Lecture Computability (DIT313, DAT415)

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- ► Rice's theorem.
- Turing machines.

Rice's theorem

A variant of Rice's theorem

Assume that $P \in CExp \rightarrow Bool$ satisfies the following properties:

► *P* is non-trivial:

There are expressions e_{true} , $e_{false} \in CExp$ satisfying $P e_{true} = true$ and $P e_{false} = false$.

► *P* respects pointwise semantic equality:

$$\forall \ e_1, e_2 \in CExp.$$
if $\forall \ e \in CExp. \llbracket e_1 \ e \rrbracket = \llbracket e_2 \ e \rrbracket$ then $P \ e_1 = P \ e_2$

Then *P* is χ -undecidable.

The halting problem reduces to *P*:

$$\begin{array}{l} halts = \lambda \, e. \, \mathbf{case} \ P^{\, \lceil} \, \lambda_{\, _}. \, \mathbf{rec} \ x = x^{\, \urcorner} \, \mathbf{of} \\ \{ \mathsf{False}() \rightarrow \\ P^{\, \lceil} \, \lambda \, x. \, (\lambda_{\, _}. \, e_{\mathsf{true}} \ x) \ (eval_{\, _} \, code \ e_{\, _})^{\, \urcorner} \\ ; \, \mathsf{True}() \rightarrow \\ not \ (P^{\, \ulcorner} \, \lambda \, x. \, (\lambda_{\, _}. \, e_{\mathsf{false}} \ x) \ (eval_{\, _} \, code \ e_{\, _})^{\, \urcorner}) \\ \} \end{array}$$

Which of the following problems are χ -decidable?

Is e ∈ CExp an implementation of the successor function for natural numbers?
 Is e ∈ CExp syntactically equal to λ n. Suc(n)?

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Is $e \in CExp$ an implementation of the successor function for natural numbers?

This problem is not χ -decidable.

Use Rice's theorem:

▶
$$P e = \mathbf{if} \forall n \in \mathbb{N}$$
. $\llbracket e \ulcorner n \urcorner \rrbracket = \ulcorner \mathsf{suc} n \urcorner$
then true else false.

- ► *P* is non-trivial:
 - $P(\lambda n. \operatorname{Suc}(n)) = \operatorname{true}.$
 - P(Zero()) = false.

► *P* respects pointwise semantic equality:

$$\begin{array}{l} (\forall e \in \textit{CExp.} \llbracket e_1 \ e \rrbracket = \llbracket e_2 \ e \rrbracket) \Rightarrow \\ (\forall n \in \mathbb{N}. \llbracket e_1 \ \ulcorner n \ \urcorner \rrbracket = \llbracket e_2 \ \ulcorner n \ \urcorner \rrbracket) \Rightarrow \\ P \ e_1 = P \ e_2 \end{array}$$

Turing machines

- A tape that extends arbitrarily far to the right.
- The tape is divided into squares.
- The squares can contain symbols, chosen from a finite alphabet.
- ► A read/write head, positioned over one square.
- The head can move from one square to an adjacent one.
- Rules that explain what the head does.



- A finite set of states.
- When the head reads a symbol (blank squares correspond to a special symbol):
 - Check if the current state contains a matching rule, with:
 - A symbol to write.
 - A direction to move in.
 - A state to switch to.
 - ► If not, halt.

- Turing motivated his design partly by reference to what a human computer does.
- Please read his text.

Abstract

syntax

A Turing machine (one variant) is specified by giving the following information:

- ► S: A finite set of states.
- $s_0 \in S$: An initial state.
- Σ: The input alphabet,
 a finite set of symbols with ⊔ ∉ Σ.
- Γ: The tape alphabet,
 a finite set of symbols with Σ ∪ { ⊔ } ⊆ Γ.
- $\delta \in S \times \Gamma \rightarrow S \times \Gamma \times \{L, R\}$: The transition "function".

$\begin{array}{lll} S \text{ is a finite set} & s_0 \in S \\ \Sigma \text{ is a finite set} & {\scriptstyle {\scriptstyle \square}} \notin \Sigma \\ \Gamma \text{ is a finite set} & \Sigma \cup \{{\scriptstyle {\scriptstyle \square}}\} \subseteq \Gamma \\ \delta \in S \times \Gamma \rightharpoonup S \times \Gamma \times \{\mathsf{L},\mathsf{R}\} \end{array}$

 $(S, s_0, \Sigma, \Gamma, \delta) \in \mathit{TM}$

Operational semantics

 Representation of the tape and the head's position:

 $Tape = List \ \Gamma \times List \ \Gamma$

• Here (ls, rs) stands for

reverse ls + rs

followed by an infinite sequence of blanks ($_{\Box}$).

