

(R)

• Ritz projection $R_h: H_0^1 \rightarrow V_h^0$

$$a(R_h v - v, v_h) = 0 \quad \forall v_h \in V_h^0$$

Here $a(u, v) = (\nabla u, \nabla v)_{L^2}$ energy i.f.

$V_h^0 \rightarrow$ FE space

$$\|R_h v - v\|_{L^2} \leq C \cdot h^2 \|v\|_{H^2}$$

• Error FE π for heat: $\|u_h(\cdot, t) - u(\cdot, t)\|_{L^2} \leq C \cdot h^2$

Idea: error = error₁ + error₂ $\begin{cases} \text{error}_1 \rightarrow \text{direct using } R_h \\ \text{error}_2 \rightarrow \text{find heat eq. for error}_2 + \text{stability} \end{cases}$

$$(W) \begin{cases} u_{tt} - \Delta u = f & \text{in } \Omega \\ u = 0 & \text{on } \partial\Omega \\ u(\cdot, 0) = u_0, u_t(\cdot, 0) = v_0 & \text{in } \Omega \end{cases}$$

$f=0 \rightarrow$ conservation of energy $\frac{1}{2} \|u_t(\cdot, t)\|_{L^2}^2 + \frac{1}{2} \|\nabla u(\cdot, t)\|_{L^2}^2$

$$(VF) (u_{tt}(\cdot, t), v)_{L^2} + (\nabla u(\cdot, t), \nabla v)_{L^2} = (f(\cdot, t), v)_{L^2} \quad \forall v \in H_0^1 + IC$$

$$(FE) (u_{h,FE}(\cdot, t), v_h)_{L^2} + (\nabla u_h(\cdot, t), \nabla v_h)_{L^2} = (f(\cdot, t), v_h)_{L^2} \quad \forall v_h \in V_h^0 + IC$$

$$V_h^0 = \text{span}(\{\psi_j\}_{j=1}^{n_i})$$

• From the FE prob., as usual, we derive a

system of ODEs $M \dot{u} + A u = F$ + the $\| \cdot \|$ is also L^2

sys. of ODE mechanics to the following observations

$$u_n(x,t) = \sum_{j=1}^{n_i} z_j(t) \varphi_j(x) \quad \text{and take } v_n = \varphi_i.$$

Insert this in (F.E) and get the syst.:

$$M \ddot{z}(t) + S z(t) = F(t) \\ z(0), \dot{z}(0),$$

$S \rightarrow$ stiffness matrix

$M \rightarrow$ mass matrix

$F \rightarrow$ vector with entry $(f(t), \varphi_i)_{L^2}$

$z \rightarrow$ unknown.

- Last step is to use f.ex. C-N to get an approx $z^n \approx z(t_n)$, where $t_n = n \cdot k$, k time step.

$$\hookrightarrow u_n^n(x, t_n) = \sum_{j=1}^{n_i} z_j^n \varphi_j(x) \approx u(x, t_n).$$

3) A priori error estimates for the semi-discrete problem:

Th: Let u, u_h be the exact sol. (VF) of wave equation, resp. to (F-E). Assume u, u_h nice enough.

For $t \geq 0$ of interest, one has the error estimate

$$\|u(\cdot, t) - u_h(\cdot, t)\|_{L^2(\Omega)} \leq C \left(\|\Pi_h u_0 - R_h u_0\|_1 + \|\overset{\pm v_0}{\Pi_h v_0} - R_h v_0\|_{L^2} \right) + C \cdot h^2 \left(\|u(\cdot, t)\|_{H^2} + \int_0^t \|u_{tt}(\cdot, s)\|_{H^2} ds \right),$$

$\leq C \cdot h^2$ since u is nice enough

$\Pi_h u_0 \rightarrow$ Cont. p.w. linear interpolant of u_0

$R_h u_0 \rightarrow$ Ritz projection

$|v|_1 \rightarrow$ semi norm $|v|_1 = \left(\sum_{|\alpha|=1} \|D^\alpha v\|_{L^2}^2 \right)^{1/2}$

$$\left(f: \mathbb{R} \rightarrow \mathbb{R}: |f|_1 = \|f'\|_{L^2} \right)$$

$$f: \mathbb{R}^2 \rightarrow \mathbb{R}: |f|_1 = \|\nabla f\|_{L^2}$$

Proof!

