

34) If $-\Delta E = \delta_0$ in \mathbb{R}^d , where δ_0 is the Dirac Delta distribution, then E is called the fundamental solution of $-\Delta$ in \mathbb{R}^d . Equivalently, for any smooth test function v vanishing outside of a bounded set, i.e. for any $v \in C_0^\infty(\mathbb{R}^d)$, E satisfies:

$$-\int_{\mathbb{R}^d} \Delta E(x) v(x) = v(0) \quad \left(\int \delta_0 v \stackrel{\text{def}}{=} v(0) \right)$$

Prove that $E(x) = \frac{1}{2\pi} \log\left(\frac{1}{|x|}\right)$ is a fundamental solution of $-\Delta$ in \mathbb{R}^2 .

Solution

We want to show that

$$-\int_{\mathbb{R}^2} \Delta \left(\frac{1}{2\pi} \log\left(\frac{1}{|x|}\right) \right) v(x) = v(0) \quad \forall v \in C_0^\infty$$

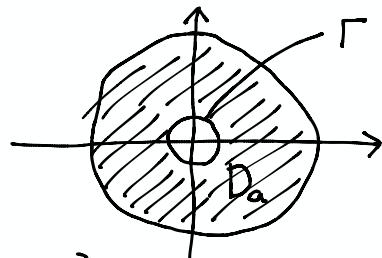
In order to apply Green's, we need a C^2 -function so we need to remove the problematic part around $x=0$.

Take $v(x) \in C_0^\infty$. Let $D_\alpha := \{x \in \mathbb{R}^2 : 0 < |x| < \frac{1}{\alpha}\}$, with α small enough so that $\text{supp } v \subset \{x \in \mathbb{R}^2 : |x| < \frac{1}{\alpha}\}$, i.e. v vanishes outside of $|x| = \frac{1}{\alpha}$.

$$\text{Let } \Gamma := \{x \in \mathbb{R}^2 : |x| = \alpha\}$$

We then get

$$\begin{aligned} -\int_{D_\alpha} \Delta E v &= \left\{ \begin{array}{l} \text{Green's formula} \\ \int_{\Omega} \Delta u v = \int_{\partial\Omega} (\nabla u \cdot n) v - \int_{\Omega} \nabla u \cdot \nabla v \end{array} \right\} = \\ &= - \int_{\partial D_\alpha} (\nabla E \cdot n) v + \int_{D_\alpha} \nabla E \cdot \nabla v = \left\{ \text{Green's} \right\} = \end{aligned}$$



$$= - \int_{\partial D_a} (\nabla E \cdot n) v + \int_{\partial D_a} (\nabla v \cdot n) E - \int_{D_a} E \Delta v = \left\{ \begin{array}{l} v \text{ vanishes} \\ \text{before outer} \\ \text{boundary } |x| = \frac{1}{a} \end{array} \right\} =$$

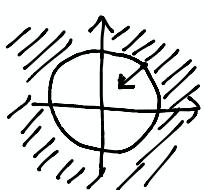
$$= - \int_{\Gamma} (\nabla E \cdot n) v + \int_{\Gamma} (\nabla v \cdot n) E - \int_{D_a} E \Delta v.$$

Exercise 27: $-\Delta E = 0$, $x \neq 0$ with E defined as (*).

$$\Rightarrow - \int_{D_a} \Delta E v = 0$$

$$\Rightarrow \int_{D_a} E \Delta v = \int_{\Gamma} (\nabla v \cdot n) E - \underbrace{\int_{\Gamma} (\nabla E \cdot n) v}_{}$$

What is $\nabla E \cdot n$ on Γ ?



$$|x|=a \quad \nabla E = -\frac{1}{2\pi} \frac{x}{|x|^2}$$

$$|n|=1 \quad \Rightarrow n = \frac{x}{|x|}$$

$$\Rightarrow \nabla E \cdot n = -\frac{1}{2\pi} \cdot \frac{x}{|x|^2} \cdot \frac{-x}{|x|} = \frac{1}{2\pi a}$$

$$\Rightarrow \int_{D_a} E \Delta v = \int_{\Gamma} \frac{1}{2\pi} \ln\left(\frac{1}{|x|}\right) \nabla v \cdot n - \int_{\Gamma} \frac{1}{2\pi a} v =$$

$$= \frac{1}{2\pi} \ln\left(\frac{1}{a}\right) \underbrace{\int_{\Gamma} \nabla v \cdot n}_{v \in C^\infty(\mathbb{R}^2)} - \frac{1}{2\pi a} \underbrace{\int_{\Gamma} v}_{\Gamma \text{ smooth}} = \left\{ \int_{\Gamma} ds = 2\pi a \right\}$$

