

MVE550 2023 Lecture 16
Dobrow Chapter 8 part 1
Introduction to Brownian motion
Gaussian processes

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Continuous-time continuous state space processes

- ▶ Having looked at
 - ▶ Discrete-time discrete state space processes. (Discrete Markov chains and Branching processes).
 - ▶ Discrete-time continuous state space processes (not so much but we had some MCMC examples).
 - ▶ Continuous-time discrete state space processes (Poisson processes and more generally continuous-time Markov chains).
 - ▶ we now look at continuous-time continuous state space processes.
- ▶ We will look at two examples:
 - ▶ Brownian motion.
 - ▶ More generally, Gaussian processes.

Brownian motion

- ▶ In a gas, atoms bump into each other and change course. Over time, how does a single atom move, on average?
- ▶ If $f(x, t)$ represents the probability density for the position x of an atom at time t moving along a line, Albert Einstein showed that

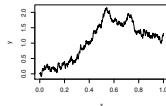
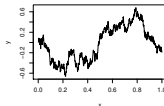
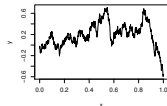
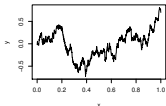
$$\frac{\partial}{\partial t} f(x, t) = \frac{1}{2} \frac{\partial^2}{\partial x^2} f(x, t).$$

- ▶ The solution is

$$f(x, t) = \frac{1}{\sqrt{2\pi t}} e^{-x^2/2t}.$$

So $x \sim \text{Normal}(0, t)$ at time t .

- ▶ It turns out a single atom will move as simulated below. These paths are sampled from a model called Brownian motion.



Definition of Brownian motion

Brownian motion is a continuous-time stochastic process $\{B_t\}_{t \geq 0}$ with the following properties:

1. $B_0 = 0$.
2. For $t > 0$, $B_t \sim \text{Normal}(0, t)$ (so the *variance* is t , not the standard deviation).
3. For $s, t > 0$, $B_{t+s} - B_s \sim \text{Normal}(0, t)$.
4. For $0 \leq q < r \leq s < t$, $B_t - B_s$ is independent from $B_r - B_q$.
5. The function $t \mapsto B_t$ is continuous with probability 1.

Simulation of Brownian motion

- ▶ Given time points $0 = t_0 < t_1 < t_2 < \dots < t_n$, we write for $i > 0$:

$$B_{t_i} = B_{t_{i-1}} + (B_{t_i} - B_{t_{i-1}}) = B_{t_{i-1}} + Z_i$$

where $Z_i \sim \text{Normal}(0, t_i - t_{i-1})$.

- ▶ We get for independent Z_1, \dots, Z_n ,

$$B_{t_n} = \sum_{i=1}^n Z_i.$$

- ▶ A good way to simulate the path $t \mapsto B_t$ on $t \in [0, a]$ is to set $t_i = ai/n$, simulate independently

$$Z_i \sim \text{Normal}(0, a/n)$$

and compute

$$B_{t_i} = \sum_{j=1}^i Z_j.$$

- ▶ Note that we can also write $Z_i = \sqrt{a/n} Y_i$, where $Y_i \sim \text{Normal}(0, 1)$.

Zooming in on a Brownian motion realization

What if we have a Brownian motion path simulated above, and want to plot it at twice the detail?

- ▶ We have

$$B_{t_i + \frac{a}{2n}} - B_{t_i} = Z_{i0} \sim \text{Normal}\left(0, \frac{a}{2n}\right)$$

$$B_{t_{i+1}} - B_{t_i + \frac{a}{2n}} = Z_{i1} \sim \text{Normal}\left(0, \frac{a}{2n}\right)$$

- ▶ Reformulating using $Z_i = B_{t_{i+1}} - B_{t_i}$ we get

$$Z_{i0} \sim \text{Normal}\left(0, \frac{a}{2n}\right), \quad Z_i \mid Z_{i0} \sim \text{Normal}\left(Z_{i0}, \frac{a}{2n}\right).$$

- ▶ Conjugacy gives the posterior

$$Z_{i0} \mid Z_i \sim \text{Normal}\left(\frac{1}{2}Z_i, \frac{a}{4n}\right).$$

- ▶ So we get $B_{t_i + \frac{a}{2n}}$ by simulating Z_{i0} given Z_i as above and adding the result to B_{t_i} .
- ▶ NOTE: Procedure for simulating B_t is unchanged if we scale x-axis with a and scale y-axis with \sqrt{a} ! Fractal behaviour!

