

MVE550 2023 Lecture 9

Markov Chain Monte Carlo

Dobrow Sections 5.1 - 5.3

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Is an approximate sample good enough?

- ▶ Strong law of large numbers for samples: If $Y_1, Y_2, \dots, Y_m$ and Y are i.i.d. random variables from a distribution with finite mean, and if $E[r(Y)]$ exists, then, with probability 1,

$$\lim_{m \rightarrow \infty} \frac{r(Y_1) + r(Y_2) + \dots + r(Y_m)}{m} = E[r(Y)]$$

- ▶ Strong law of large numbers for Markov chains: If $X_0, X_1, \dots$, is an ergodic Markov chain with stationary distribution π , and if $E[r(X)]$ exists, then, with probability 1,

$$\lim_{m \rightarrow \infty} \frac{r(X_1) + r(X_2) + \dots + r(X_m)}{m} = E[r(X)]$$

where X has the stationary distribution π .

- ▶ NOTE: When using this theorem in practice, one might improve accuracy by throwing away the first sequence $X_1, \dots, X_s$ for $s < m$ before computing the average. The first sequence is then called the *burn-in*.

Toy example

- Consider the Markov chain $X_0, X_1, \dots$ with states $\{0, 1, 2\}$ and with

$$P = \begin{bmatrix} 0.99 & 0.01 & 0 \\ 0 & 0.9 & 0.1 \\ 0.2 & 0 & 0.8 \end{bmatrix}.$$

Using theory from Chapter 3 we get that the limiting distribution is $\nu = (20/23, 2/23, 1/23)$.

- Consider the function $r(x) = x^5$. If X is a random variable with the limiting distribution,

$$E(r(X)) = 0^5 \cdot \frac{20}{23} + 1^5 \cdot \frac{2}{23} + 2^5 \cdot \frac{1}{23} = \frac{34}{23} = 1.4783$$

- If $Y_1, \dots, Y_n$ are all i.i.d. variables with the limiting distribution, we can check numerically (see R code) that

$$\lim_{n \rightarrow \infty} \frac{r(Y_1) + \dots + r(Y_n)}{n} = 1.4783$$

- We also get (see R code), for $X_0, X_1, \dots$, that

$$\lim_{n \rightarrow \infty} \frac{r(X_1) + \dots + r(X_n)}{n} = 1.4783$$

but in this case the limit is approached more slowly.

Less toy-ish example: “Good” sequences

Consider sequences of length m consisting of 0's and 1's.

- ▶ A sequence is called “good” if it contains no consecutive 1's.
- ▶ What is the average number of 1's in good sequences of length m ?
- ▶ Brute force computation will not work even for m of moderate size.
- ▶ Theoretical computation is possible, but not obvious how to do.
- ▶ *Efficient* direct simulation of a sample of good sequences is not obvious how to do.
- ▶ We construct a random walk on a weighted un-directed graph with nodes consisting of all good sequences (fixed m) so that the limiting distribution is uniform:
 - ▶ Two good sequences are neighbours when they differ at exactly one position. The weight of edge connecting them is 1.
 - ▶ Each good sequence has an edge connecting it to itself, with weight so that the total weights of edges going out from the sequence is m .
 - ▶ Then the limiting distribution is the uniform distribution.
 - ▶ Thus we can estimate the solution by counting 1's in sequences generated by the Markov chain, and then take the average.
 - ▶ This is both easy to program and gives efficient and accurate results.

The Metropolis Hastings algorithm

If we start with a particular distribution, can we construct a Markov chain with that as the limiting distribution?

- ▶ Let θ be a random variable with probability mass function, or density, $\pi(\theta)$.
- ▶ We also assume given a *proposal distribution* $q(\theta_{new} | \theta)$, which, for every given θ , provides a pmf or density for a new θ_{new} .
- ▶ Finally, define, for θ and θ_{new} , the acceptance probability

$$a = \min \left(1, \frac{\pi(\theta_{new})q(\theta | \theta_{new})}{\pi(\theta)q(\theta_{new} | \theta)} \right)$$

- ▶ The Metropolis Hastings algorithm is: Starting with some initial value θ_0 , generate $\theta_1, \theta_2, \dots$ by, at each step, proposing a new θ based on the old using the proposal function and accepting it with probability a . If it is not accepted, the old value is used again.
- ▶ If this defines an ergodic Markov chain, its unique stationary distribution is $\pi(\theta)$ (Proof below).