$([2,1],[3,4,\sqcup,\sqcup])$ stands for:



The head is located over the first symbol in rs (or a blank, if rs is empty):

$$\begin{array}{l} head_{T} \in \ Tape \rightarrow \Gamma \\ head_{T} \ (ls, rs) = head \ rs \end{array}$$

 $\begin{array}{l} head \in List \ \Gamma \to \Gamma \\ head \ [\] \qquad = \llcorner \\ head \ (x :: xs) = x \end{array}$

Writing

Writing to the tape:

$$write \in \Gamma \to Tape \to Tape$$

write $x (ls, rs) = (ls, x :: tail rs)$

The "tail" of a sequence:

$$\begin{aligned} tail \in List \ \Gamma \to List \ \Gamma \\ tail \ [\] &= [\] \\ tail \ (r :: rs) = rs \end{aligned}$$



Moving the head:

$$\begin{array}{l} move \in \{\mathsf{L},\mathsf{R}\} \rightarrow Tape \rightarrow Tape \\ move \; \mathsf{R} \; (ls,rs) = (head \; rs :: \; ls, tail \; rs) \\ move \; \mathsf{L} \; ([],rs) = ([] \; , rs) \\ move \; \mathsf{L} \; (ls,rs) = (tail \; ls \; , head \; ls :: \; rs) \end{array}$$

Actions

Actions describe what the head will do:

$$Action = \Gamma \times \{\mathsf{L},\mathsf{R}\}$$

Note:

$$\delta \in S \times \Gamma \rightharpoonup S \times Action$$

First write, then move:

$$act \in Action \rightarrow Tape \rightarrow Tape$$

 $act (x, d) t = move d (write x t)$

Which of the following equalities are valid?

1. act (0, L) (act (1, L) ([], [])) = ([], [0, 1])2. act (0, L) (act (1, L) ([], [])) = ([0, 1], [])3. act (0, L) (act (1, L) ([], [])) = ([1, 0], [])4. act (0, R) (act (1, R) ([], [])) = ([], [0, 1])5. act (0, R) (act (1, R) ([], [])) = ([0, 1], [])6. act (0, R) (act (1, R) ([], [])) = ([1, 0], [])

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\begin{array}{l} act \ (0, \mathsf{L}) \ (act \ (1, \mathsf{L}) \ ([], [])) &= \\ act \ (0, \mathsf{L}) \ (move \ \mathsf{L} \ (write \ 1 \ ([], []))) &= \\ act \ (0, \mathsf{L}) \ (move \ \mathsf{L} \ ([], [1])) &= \\ act \ (0, \mathsf{L}) \ ([], [1]) &= \\ move \ \mathsf{L} \ (write \ 0 \ ([], [1])) &= \\ move \ \mathsf{L} \ (write \ 0 \ ([], [1])) &= \\ ([], [0]) &= \\ \end{array}
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\begin{array}{l} act \ (0,\mathsf{R}) \ (act \ (1,\mathsf{R}) \ ([],[])) &= \\ act \ (0,\mathsf{R}) \ (move \ \mathsf{R} \ (write \ 1 \ ([],[]))) &= \\ act \ (0,\mathsf{R}) \ (move \ \mathsf{R} \ ([],[1])) &= \\ act \ (0,\mathsf{R}) \ ([1],[]) &= \\ move \ \mathsf{R} \ (write \ 0 \ ([1],[])) &= \\ move \ \mathsf{R} \ (write \ 0 \ ([1],[])) &= \\ ([0,1],[]) &= \\ \end{array}
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A configuration consists of a state and a tape:

 $Configuration = State \times Tape$

The small-step operational semantics relates configurations:

$$\frac{\delta(s, head_T t) = (s', a)}{(s, t) \longrightarrow (s', act \ a \ t)}$$

Zero or more small steps:

$$\frac{c_1 \longrightarrow c_2 \quad c_2 \longrightarrow^{\star} c_3}{c_1 \longrightarrow^{\star} c_3}$$

The machine halts if it ends up in a configuration c for which there is no c' such that $c \longrightarrow c'$.

