

(P) • Error estimate for FEM for wave eq.

• Def: Finite element (K, P, Σ)

$K \rightarrow$ element domain (think Δ)

$P \rightarrow$ polyn. sp. / sp. of shape fct. (think $P^{(n)}(K)$)

$\Sigma = \{L_1, \dots, L_n\}$, $n = \dim(P)$, $L_j: P \rightarrow \mathbb{R}$ unisolvent
 $\exists p_i \in P$ s.t. $\{p_i\}_{i=1}^n$ indep. and $L_j(p_i) = \delta_{ij}$
(think set of nodal values)

Ex: 1d Lagrange $P^{(e)}$ element:

Let $e > 0$ integer, $a, b \in \mathbb{R}$, $a < b$, and $e+1$ distinct points $a = x_0 < x_1 < x_2 < \dots < x_e = b$.

For K , we let $K = [a, b]$.

For P , we let $P = P^{(e)}(K) = \{ \text{set of polyn of degree } \leq e \text{ defined on } K \}$

For Σ , we let $\Sigma = \{L_0, L_1, \dots, L_e\}$ where $L_j: P \rightarrow \mathbb{R}$ are defined by $L_j(f) = f(x_j) \forall f \in P, j = 0, 1, \dots, e$.

We now need to find polyn. $\lambda_i, i = 0, \dots, e$, s.t.

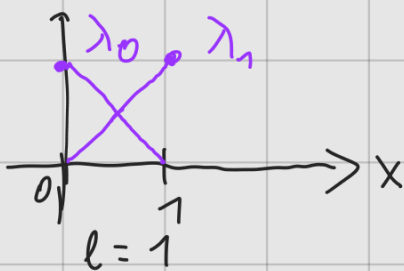
$L_j(\lambda_i) = \delta_{ij}$ that is, by def of L_j ,

$$\lambda_i(x_j) = \delta_{ij} = \begin{cases} 1 & \text{if } i=j \\ 0 & \text{else} \end{cases} \text{ for } i, j = 0, \dots, l.$$

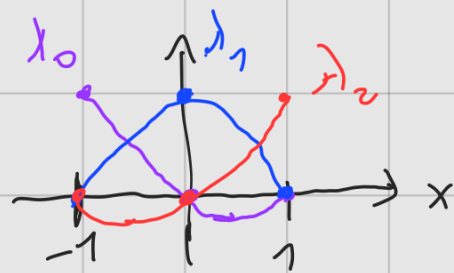
These are exactly Lagrange polynomials

$$\lambda_i(x) = \prod_{\substack{j=0 \\ j \neq i}}^l \frac{x - x_j}{x_i - x_j}$$

seen longtime ago.



but functions
seen before



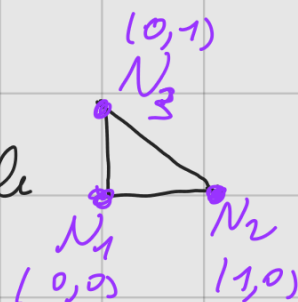
$l=2$

see 6.1(2) in Ass. 1.

↳ The polyn. $\lambda_i(x)$ are called shape functions and build a nodal basis of $P = P^{(l)}(K)$.

Ex: 2d linear Lagrange element:

$K \rightarrow$ take the reference triangle



$P \rightarrow P^{(1)}(K) = \{ \text{set of poly. of degree } \leq 1 \text{ defined} \}$

on K

$\Sigma \rightarrow \Sigma = \{L_1, L_2, L_3\}$ defined by $L_j(f) = f(N_j)$

for $f \in P$, $j = 1, 2, 3$ (N_j are nodes of K)

let us now find shape functions using the conditions:

$$S_i(x, y) = a_i + b_i x + c_i y \quad \text{for } i = 1, 2, 3$$

($S_i \in P$)

$$L_j(S_i) = \delta_{ij} = \begin{cases} 1 & i=j \\ 0 & \text{else} \end{cases} \quad (\text{unisolvent})$$