$$\Rightarrow \int_{\Gamma} \nabla v \cdot n = \nabla v \cdot n \Big|_{\eta}^{\Gamma} \int_{\Gamma} ds$$

some $\eta \in \Gamma$

$$\Rightarrow \exists \xi \in \Gamma:$$

$$\int_{\Gamma} v = v(\xi) \int_{\Gamma} ds$$

$$= \frac{2\pi a}{2\pi} \ln\left(\frac{1}{a}\right) (\nabla v \cdot n)_{\eta} - \frac{2\pi a}{2\pi a} v(\xi) =$$

$$= \underbrace{a \ln(\frac{1}{a})}_{\rightarrow 0, a \rightarrow 0^+} (\nabla v \cdot n)_{\eta} - v(\xi) \rightarrow -v(0), \quad a \rightarrow 0^+$$

bounded

$$\Rightarrow - \int_{\mathbb{R}^2} \Delta E(x) v(x) \stackrel{\text{def}}{=} - \int_{\mathbb{R}^2} E(x) \Delta v(x) = v(0) . \text{ any } v \in C_0^\infty.$$

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40) Consider the Poisson equation with non-homog.

Dirichlet boundary conditions

$$\begin{cases} -\Delta u(x) = f(x), & x \in \Omega \\ u(x) = g(x), & x \in \Gamma = \partial \Omega \end{cases}$$

where $g(x)$ is given boundary data. The variational formulation takes the following form:

find $u \in V_g$, where $V_g := \{v : v = g \text{ on } \Gamma, \int_{\Omega} (|\nabla v|^2 + v^2) dx < \infty\}$
such that

$$(\nabla u, \nabla v) = (f, v) \quad \forall v \in V_0$$

$$\text{where } V_0 := \{v : v = 0 \text{ on } \Gamma, \int_{\Omega} (|\nabla v|^2 + v^2) dx < \infty\}$$

* Show that V_g is not a vector space.

* Prove that the solution of the weak form is unique.

Solution

* Let $g(x) \neq 0$ on Γ . Let $u, v \in V_g$. $u+v|_{\Gamma} = 2g(x)$
 $\Rightarrow u+v \notin V_g$. Hence not a vector space.

* To show uniqueness, assume $u_1, u_2 \in V_g$ such that $(\nabla u_1, \nabla v) = (f, v)$ and $(\nabla u_2, \nabla v) = (f, v) \quad \forall v \in V_0$.

$\Rightarrow w = u_1 - u_2 \in V_0$, satisfies $(\nabla w, \nabla v) = 0 \quad \forall v \in V_0$.

Let $v = w$. Then $\|\nabla w\|^2 = 0$

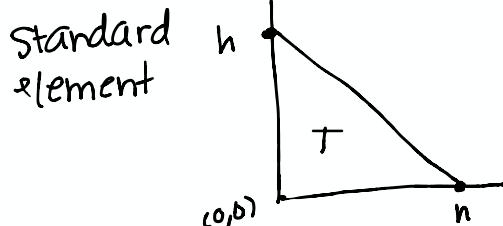
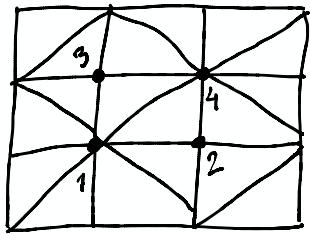
By Poincaré, $0 \leq \|w\|_{L^2}^2 \leq C \|\nabla w\|_{L^2}^2 = 0$, $w \in V_0 = H_0^1$

$\|\cdot\|_{L^2}$ = norm $\Rightarrow w = 0$ a.e. $\Rightarrow u_1 = u_2$ a.e. \therefore

9.12) Formulate the CG(1) method for the BVP

$$\begin{cases} -\Delta u + u = f, & x \in \Omega \subset \mathbb{R}^2 \\ u=0, & x \in \partial\Omega \end{cases}$$

Write down the matrix form of the resulting system of equations using the uniform mesh:



Solution

$$VF: - \int_{\Omega} \Delta u v + \int_{\Omega} u v = \int_{\Omega} f v \quad \forall v \in H_0^1(\Omega)$$

$$\text{Green's} + \int_{\partial\Omega} (\nabla u \cdot n) v = 0, \quad v \in H_0^1$$

$$\int_{\Omega} \nabla u \cdot \nabla v + \int_{\Omega} u v = \int_{\Omega} f v \quad \forall v \in H_0^1$$

FEM: Let $u_h = \sum_{j=1}^4 \xi_j \varphi_j$, φ_j = tent functions with $\varphi_j = 1$ in the point j .

$$\Rightarrow \sum_{j=1}^4 \xi_j \left(\underbrace{\int_T \nabla \varphi_j \cdot \nabla \varphi_i}_{S_{ij}} + \underbrace{\int_T \varphi_j \varphi_i}_{m_{ij}} \right) = \int_T f \varphi_i, \quad i = 1, \dots, 4$$

