

$$\begin{aligned} (R) & \begin{cases} u_t(x,t) - u_{xx}(x,t) = f(x,t) \\ u(0,t) = 0, u_x(1,t) = 0 \\ u(x,0) = u_0(x) \end{cases} \\ (H) & \end{aligned}$$

$\Gamma \in \Pi \mapsto x$

Euler $\mapsto t$

Estimates (i) $\|u(\cdot, t)\|_{L^2(\Omega)} \leq \|u_0\|_{L^2(\Omega)} + \int_0^t \|f(\cdot, s)\|_{L^2(\Omega)} ds$

(iii) $f \equiv 0$: $\|u(\cdot, t)\|_{L^2(\Omega)} \leq \|u_0\|_{L^2(\Omega)} e^{-2t}$

Use: $\frac{1}{2} \frac{d}{ds} \|u(\cdot, s)\|_{L^2}^2 + \|u_x(\cdot, s)\|_{L^2}^2 = 0$

• Quiz, feedback, exam

Application of (i): Continuous dependence of sol. to (H) on data:

If u_1 , resp. u_2 are sol. to (H) with RMS (= right hand side) f_1 , resp. f_2 and IC v_1 and v_2 : Then, using (i) above, one gets
 $[u_1 - u_2 \text{ solves PDE } u_t - u_{xx} = f_1 - f_2, u(x, 0) = v_1(x) - v_2(x)]$

$$\|u_1(\cdot, t) - u_2(\cdot, t)\|_{L^2} \leq \|v_1 - v_2\|_{L^2} + \int_0^t \|f_1(\cdot, s) - f_2(\cdot, s)\|_{L^2} ds$$

We next show another technical result

Th: ("energy estimate")

Consider (H) with $f \equiv 0$ and let $\varepsilon > 0$. Then, one has the estimate

$$\int_0^t \|u_f(\cdot, s)\|_{L^2(0,1)}^2 ds \leq \frac{1}{2} \sqrt{\ln\left(\frac{t}{\varepsilon}\right)} \cdot \|u_0\|_{L^2(0,1)}^2 \quad \forall t \in (0, T].$$

Proof:

- First, multiply PDE with $-t u_{xx}$, integrate by parts $\int_0^1 \dots dx$ to get:

$$-t \underbrace{\int_0^1 u_t(x, t) u_{xx}(x, t) dx}_{\text{by parts}} + t \underbrace{\int_0^1 (u_{xx}(x, t))^2 dx}_{\|u_{xx}(\cdot, t)\|_{L^2}^2} = 0$$

$$\underbrace{u_t(x, t) u_x(x, t) \Big|_{x=0}^1}_{=0} - \underbrace{\int_0^1 u_{tx}(x, t) u_{xx}(x, t) dx}_{\frac{1}{2} \frac{d}{dt} \|u_x\|_{L^2}^2} = 0 \quad (\text{Def norm})$$

This gives us: $\frac{t}{2} \frac{d}{dt} \|u_x(\cdot, t)\|_{L^2}^2 + t \|u_{xx}(\cdot, t)\|_{L^2}^2 \geq 0$

- Next, one observes that:

product rule

$$\frac{d}{dt} (t \cdot \|u_x(\cdot, t)\|_{L^2}^2) \stackrel{\text{product rule}}{=} \|u_x(\cdot, t)\|_{L^2}^2 + t \frac{d}{dt} \|u_x(\cdot, t)\|_{L^2}^2$$

that is $t \frac{d}{dt} \|u_x(\cdot, t)\|_{L^2}^2 = \frac{d}{dt} (t \cdot \|u_x(\cdot, t)\|_{L^2}^2) - \|u_x(\cdot, t)\|_{L^2}^2$

All in all, we obtain the relation

$$\frac{d}{dt} (t \cdot \|u_x(\cdot, t)\|_{L^2}^2) + 2t \|u_{xx}(\cdot, t)\|_{L^2}^2 = \|u_x(\cdot, t)\|_{L^2}^2$$

• We integrate the above over time $\int_0^t \dots ds$:

$$\begin{aligned} \int_0^t \frac{d}{ds} (s \cdot \|u_x(\cdot, s)\|_{L^2}^2) ds + 2 \cdot \int_0^t s \|u_{xx}(\cdot, s)\|_{L^2}^2 ds &= \\ &= \int_0^t \|u_x(\cdot, s)\|_{L^2}^2 ds \leq \frac{1}{2} \|u_0\|_{L^2}^2 \end{aligned}$$

☒

☒: We recall the relation

$$\frac{1}{2} \frac{d}{ds} \|u(\cdot, s)\|_{L^2}^2 + \|u_x(\cdot, s)\|_{L^2}^2 = 0$$

from the proof of the previous theorem.