The above gives conditions in order to find a unique nodal basis which is given by

$$S_1(x, y) = 1 - x - y$$

$$S_2(x, y) = x$$

$$S_3(x, y) = y$$

$\hookrightarrow$ These are the shape fct seen in chapter IX

One can do much more than the above.

for instance:

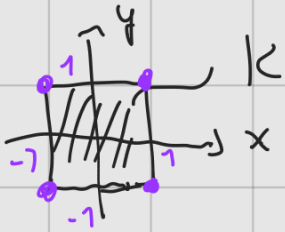
- 2d quadratic Lagrange element, one would take



6 nodes and the shape fun. are of form $S_i(x,y) = a_i + b_i x + c_i y + d_i xy + e_i x^2 + g_i y^2$

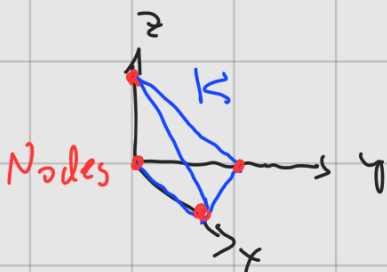
$$S_1 = 1 - 3x - 3y + 2x^2 + 4xy + 2y^2, \quad S_2 = 2x^2 - x, \quad S_3 = 2y^2 - y, \\ S_4 = 4xy, \quad S_5 = 4y - 4xy - 4y^2, \quad S_6 = 4x - 4x^2 - 4xy$$

- For 2d bilinear quadrilateral element, one takes



The shape fun. will have the form $S(x,y) = (a + bx) \cdot (c + dy)$

- For 3d linear Lagrange element, the element K is the tetrahedron;

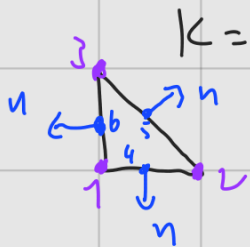


Rem! • One can use other polynomials than Lagrange polyn.

Ex1 Hermite polynomials

(enforce C^1 continuity at the interface, instead of C^0 continuity for Lagrange)

Ex1 Morley element / Morley-Wang-Xu / MWX elements



$K = \text{ref. triangle}$

$$L_i(f) = f(\text{node } i) \quad \text{for nodes } 1, 2, 3$$

$$L_{i+3}(f) = n \cdot \nabla f(\text{node } i) \quad \text{for nodes } 4, 5, 6$$

Good for approximation in H^m in $\mathbb{R}^n$.

Used in solid mechanics (bridge)

2) Higher order FE:

Recall! For an integer $\ell \geq 1$, and a triangle $K \subset \mathbb{R}^2$, one recalls

$$\mathcal{P}^{(\ell)}(K) = \left\{ V: K \rightarrow \mathbb{R} : V(x, y) = \sum_{0 \leq i+j \leq \ell} c_{ij} x^i y^j \text{ for } (x, y) \in K, c_{ij} \in \mathbb{R} \right\}$$

Ex1 $\ell=2$: $\mathcal{P}^{(2)}(K) = \left\{ V: K \rightarrow \mathbb{R} : V(x, y) = a_0 + a_1 x + a_2 y + a_3 xy + a_4 x^2 + a_5 y^2 \right\}$

A polynomial $V \in \mathcal{P}^{(\ell)}(K)$ is determined by

the values at nodes



Shape fct :

When considering a FEM for Poisson's eq.,
one works with the space

$$V_h^0 = \{v \in C^0(\bar{\Omega}) : v|_K \in \mathcal{P}^{(e)}(K) \forall K \in \mathcal{T}_h \text{ and } v|_{\partial\Omega} = 0\}$$

One then obtains error estimates of the form

Th: Let $\Omega \subset \mathbb{R}^2$ convex polygon. Let u be sol. Poisson's eq

$$\begin{cases} -\Delta u = f & \text{in } \Omega \\ u = 0 & \text{on } \partial\Omega \end{cases}$$

Let $u_h \in V_h^0$ the corresponding FE approximation.

