{(n)} \underbrace{(\varphi_j', \varphi_i')}_{\delta_{ij}}_{L^2} = (Z^{(n)})^T Z^{(n)} \end{aligned}$$

Chapter X: On our way to FEM in 2d

Goal: Extend integration by parts in 2d and higher.

Extend pw linear interpolation, FEM.

1) Green's formula:

To get a VF in 1d, we started with integration by parts $\rightarrow$ we extend this: Green's formula.

Th: (Green's formula)

Let $\Omega \subset \mathbb{R}^2$ open and bounded with $\partial\Omega$ pw smooth.

For $u \in C^{(2)}(\Omega)$ and $v \in C^{(1)}(\Omega)$, one gets

$$\iint_{\Omega} \left(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right) v \, dx \, dy = \int_{\partial\Omega} \left(\left(\frac{\partial u}{\partial x}, \frac{\partial u}{\partial y} \right) \cdot n \right) v \, ds$$

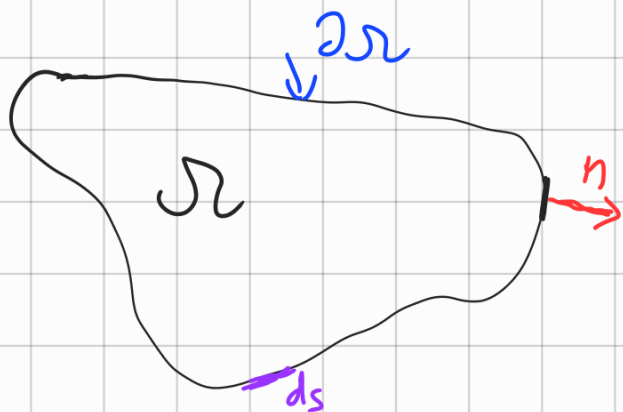
$$- \iint_{\Omega} \left(\frac{\partial u}{\partial x}, \frac{\partial u}{\partial y} \right) \cdot \left(\frac{\partial v}{\partial x}, \frac{\partial v}{\partial y} \right) \, dx \, dy,$$

where $n = n(x, y)$ is the outward unit normal vector

at the boundary at the point $(x, y) \in \partial\Omega$;

ds is a curve element on $\partial\Omega$,

- stand for scalar product, dot product, inner prod.



In short:

$$\int_{\Omega} (\Delta u) v \, dx = \int_{\partial\Omega} (\nabla u \cdot n) v \, ds - \int_{\Omega} \nabla u \cdot \nabla v \, dx$$

$x = (x_1, x_2) \in \mathbb{R}^2$

P_{200b} : ("simple case")



• Let us start with

$$\iint_{\Omega} \frac{\partial^2 u(x,y)}{\partial x^2} v(x,y) dx dy = \int_0^b \left(\int_0^a \frac{\partial^2 u(x,y)}{\partial x^2} v(x,y) dx \right) dy =$$

Def Ω

$$= \int_0^b \left(\frac{\partial u}{\partial x}(a,y) v(a,y) - \frac{\partial u}{\partial x}(0,y) v(0,y) \right) dy$$

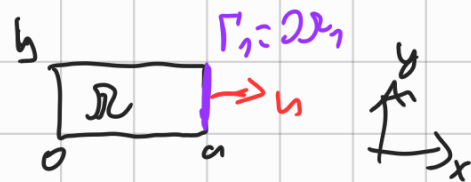
int. by parts in 1d

$$= \int_0^b \left(\int_0^a \frac{\partial u}{\partial x}(x,y) \frac{\partial v}{\partial x}(x,y) dx \right) dy =$$

$$= \dots - \iint_{\Omega} \frac{\partial u}{\partial x}(x,y) \frac{\partial v}{\partial x}(x,y) dx dy \quad (*)$$

Def Ω

• Next, observe that, on $\Gamma_1 = \partial \Omega$



one has $n(x,y) = (1,0)$, x is constant $\rightarrow dx$.

We compare with term, see above, (*)

$$\int_0^b \frac{\partial u}{\partial x}(a, y) v(a, y) dy = \int_0^b \underbrace{n(x, y)}_{(1, 0)} \cdot \left(\frac{\partial u}{\partial x}(x, y), \frac{\partial u}{\partial y}(x, y) \right) v(x, y) dy =$$

" on $\Gamma_1 : x=a \forall x \in \Gamma_1$ "

$$= \int_{\Gamma_1} (n \cdot \nabla u) v ds$$

• Similarly, on Γ_3 , one has $n(x, y) = (-1, 0)$ and (see (*)) :

$$\int_0^b \left(- \frac{\partial u}{\partial x}(0, y) v(0, y) \right) dy = \dots = \int_{\Gamma_3} (n \cdot \nabla u) v ds$$

↳ Thus, we can rewrite (*) as follows:

$$\iint_{\Omega} \frac{\partial^2 u}{\partial x^2} v dx dy = \int_{\Gamma_1 \cup \Gamma_3} (n \cdot \nabla u) v ds - \iint_{\Omega} \frac{\partial u}{\partial x} \frac{\partial v}{\partial x} dx dy \quad (1)$$

• Similarly:

$$\iint_{\Omega} \frac{\partial^2 u}{\partial y^2} v dx dy = \int_{\Gamma_2 \cup \Gamma_4} (n \cdot \nabla u) v ds - \iint_{\Omega} \frac{\partial u}{\partial y} \frac{\partial v}{\partial y} dx dy \quad (2)$$

Finally, taking the sum of (1) and (2), we get

$$\iint_{\Omega} (\Delta u) v dx = \int_{\partial \Omega} (n \cdot \nabla u) v ds - \iint_{\Omega} (\nabla u) \cdot (\nabla v) dx$$