Integrate with respect to time gives:

$\int_0^t$

$$\int_0^t \left\{ \frac{1}{2} \frac{d}{ds} \|u(\cdot, s)\|_{L^2}^2 + \|u_x(\cdot, s)\|_{L^2}^2 \right\} ds = 0 \Rightarrow$$

$$\frac{1}{2} \|u(\cdot, t)\|_{L^2}^2 - \frac{1}{2} \|u_0\|_{L^2}^2 + \int_0^t \|u_x(\cdot, s)\|_{L^2}^2 ds = 0$$

("s=t") ("s=0")

This gives us the bound

$$\int_0^t \|u_x(\cdot, s)\|_{L^2}^2 ds = \frac{1}{2} \|u_0\|_{L^2}^2 - \underbrace{\frac{1}{2} \|u(\cdot, t)\|_{L^2}^2}_{\geq 0} \leq \frac{1}{2} \|u_0\|_{L^2}^2$$

• The above thus provides:

$$\underbrace{\int_0^t \frac{d}{ds} (s \|u_x(\cdot, s)\|_{L^2}^2) ds}_{=0} + 2 \int_0^t s \|u_{xx}(\cdot, s)\|_{L^2}^2 ds \leq \frac{1}{2} \|u_0\|_{L^2}^2$$

$$t \|u_x(\cdot, t)\|_{L^2}^2 - 0$$

("s=t") ("s=0")

$$\hookrightarrow t \|u_x(\cdot, t)\|_{L^2}^2 + 2 \int_0^t s \|u_{xx}(\cdot, s)\|_{L^2}^2 ds \leq \frac{1}{2} \|u_0\|_{L^2}^2$$

Hence (i) $t \|u_x(\cdot, t)\|_{L^2}^2 \leq \frac{1}{2} \|u_0\|_{L^2}^2$

(ii) $2 \int_0^t s \|u_{xx}(\cdot, s)\|_{L^2}^2 ds \leq \frac{1}{2} \|u_0\|_{L^2}^2$

• Finally, we go back to what we were

interested in: $u_t - u_{xx} = 0$ or $u_t = u_{xx}$.

$$\int_{\varepsilon}^t \|u_t(\cdot, s)\|_{L^2} ds \stackrel{u_t = u_{xx}}{=} \int_{\varepsilon}^t \|u_{xx}(\cdot, s)\|_{L^2} ds =$$

$$= \int_{\varepsilon}^t \frac{1}{\sqrt{s}} \cdot \sqrt{s} \|u_{xx}(\cdot, s)\|_{L^2} ds \stackrel{C-S}{\leq}$$

$$\left(\int_{\varepsilon}^t \left(\frac{1}{\sqrt{s}} \right)^2 ds \right)^{1/2} \cdot \left(\int_{\varepsilon}^t s \|u_{xx}(\cdot, s)\|_{L^2}^2 ds \right)^{1/2} \leq$$

$$\stackrel{(ii)}{\leq} \left(\ln(t) - \ln(\varepsilon) \right)^{1/2} \cdot \left(\frac{1}{4} \|u_0\|_{L^2}^2 \right)^{1/2}$$

$$\leq \frac{1}{2} \sqrt{\ln\left(\frac{t}{\varepsilon}\right)} \cdot \|u_0\|_{L^2(0,1)}$$

$\Rightarrow$

2) Discretisation of the heat equation:

Consider the following PDE

$$(H) \begin{cases} u_t(x, t) - u_{xx}(x, t) = f(x, t) & 0 < x < 1, 0 < t \leq T \\ u(0, t) = u(1, t) = 0 \\ u(x, 0) = u_0(x) \end{cases}$$

(i) To find a variational formulation (in space),
consider trial/test space:

$$H_0^1(0,1) = \{v: [0,1] \rightarrow \mathbb{R}, v, v' \in L^2(0,1) \text{ and } v(0)=v(1)=0\}$$

As for BVP, we multiply PDE with test fct $v \in H_0^1$ integrate by parts and get:

$$\int_0^1 u_t(x,t) \cdot v(x) dx - \underbrace{\int_0^1 u_{xx}(x,t) v(x) dx}_{\underbrace{\left(u_x(x,t) v(x) \right)'_{x=0}^1}_{=0 \text{ since } v \in H_0^1}} = \int_0^1 f(x,t) v(x) dx$$

that is
$$\int_0^1 u_t(x,t) \cdot v(x) dx + \int_0^1 u_x(x,t) v'(x) dx = \int_0^1 f(x,t) v(x) dx$$