For the standard element T , we have:

$$\begin{aligned}\phi_1(x,y) &= (h-x-y)/h & \nabla \phi_1 &= (-\frac{1}{h}, -\frac{1}{h}) \\ \phi_2(x,y) &= x/h & \nabla \phi_2 &= (\frac{1}{h}, 0) \\ \phi_3(x,y) &= y/h & \nabla \phi_3 &= (0, \frac{1}{h})\end{aligned}$$

$$\text{area} : h^2/2$$

Find local stiffness matrix, S

$$\int_T \nabla \phi_1 \cdot \nabla \phi_1 = \int_T \frac{2}{h^2} = \frac{h^2}{2} \cdot \frac{2}{h^2} = 1$$

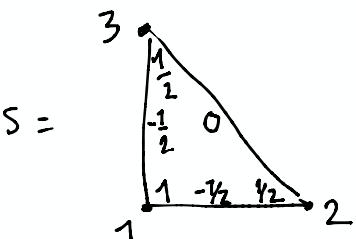
$$\int_T \nabla \phi_1 \cdot \nabla \phi_2 = \int_T \nabla \phi_1 \cdot \nabla \phi_3 = \dots = -\frac{1}{2}$$

$$\int_T \nabla \phi_2 \cdot \nabla \phi_2 = \int_T \nabla \phi_3 \cdot \nabla \phi_3 = \dots = \frac{1}{2}$$

$$\int_T \nabla \phi_2 \cdot \nabla \phi_3 = 0$$

$$S = \begin{bmatrix} 1 & -\frac{1}{2} & -\frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} & 0 \\ -\frac{1}{2} & 0 & \frac{1}{2} \end{bmatrix}$$

when assembling the global stiffness matrix, it may be easier to view S like this:



Find local mass matrix, m :

$$\int_T \phi_1 \phi_1 = \dots = \frac{h^2}{12}$$

$$m = \frac{h^2}{24} \begin{bmatrix} 2 & 1 & 1 \\ 1 & 2 & 1 \\ 1 & 1 & 2 \end{bmatrix}$$

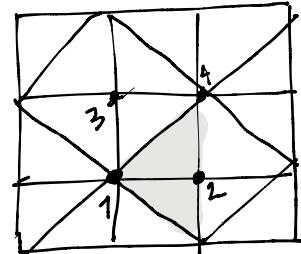
$$\int_T \phi_1 \phi_2 = \int_T \phi_1 \phi_3 = \frac{h^2}{24}$$

$$\int_T \phi_2 \phi_2 = \int_T \phi_3 \phi_3 = \frac{h^2}{12}$$

$$\int_T \phi_2 \phi_3 = \dots = \frac{h^2}{24}$$

$$M = \frac{h^2}{24} \cdot \begin{array}{c} 3 \\ 2 \\ 1 \\ 1 \\ 2 \\ 1 \\ 2 \end{array}$$

Assemble the global matrices:



$$S = \begin{bmatrix} 8 \cdot S_{22} & 2 \cdot S_{12} & 2 \cdot S_{12} & 2 \cdot S_{23} \\ 2 \cdot S_{12} & 4 \cdot S_{11} & 0 & 2 \cdot S_{12} \\ 2 \cdot S_{12} & 0 & 4 \cdot S_{11} & 2 \cdot S_{12} \\ 2 \cdot S_{23} & 2 \cdot S_{12} & 2 \cdot S_{12} & 8 \cdot S_{22} \end{bmatrix} = \begin{bmatrix} 4 & -1 & -1 & 0 \\ -1 & 4 & 0 & -1 \\ -1 & 0 & 4 & -1 \\ 0 & -1 & -1 & 4 \end{bmatrix}$$

$$M = \begin{bmatrix} 8m_{22} & 2 \cdot m_{12} & 2 \cdot m_{12} & 2m_{23} \\ 2 \cdot m_{12} & 4 \cdot m_{11} & 0 & 2m_{12} \\ 2 \cdot m_{12} & 0 & 4 \cdot m_{11} & 2 \cdot m_{12} \\ 2 \cdot m_{23} & 2m_{12} & 2m_{12} & 8m_{22} \end{bmatrix} = \frac{h^2}{24} \begin{bmatrix} 16 & 2 & 2 & 2 \\ 2 & 8 & 0 & 2 \\ 2 & 0 & 8 & 2 \\ 2 & 2 & 2 & 16 \end{bmatrix}$$

Resulting system:

$$(S+M) \psi = b, \quad b = \left[\int_{\Omega} f \varphi_1 \quad \int_{\Omega} f \varphi_2 \quad \int_{\Omega} f \varphi_3 \quad \int_{\Omega} f \varphi_2 \right]^T. \quad \therefore$$

39) For the linear system $M\eta = b$, where M is the mass matrix w/ coeff. $(\varphi_j, \varphi_i)_{i,j=1}^m$, b is load vector (v, φ_i) , prove that M is symmetric, pos. def.