• We start by writing the error $u_h - u$ as

$$u_h - u = (u_h - R_h u) + (R_h u - u) =: \Theta + \mathcal{I}$$

• For the error term $\mathcal{I} = R_h u - u$, we use the following

$$\|S(\cdot, t)\|_{L^2} + h \|S(\cdot, t)\|_1 \leq C \cdot h^2 \|u(\cdot, t)\|_{H^2}$$

$$\|S_t(\cdot, t)\|_{L^2} \leq C \cdot h^2 \|u_t(\cdot, t)\|_{H^2}$$

$$\|S_{tt}(\cdot, t)\|_{L^2} \leq C \cdot h^2 \|u_{tt}(\cdot, t)\|_{H^2} \quad (\text{see end proof})$$

- For the error term $\Theta = u_h - R_h u$, we find an equation that is satisfied by Θ (wave eq.) and use something related to the energy.

As for the heat eq., one shows that Θ satisfies

$$(\Theta_{tt}(\cdot, t), v_h)_{L^2} + (\nabla \Theta(\cdot, t), \nabla v_h)_{L^2} = - (S_{tt}(\cdot, t), v_h)_{L^2} \quad \forall v_h \in V_h^0 \quad \forall t \geq 0.$$

Choose now $v_h = \Theta_t$ and get from the above:

$$\underbrace{(\Theta_{tt}(\cdot, t), \Theta_t(\cdot, t))_{L^2}}_{\text{kinetic energy}} + \underbrace{(\nabla \Theta(\cdot, t), \nabla \Theta_t(\cdot, t))_{L^2}}_{\text{potential energy}} = - (S_{tt}(\cdot, t), \Theta_t(\cdot, t))$$

$$\frac{1}{2} \frac{d}{dt} (\Theta_t(\cdot, t), \Theta_t(\cdot, t))_{L^2}$$

kinetic energy

$$\frac{1}{2} \frac{d}{dt} (\nabla \Theta(\cdot, t), \nabla \Theta(\cdot, t))_{L^2} \quad (\text{see cons. energy})$$

potential energy

That is, we get:

$$\frac{1}{2} \frac{d}{dt} \left(\|\theta_t(\cdot, t)\|_{L^2}^2 + \underbrace{\|\nabla \theta_t(\cdot, t)\|_{L^2}^2}_{\|\theta(\cdot, t)\|_1^2 \text{ (semi-norm)}} \right) = - (S_{tt}(\cdot, t), \theta_t(\cdot, t))$$

Use C-S to get:

$$\frac{1}{2} \frac{d}{dt} \left(\cdot \right) \leq \|S_{tt}(\cdot, t)\|_{L^2} \cdot \|\theta_t(\cdot, t)\|_{L^2}$$

Integrate in time $\int_0^t \dots ds$:

$$\begin{aligned} \frac{1}{2} \left(\|\theta_t(\cdot, t)\|_{L^2}^2 + \|\theta(\cdot, t)\|_1^2 - \|\theta_t(\cdot, 0)\|_{L^2}^2 - \|\theta(\cdot, 0)\|_1^2 \right) &\leq \\ &\leq \int_0^t \|S_{tt}(\cdot, s)\|_{L^2} \cdot \|\theta_t(\cdot, s)\|_{L^2} ds \end{aligned}$$

Next, we get:

$$\begin{aligned} \|\theta_t(\cdot, t)\|_{L^2}^2 + \|\theta(\cdot, t)\|_1^2 &\leq \|\theta_t(\cdot, 0)\|_{L^2}^2 + \|\theta(\cdot, 0)\|_1^2 + \\ &+ 2 \int_0^t \|S_{tt}(\cdot, s)\|_{L^2} \underbrace{\|\theta_t(\cdot, s)\|_{L^2}}_{\leq \max_{0 \leq s \leq t} \|\theta_t(\cdot, s)\|_{L^2}} ds \end{aligned}$$

On the equations

$$\begin{aligned} \|\vartheta_t(\cdot, t)\|_{L^2}^2 + \underbrace{|\vartheta(\cdot, t)|_1^2}_{\geq 0} &\leq \|\vartheta_t(\cdot, 0)\|_{L^2}^2 + |\vartheta(\cdot, 0)|_1^2 + \\ &+ 2 \int_0^t \|\mathcal{S}_{t-s}(\cdot, s)\|_{L^2} ds \cdot \max_{0 \leq s \leq t} \|\vartheta_t(\cdot, s)\|_{L^2} \\ &\leq \|\vartheta_t(\cdot, 0)\|_{L^2}^2 + |\vartheta(\cdot, 0)|_1^2 + 2 \left(\int_0^T \|\mathcal{S}_{t-s}(\cdot, s)\|_{L^2} ds \right)^2 + \\ &+ \frac{1}{2} \left(\max_{0 \leq s \leq T} \|\vartheta_t(\cdot, s)\|_{L^2} \right)^2 \quad (*) \end{aligned}$$