We thus obtain the VF:

(VF) For each $0 < t \leq T$, find $u(\cdot, t) \in H_0^1$ s.t.

$$(u_t(\cdot, t), v)_{L^2} + (u_x(\cdot, t), v')_{L^2} = (f(\cdot, t), v)_{L^2} \quad \forall v \in H_0^1$$

$$\underline{u(x, 0) = u_0(x)}$$

(ii) To get a FE prob., we consider a uniform partition of $[0,1]$; $T_h: x_0 = 0 < x_1 < x_2 < \dots < x_{m+1} = 1$, with $x_j - x_{j-1} = h = \frac{1}{m+1}$.

Consider space

$$V_h^0 = \{v: [0,1] \rightarrow \mathbb{R} : v \text{ cont, pw linear on } T_h \text{ and } v(0)=v(1)=0\}$$

$$= \text{span}(\varphi_1, \varphi_2, \dots, \varphi_m), \text{ where}$$

φ_j are hat functions.

Obs! $V_h^0 \subset H_0^1$.

The FE then reads

(FE) For each $0 < t \leq T$, find $U_h(\cdot, t) \in V_h^0$ s.t.

$$(U_{h,t}(\cdot, t), V_h)_{L^2} + (U_{h,x}(\cdot, t), V_h')_{L^2} = (f(\cdot, t), V_h)_{L^2}$$

$$\underline{U_h(x, 0)} = \Pi_h U_0(x) \quad \forall V_h \in V_h^0.$$

↓
cont pw. linear interpolant
of U_0 .

(iii) We now obtain a system of linear ODE
by writing $U_h(x, t) = \sum_{j=1}^m \underline{\zeta_j(t)} \cdot \varphi_j(x)$ and $V_h = \varphi_i$:

Insert into (FE) to get:

$$\sum_{j=1}^m \dot{\zeta_j(t)} \underbrace{(\varphi_j, \varphi_i)_{L^2}}_{m_{ij}} + \sum_{j=1}^m \zeta_j(t) \underbrace{(\varphi_j', \varphi_i')_{L^2}}_{S_{ij}} = \underbrace{(f(\cdot, t), \varphi_i)_{L^2}}_{F_i(t)}$$

for $i = 1, \dots, m$

This gives us the syst. of ODE:

$$M \dot{\zeta}(t) + S \zeta(t) = F(t)$$

$\zeta(0),$

where

$M = (m_{ij}) \rightarrow$ mass matrix (can be seen)

$$S = (s_{ij})_{i,j=1}^m \rightarrow \text{stiffness matrix} \quad (\text{see above})$$

$$F(t) = (F_i(t))_{i=1}^m \rightarrow \text{"load vector"}$$

$$Z(t) = \begin{pmatrix} z_1(t) \\ \vdots \\ z_m(t) \end{pmatrix} \rightarrow \text{unknown}$$

$$Z(0) = \begin{pmatrix} u_0(x_1) \\ u_0(x_2) \\ \vdots \\ u_0(x_m) \end{pmatrix} \quad (\text{def interpolant})$$

(iv) Finally, one uses f.ex. implicit Euler scheme to approximate $Z(t)$ at time grid points $0 = t_0 < t_1 < \dots < t_N = T$, $t_j - t_{j-1} = k = \frac{T}{N}$.

$$M \left(\frac{\underline{Z}^{(n+1)} - \underline{Z}^{(n)}}{k} \right) + k \underline{Z}^{(n+1)} = F(t_{n+1})$$

$$\Leftrightarrow (\underline{M} + k \underline{S}) \cdot \underline{Z}^{(n+1)} = M \underline{Z}^{(n)} + k F(t_{n+1}) \quad \text{for } n = 0, 1, 2, \dots$$

(Ax=b)

$$\underline{Z}^{(0)} = Z(0)$$

Computing $\underline{Z}^{(n)}$ gives approx. of $Z(t_n)$ and thus $u_n^n(x, t_n) \approx u(x, t)$ of heat eqn. (H)

Rem: • OK to use C-N, but for
exp. Euler one needs to be careful
(see last ex. in Ass. 1)

• For each time step $\rightarrow$ solve linear syst.
($Ax=b$)

• If F is complicated $\rightarrow$ use quadrature rule.