Solution Symmetry obvious.

Positive definite

For $v \in \mathbb{R}^m \setminus \{0\}$:

$$\begin{aligned} v^T M v &= \sum_{i=1}^m \sum_{j=1}^m v_i (\varphi_j, \varphi_i) v_j = \left(\sum_{j=1}^m v_j \varphi_j, \sum_{i=1}^m v_i \varphi_i \right) = \\ &= \|w\|_{L^2}^2 > 0 \quad \text{since } w := \sum_{i=1}^m v_i \varphi_i \neq 0 \text{ since } v \neq 0. \end{aligned}$$

37) Describe a discrete system of equations for a p.w. polynomial approximation for

$$\begin{cases} -\Delta u(x) = f(x), & x \in \Omega \\ u(x) = 0, & x \in \partial\Omega \end{cases}$$

with continuous polynomial basis functions, $\{\varphi_j\}_{j=1}^M$.

Show that the stiffness matrix for this approximation is symmetric and positive definite.

Solution

$$\begin{aligned} V_h := & \{v: \text{p.w. polynomial, continuous, } v=0 \text{ on } \Gamma\} = \\ & = \text{span}\{\varphi_j\}_{j=1}^M \end{aligned}$$

Discrete VF of the problem: Find $u_h \in V_h$ s.t. $(\nabla u_h, \nabla v) = (f, v)$

$\forall v \in V_h$. Let $u_h = \sum_{j=1}^M \xi_j \varphi_j$. Then the problem is equivalent to finding $\xi = (\xi_j)_{j=1}^M \in \mathbb{R}^M$ such that

$$\sum_{j=1}^M \xi_j (\nabla \varphi_j, \nabla \varphi_i) = (f, \varphi_i) \text{ for } i=1, \dots, M$$

$$\begin{aligned} \text{This can be written } A\xi &= b, \quad A = (a_{ij})_{i,j=1}^M = ((\nabla \varphi_j, \nabla \varphi_i))_{i,j=1}^M \\ b &= (b_i)_{i=1}^M = ((f, \varphi_i))_{i=1}^M \end{aligned}$$

A is obviously symmetric. Positive definite? ($v^T A v > 0$ for every $v \in \mathbb{R}^M \setminus \{0\}$.)

$$\text{Let } v \in \mathbb{R}^M \setminus \{0\} \text{ and let } w = \sum_{i=1}^M v_i \varphi_i \in V_h \setminus \{0\}$$

$$\begin{aligned} v^T A v &= \sum_{i=1}^M \sum_{j=1}^M v_i (\nabla \varphi_j, \nabla \varphi_i) v_j = \left(\sum_{j=1}^M v_j \nabla \varphi_j, \sum_{i=1}^M v_i \nabla \varphi_i \right) = \\ &= \left(\nabla \left(\sum_{j=1}^M v_j \varphi_j \right), \nabla \left(\sum_{i=1}^M v_i \varphi_i \right) \right) = (\nabla w, \nabla w) = \|\nabla w\|_{L^2}^2 \geq 0 \end{aligned}$$

$$v^T A v = 0 \iff \nabla w = 0 \iff w \text{ constant} \iff w = 0 \text{ in } \Omega$$

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since $w=0$ on $\partial\Omega$

Thus $v^T A v > 0$ for $v \neq 0$ and A is positive definite.

and continuous.

7.

38) We define the L^2 -projection $P_h v$ of a function $v \in L^2(\Omega)$ into the finite element space by

$$(P_h v, w) = (v, w) \quad \forall w \in V_h.$$

We also define the discrete Laplacian Δ_h by

$$-(\Delta_h w, v) = (\nabla w, \nabla v) \quad \forall v \in V_h.$$

Verify that we may express the finite problem

$$(\nabla u, \nabla v) = (f, v) \quad \forall v \in V_h$$

as finding $u \in V_h$ such that

$$-\Delta_h u = P_h f.$$

Solution

$$-\Delta_h u = P_h f \quad \text{in } V_h \quad (\text{Uniqueness by L-M})$$

$$\Leftrightarrow -(\Delta_h u, v) = (P_h f, v) \quad \forall v \in V_h$$

$$\stackrel{\text{def } \Delta_h}{\Leftrightarrow} (\nabla u, \nabla v) = (P_h f, v) \quad \forall v \in V_h$$

$$\stackrel{\text{def } P_h}{\Leftrightarrow} (\nabla u, \nabla v) = (f, v) \quad \forall v \in V_h \quad \therefore$$