The machine's result

- The machine is started in state s_0 .
- The head is initially over the left-most square.
- The tape's contents is initially a string of characters from the input alphabet Σ.
- If the machine halts, then the result consists of the contents of the tape, up to the last non-blank symbol.
- (In 2016/2017 I required the machine to halt with the head over the left-most square.)

A relation between $List \Sigma$ and $List \Gamma$:

$$\frac{(s_0, [], xs) \longrightarrow^{\star} (s, t) \quad \nexists c. (s, t) \longrightarrow c}{xs \Downarrow remove \ (list \ t)}$$

Constructing the result

The function *list* converts the representation of the tape to a list, and *remove* removes all trailing blanks:

$$\begin{split} list \in Tape \to List \ \Gamma \\ list \ (ls, rs) &= reverse \ ls + rs \\ remove \in List \ \Gamma \to List \ \Gamma \\ remove \ [] &= [] \\ remove \ (x :: xs) &= cons' \ x \ (remove \ xs) \\ cons' \in \Gamma \to List \ \Gamma \to List \ \Gamma \\ cons' \ \sqcup \ [] &= [] \\ cons' \ x \ xs &= x :: xs \end{split}$$

Quiz

Which properties does \Downarrow satisfy?

1. Is it deterministic (for every Turing machine)?

 $\begin{array}{l} \forall \ tm \in \ TM. \\ \forall \ xs \in \ List \ \Sigma_{tm}. \ \forall \ ys, zs \in \ List \ \Gamma_{tm}. \\ xs \Downarrow_{tm} \ ys \land xs \Downarrow_{tm} \ zs \Rightarrow ys = zs \end{array}$

2. Is it total (for every Turing machine)?

 $\forall tm \in TM. \ \forall xs \in List \Sigma_{tm}. \\ \exists ys \in List \Gamma_{tm}. \ xs \Downarrow_{tm} \ ys$

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The semantics as a partial function:

$$\llbracket - \rrbracket \in \forall tm \in TM. \ List \ \Sigma_{tm} \rightharpoonup List \ \Gamma_{tm} \\ \llbracket tm \rrbracket \ xs = ys \ \text{ if } xs \Downarrow_{tm} ys$$

Two examples

- ▶ Input alphabet: {0,1}.
- Tape alphabet: $\{0, 1, \sqcup\}$.
- States: $\{s_0\}$.
- Initial state: s_0 .

Transition function

$$\begin{array}{l} \delta \; (s_0,0) = (s_0,1,\mathsf{R}) \\ \delta \; (s_0,1) = (s_0,0,\mathsf{R}) \end{array}$$

$$(0, 1, \mathsf{R})$$

 s_0 $(1, 0, \mathsf{R})$



What is the result of running this TM with 0101 as the input string?

- 1. No result
- 2. 0000
- **3**. 1111
- **4**. 0101
- **5**. 1010
- **6**. 0101⊔
- **7**. 1010∟

Respond at https://pingo.coactum.de/921051.



One way to make sure that the head ends up over the left-most square:

- ▶ Input alphabet: {0,1}.
- Tape alphabet: $\{0, 1, \underline{0}, \underline{1}, \sqcup\}$.
- States: $\{s_0, s_1, s_2, s_3\}$.
- ▶ Initial state: s₀.

Transition function



Accepting states

Turing machines with *accepting states*:

 $\begin{array}{lll} S \text{ is a finite set} & s_0 \in S & A \subseteq S \\ & \Sigma \text{ is a finite set} & {}_{\square} \notin \Sigma \\ & \Gamma \text{ is a finite set} & \Sigma \cup \{ {}_{\square} \} \subseteq \Gamma \\ & \delta \in S \times \Gamma \rightharpoonup S \times \Gamma \times \{ \mathsf{L}, \mathsf{R} \} \end{array}$

 $(S, s_0, A, \Sigma, \Gamma, \delta) \in \mathit{TM}$

A relation on $List \Sigma$:

$$\underbrace{ \begin{array}{c} (s_0, [\,], xs) \longrightarrow^{\star} (s, t) & \nexists c. \, (s, t) \longrightarrow c \\ \\ \hline \\ \hline \\ \hline \\ \hline \\ \hline \\ A \, ccept \, xs \end{array} }$$

A relation on $List \Sigma$:

Note that if the TM fails to halt, then the string is neither accepted nor rejected.

- ▶ Input alphabet: {1}.
- Tape alphabet: $\{1, \sqcup\}$.
- States: $\{s_0, s_1\}$.
- ▶ Initial state: s₀.
- ► Accepting states: { *s*₀ }.