The Metropolis Hastings algorithm, continued

NOTES:

- ▶ The pmf or density $\pi(\theta)$ only needs to be known up to a constant.
- ▶ If the proposal function is symmetric, i.e., $q(\theta \mid \theta_{new}) = q(\theta_{new} \mid \theta)$ for all θ and θ_{new} , then q disappears in the formula for the acceptance probability a .
- ▶ The computations for good sequences is an example, with $\pi(\theta)$ uniform and q the random walk, so that $q(\theta \mid \theta_{new}) = q(\theta_{new} \mid \theta)$.
- ▶ Unless the distribution $\pi(\theta)$ is *positive*, remark 4 in Dobrow page 188 does NOT hold. If $\pi(\theta)$ is not positive, ergodicity of the Metropolis Hastings Markov chain needs to be checked separately, even if the proposal Markov chain is ergodic.

Proof that MH algorithm works

- ▶ In fact, we will show that the Metropolis Hastings chain fulfills the detailed balance condition relative to $\pi(\theta)$. Thus it is time reversible and if it is ergodic it will have $\pi(\theta)$ as its limiting distribution.
- ▶ Let $T(\theta_{i+1} | \theta_i)$ be the transition function for the MH Markov chain. Assume $\theta_{i+1} \neq \theta_i$, and

$$\frac{\pi(\theta_{i+1})q(\theta_i | \theta_{i+1})}{\pi(\theta_i)q(\theta_{i+1} | \theta_i)} \leq 1$$

Then

$$\begin{aligned}\pi(\theta_i)T(\theta_{i+1} | \theta_i) &= \pi(\theta_i)q(\theta_{i+1} | \theta_i) \frac{\pi(\theta_{i+1})q(\theta_i | \theta_{i+1})}{\pi(\theta_i)q(\theta_{i+1} | \theta_i)} \\ &= \pi(\theta_{i+1})q(\theta_i | \theta_{i+1}) = \pi(\theta_{i+1})T(\theta_i | \theta_{i+1}),\end{aligned}$$

the last step because, with assumption above, $\frac{\pi(\theta_i)q(\theta_{i+1}|\theta_i)}{\pi(\theta_{i+1})q(\theta_i|\theta_{i+1})} \geq 1$

- ▶ We get a similar computation when the opposite inequality holds.

Example 1: Cryptography (from Dobrow)

- ▶ A simple way to encrypt a text is to apply to each character a fixed permutation of the set of the 26 English characters plus space. The text can be decrypted by applying the reverse permutation f , if it is known. If T is an encrypted text we write $f(T)$ for T decrypted with f .
- ▶ Given a short encrypted text T , can we find the permutation f ?
- ▶ Using a text database we first fit a Markov model for text by counting transitions between consecutive characters.
- ▶ For any text T' , we can then compute the probability $S(T')$ for T' being observed as a sequence in this Markov model.
- ▶ We get a probability distribution on the set of all the permutations above by defining, for any f ,

$$\pi(f) \propto_f S(f(T))$$

- ▶ The density $\pi(f)$ is on a very large set, with very few of the f having significant probability. Yet a M.H. can manage to find these (or this) f .
- ▶ We use Metropolis Hastings with a proposal function that picks two characters at random and adds to f a switch of these.