$2xy \leq 2x^2 + \frac{1}{2}y^2$

Observe that the above inequality is valid for all time of interest $t > 0$, hence we get

$$\underbrace{\left(1 - \frac{1}{2}\right)}_{\frac{1}{2}} \left(\max_{s \in [0, T]} \|\vartheta_t(\cdot, s)\|_{L^2} \right)^2 \leq \|\vartheta_t(\cdot, 0)\|_{L^2}^2 + |\vartheta(\cdot, 0)|_1^2 + 2 \left(\int_0^T \|\mathcal{S}_{t-s}(\cdot, s)\|_{L^2} ds \right)^2$$

We insert the above estimate into (*) and

finally obtain:

$$\|\vartheta_t(\cdot, t)\|_{L^2}^2 + |\vartheta(\cdot, t)|_1^2 \leq 2 \|\vartheta_t(\cdot, 0)\|_{L^2}^2 +$$

$$+ 2|\theta(\cdot, 0)|_1^2 + 4 \left(\int_0^T \|S_{t,t}(\cdot; s)\|_{L^2} ds \right)^2 \quad (**)$$

The above is valid for $t \in (0, T]$ and in particular for $t = T$, where T arbitrary.

• Last step: we put everything together:

$$\|u_{\eta}(\cdot, t) - u(\cdot, t)\|_{L^2} \stackrel{\Delta}{\leq} \|\theta(\cdot, t)\|_{L^2} + \|S(\cdot, t)\|_{L^2} \leq$$

↑
Def of θ, S

Poincaré (**)

$$\leq |\theta(\cdot, t)|_1 + \|S(\cdot, t)\|_{L^2} \leq$$

↑
 $|v|_1 = \|\nabla v\|_{L^2}$

$$\leq C \cdot \|\theta_{t=1}(\cdot, 0)\|_{L^2} + C \cdot |\theta(\cdot, 0)|_1 +$$

$$+ C \cdot \int_0^T \|S_{t,t}(\cdot; s)\| ds + \|S(\cdot, t)\|_{L^2} \leq$$

$$\leq C \cdot \|u_{\eta,t}(\cdot, 0) - R_{\eta} u_t(\cdot, 0)\|_{L^2} + C \cdot |u_t(\cdot, 0) - R_{\eta} u_t(\cdot, 0)|_1 +$$

↑
Def of $\theta = u_{\eta} - R_{\eta} u$, estimates for $S, S_{t,t}$ seen in beginning

$$+ C \cdot h^2 \int_0^1 \|u_{tt}(\cdot, s)\|_{H^2} ds + C \cdot h^2 \|u(\cdot, t)\|_{H^2}$$

Def u_h and u

$$\leq C \cdot \|\pi_h v_0 - R_h v_0\|_{L^2} + C \cdot \|\pi_h u_0 - R_h u_0\|_1 +$$

$$+ C \cdot h^2 \int_0^T \|u_{tt}(\cdot, s)\|_{H^2} ds + C \cdot h^2 \|u(\cdot, t)\|_{H^2}.$$

... out



Chapter XIII: The finite element

Goal: Study the concept of FE

1) Formal definition of a FE:

We begin by giving the def. of FE:

Def. (Ciarlet 1978) A finite element consists of the triplet (K, P, Σ) , where

- $K \subset \mathbb{R}^d$ is a polygon

- P is a space of polynomials on K ($\dim(P) = n$)
- Σ_1 is a unisolvent set of linear functionals on P : That is $\Sigma_1 = \{L_1, L_2, \dots, L_n\}$ where $\dim(P) = n$ and $L_j: P \rightarrow \mathbb{R}$,

Rem! unisolvent means, more or less, that one can find n linearly independent polynomials $p_i \in P$ s.t. $L_j(p_i) = \delta_{ij} = \begin{cases} 1 & \text{if } i=j \\ 0 & \text{else} \end{cases}$

Ex! • Each polygon comes from a mesh/triangulation of Ω . Mesh $T_h = \{K\}$.
 K could be

1d  (interval)

2d  or  (quadrilaterals)

3d  (bricks)

etc

element domain

• P could be $P^{(1)}(K) \rightarrow$ polynomials of degree ≤ 1 defined on K

$P^{(2)}(K) \rightarrow \dots$ degree ≤ 2

Space of shape functions

- Σ_1 : This gives a way to uniquely specify a basis / shape fct on each polygon K as well as the behaviour of these functions between adjacent polygons.
→ set of nodal values