Transition function



Transition function



 Quiz: Which strings are accepted by this Turing machine? (Respond at https://pingo.coactum.de/921051.)

Variants

Equivalent (in some sense) variants:

- Possibility to stay put.
- A tape without a left end.
- Multiple tapes.
- Only two symbols, other than the blank one.

Representing inductively defined sets

One method:

$$\begin{bmatrix} - \\ - \end{bmatrix} \in \mathbb{N} \to List \{1\}$$
$$\begin{bmatrix} \\ zero \\ - \end{bmatrix} = \begin{bmatrix} \\ \end{bmatrix}$$
$$\begin{bmatrix} \\ suc \\ n \end{bmatrix} = 1 :: \begin{bmatrix} n \\ - \end{bmatrix}$$

Another method:

This method is used below.

Lists

Assume that members of A can be represented using a function $\lceil _ \rceil \in A \rightarrow List \Xi$ that is *splittable*:

- It is injective.
- There is a function

 $split \in List \Xi \rightarrow List \Xi \times List \Xi$

such that, for any $x \in A$, $xs \in List \Xi$,

$$split (\ulcorner x \urcorner + xs) = (\ulcorner x \urcorner, xs).$$

Lists

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such that, for any $x \in A$, $xs \in List \Xi$,

$$split (\ulcorner x \urcorner + xs) = (\ulcorner x \urcorner, xs).$$

Note that *split* can only be defined for one of the presented methods for representing natural numbers.

Representation of *List A*:

$$\begin{bmatrix} - \\ - \\ - \end{bmatrix} \in List \ A \to List \ (\Xi \cup \{0, 1\})$$
$$\begin{bmatrix} - \\ - \\ - \\ - \end{bmatrix} = 0 :: \begin{bmatrix} - \\ - \\ - \\ - \end{bmatrix}$$
$$\begin{bmatrix} - \\ - \\ - \\ - \\ - \end{bmatrix} : x : xs = 1 :: \begin{bmatrix} - \\ - \\ - \\ - \\ - \end{bmatrix}$$

This function is splittable.



Which list of natural numbers does 11110101110100 stand for?

- 1. None
- **2**. [3, 0, 2]
- **3**. [3, 0, 2, 0]
- **4**. [3, 2, 0]
- 5. [4, 1, 3, 1]
- **6**. [4, 1, 3, 1, 0]

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Assume that members of A and B can be represented using functions $\lceil _ \rceil^A \in A \rightarrow List \Xi$ and $\lceil _ \rceil^B \in B \rightarrow List \Xi$ that are splittable.

Representation of $A \times B$:

$$\begin{bmatrix} - \\ - \end{bmatrix} \in A \times B \to List \Xi$$
$$\begin{bmatrix} (x, y) \\ - \end{bmatrix} = \begin{bmatrix} x \\ x^A \\ + \end{bmatrix} \begin{bmatrix} y \\ y^B \end{bmatrix}$$

This function is also splittable.

Turingcomputability

Turing-computable functions

Assume that we have methods for representing members of the sets A and B as elements of $List \Sigma$, where Σ is a finite set.

A partial function $f \in A \rightarrow B$ is *Turing-computable* (with respect to these methods) if there is a Turing machine tm such that:

•
$$\Sigma_{tm} = \Sigma.$$

$$\blacktriangleright \quad \forall a \in A. \llbracket tm \rrbracket \ulcorner a \urcorner = \ulcorner f a \urcorner.$$



A language over an alphabet Σ is a subset of List Σ.

Turing-decidable

A language L over Σ is *Turing-decidable* if there is a Turing machine tm such that:

•
$$\Sigma_{tm} = \Sigma$$
.

- $\forall xs \in List \Sigma$. if $xs \in L$ then $Accept_{tm} xs$.
- ▶ $\forall xs \in List \Sigma$. if $xs \notin L$ then $Reject_{tm} xs$.

Turing-recognisable

A language L over Σ is *Turing-recognisable* if there is a Turing machine tm such that:

•
$$\Sigma_{tm} = \Sigma$$
.

• $\forall xs \in List \Sigma$. $xs \in L$ iff $Accept_{tm} xs$.



- Rice's theorem.
- Turing machines:
 - Abstract syntax.
 - Operational semantics.
 - Variants.
 - Representing inductively defined sets.
 - ► Turing-computability.