Example 2: Darwin's finches (from Dobrow)

- ▶ A *co-occurrence matrix* M has different species as rows and different locations as columns. If a species occurs at a location, the matrix contains 1, otherwise 0.
- ▶ A *checkerboard* is a submatrix $\begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$ or $\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$. Let $C(M)$ count the number of checkerboards in M .
- ▶ Darwin made a co-occurrence matrix for finches on the Galapagos islands. Compared to the set Ω of possible co-occurrence matrices with the same marginal sums, did it contain an unusually large number of checkerboards?
- ▶ Use Metropolis Hastings to simulate from the uniform distribution on Ω . Use a proposal function that uniformly randomly locates one of the checkerboards and switches it to the opposite form.
- ▶ The acceptance probability becomes $\min(1, C(M)/C(M^*))$ where M^* is proposed from M (error in Dobrow!)
- ▶ Simulation results show that the number of checkerboards observed by Darwin (333) is indeed unexpectedly large, proving competition between the finches.

Gibbs sampling

- ▶ For any probability model over a vector $\theta = (\theta_1, \theta_2, \dots, \theta_k)$, consider a MH proposal function changing only one coordinate, with the value of this coordinate simulated from the conditional distribution given the remaining coordinates.
- ▶ Prove that the acceptance probability is 1.
- ▶ Putting together an algorithm updating different coordinates in different steps may create an ergodic Markov chain.
- ▶ This is then called *Gibbs sampling*.
- ▶ Sometimes the conditional distributions are easy to derive. Then this is an easy-to-use version of Metropolis Hastings.

The Ising model

- ▶ Uses a grid of vertices; we will assume an $n \times n$ grid. Two vertices v and w are *neighbours*, denoted $v \sim w$, if they are next to each other in the grid.
- ▶ Each vertex v can have value $+1$ or -1 (called its “spin”); we denote this by $\sigma_v = 1$ or $\sigma_v = -1$.
- ▶ A *configuration* σ consists of a choice of $+1$ or -1 for each vertex: Thus the set Ω of possible configurations has $2^{(n^2)}$ elements.
- ▶ We define the *energy* of a configuration as $E(\sigma) = -\sum_{v \sim w} \sigma_v \sigma_w$.
- ▶ The Gibbs distribution is the probability mass function on Ω defined by

$$\pi(\sigma) \propto \exp(-\beta E(\sigma))$$

where β is a parameter of the model; $1/\beta$ is called the *temperature*.

- ▶ It turns out that when the temperature is high, samples from the model will show a chaotic pattern of spins, but when the temperature sinks below the *phase transition* value, in our case $1/\beta = 2/\log(1 + \sqrt{2})$, samples will show chunks of neighbouring vertices with the same spin; the system will be “magnetized”.

Simulating from the Ising model using Gibbs sampling

- ▶ For a vertex configuration σ and a vertex v let σ_{-v} denote the part of σ that does not involve v .
- ▶ Propose a new configuration σ^* given an old configuration σ by first choosing a vertex v , then, let σ^* be identical to σ except possibly at v : Decide the spin at v using the conditional distribution given σ_{-v} :

$$\begin{aligned}\pi(\sigma_v = 1 \mid \sigma_{-v}) &= \frac{\pi(\sigma_v = 1, \sigma_{-v})}{\pi(\sigma_{-v})} = \frac{\pi(\sigma_v = 1, \sigma_{-v})}{\pi(\sigma_v = 1, \sigma_{-v}) + \pi(\sigma_v = -1, \sigma_{-v})} \\&= \frac{1}{1 + \frac{\pi(\sigma_v = -1, \sigma_{-v})}{\pi(\sigma_v = 1, \sigma_{-v})}} = \frac{1}{1 + \exp(-\beta E(\sigma_v = -1, \sigma_{-v}) + \beta E(\sigma_v = 1, \sigma_{-v}))} \\&= \frac{1}{1 + \exp(\beta \sum_{v \sim w} \sigma_v \sigma_w \mid_{\sigma_v = -1} - \beta \sum_{v \sim w} \sigma_v \sigma_w \mid_{\sigma_v = 1})} \\&= \frac{1}{1 + \exp(-2\beta \sum_{v \sim w} \sigma_w)}.\end{aligned}$$

- ▶ This works. However, we will see next time an even better approach, "perfect sampling", to this simulation problem.