Assume that $u \in H^{e+1}(\Omega)$, then the error of FEh reads

$$\|u_h - u\|_{H^1(\Omega)} \leq C h^{\boxed{e}} |u|_{H^{e+1}(\Omega)}$$

(Semi-norm)

3) Variational forms :

Consider a variational problem

(VF) Find $u \in U$ s.t. $a(u, v) = \ell(v) \quad \forall v \in V$.

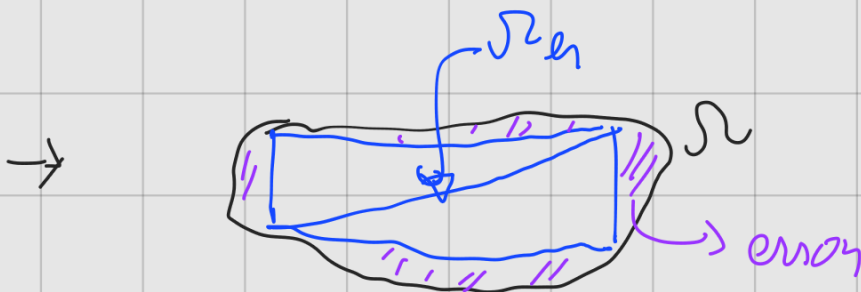
In reality, one must work with the prob

(FE) Find $u_h \in U_h$ s.t. $a_h(u_h, v_h) = \ell_h(v_h) \quad \forall v_h \in V_h$,

Where the index h denotes approximation errors, for instance:

→ From numerical integration, what is

$$\int_K f(x, y) dx dy \approx \frac{|K|}{3} f(1/2, 1/2) \text{ or any other quadrature formula.}$$



error in triangulation.

→ etc.

|| Such errors are called variational crimes

→ such errors are called variational errors

(G. Strang 1972)

As a consequence, error estimates for FEM are much more involved!

Ex! $a(u, v) = \ell(v)$

$a(u, v) = \ell_h(v)$ ← error only in $\ell(\cdot)$

→ of order p

For a FEM for Poisson's eq., one gets

$$\|u - u_h\|_{H^1(\Omega)} \leq C \cdot h^p \|u\|_{H^{p+1}(\Omega)} + \underbrace{C \cdot h^p}_{\approx h^p + h^2(\omega)^2 + \dots} \sup_{w \in V_h^0} \frac{|\ell(w) - \ell_h(w)|}{\|w\|_{H^1(\Omega)}}$$

Want this term to be of the size h^p

(linear element, $p=1$, h)

Chapter XIV: Finite difference approximation

Goal: Present finite difference (FD) for Poisson's eq. in 2d.

Recall:

Forward difference $y'(x) \approx \frac{y(x+h) - y(x)}{h}$

Backward difference: $y'(x) \approx \frac{y(x) - y(x-h)}{h}$

1) FD for Poisson's equation in 2d:

Want to compute numerical approximation of Poisson's eq:

$$\begin{cases} \Delta u = f & \text{in } \Omega \\ u = g & \text{on } \partial\Omega, \end{cases}$$

where $\Omega = [0,1] \times [0,1]$ unit square,

$f = f(x,y)$, $g = g(x,y)$ are given, $u = u(x,y) = ??$

Idea: Using FD to approximate Δu

Recall: $\Delta u(x,y) = u_{xx}(x,y) + u_{yy}(x,y)$

One has:

Forward difference

Backward difference

$$\begin{aligned}
 u_{xx}(x,y) &\equiv \frac{\partial}{\partial x} (u_x(x,y)) \approx \frac{u_x(x+h,y) - u_x(x,y)}{h} \approx^{\text{diff.}} \\
 &\approx \frac{\frac{u(x+h,y) - u(x,y)}{h} - \frac{u(x,y) - u(x-h,y)}{h}}{h}
 \end{aligned}$$