Computing with Brownian motion

- ▶ To compute probabilities for Brownian motion, we generally use the properties in the definition, e.g.,
 - ▶ $B_{t+s} - B_s \sim \text{Normal}(0, t)$
 - ▶ For $0 \leq q < r \leq s < t$, $B_t - B_s$ is independent from $B_r - B_q$.
- ▶ Example: Show that $B_1 + B_3 + 2B_7 \sim \text{Normal}(0, 50)$.
- ▶ Example: Show that $P(B_2 > 0 \mid B_1 = 1) = 0.8413$.
- ▶ Example: Show that $\text{Cov}(B_s, B_t) = \min\{s, t\}$.

Random walks: What happens when $n \rightarrow \infty$?

- ▶ A symmetric random walk is a discrete time Markov chain S_0, S_1, S_2, \dots where $S_0 = 0$ and

$$S_n = X_1 + X_2 + \dots + X_n$$

where X_1, X_2, \dots are independent random variables with expectation zero.

- ▶ If we assume $\text{Var}(X_i) = 1$ we get $\text{Var}(S_n) = n$.
- ▶ Interpolating between the values S_n we can make this into a continuous time process S_t (see Dobrow). $\text{Var}(S_t) \approx t$.
- ▶ We may scale with an $s > 0$ to get processes $S_t^{(s)} = S_{st}/\sqrt{s}$ where we get $\lim_{s \rightarrow \infty} \text{Var}(S_t^{(s)}) = t$.
- ▶ It turns out that the processes $S_t^{(s)}$ when $s \rightarrow \infty$ are *exactly* Brownian motion, no matter what type of X_i we start with!
- ▶ This is the **Donsker invariance principle**.
- ▶ We can see this effect in simulations.
- ▶ We can use this to find approximate properties of random walks.

Nowhere differentiable paths

- ▶ We have seen in our simulations that paths of Brownian motion are “jagged”.
- ▶ We have also seen that this quality is unchanged if we change the scale, i.e., look at smaller intervals.
- ▶ Formally note that $B_{t+h} - B_t \sim \text{Normal}(0, h)$ so that

$$\frac{B_{t+h} - B_t}{h} \sim \text{Normal}(0, 1/h)$$

- ▶ Using these observations as starting points, one may show that the path (i.e., the function $t \mapsto B_t$) of a Brownian motion is nowhere differentiable, even though it is everywhere continuous.

The multivariate normal distribution (review)

- ▶ Definition (one of many): A set of random variables X_1, \dots, X_k has a *multivariate normal distribution* if, for all real a_1, \dots, a_k , $a_1X_1 + \dots + a_kX_k$ is normally distributed.
- ▶ It is completely determined by the expectation vector $\mu = (E(X_1), \dots, E(X_k))$ and the $(k \times k)$ covariance matrix Σ , where $\Sigma_{ij} = \text{Cov}(X_i, X_j)$.
- ▶ The joint density function on the vector $x = (x_1, \dots, x_k)$ is

$$\pi(x) = \frac{1}{|2\pi\Sigma|^{1/2}} \exp\left(-\frac{1}{2}(x - \mu)^T \Sigma^{-1}(x - \mu)\right).$$

where $|2\pi\Sigma|$ is the determinant of the matrix $2\pi\Sigma$.

- ▶ All marginal distributions and all conditional distributions are also multivariate normal.

- ▶ A *Gaussian process* is a continuous-time stochastic process $\{X_t\}_{t \geq 0}$ with the property that for all $n \geq 1$ and $0 \leq t_1 < t_2 < \dots < t_n$, X_{t_1}, \dots, X_{t_n} has a multivariate normal distribution.
- ▶ Thus, a Gaussian process is completely determined by its mean function $E(X_t)$ and its covariance function $\text{Cov}(X_s, X_t)$.
- ▶ Gaussian processes are extremely versatile as models. One may generalize for example so that the index set (the t 's) is \mathbb{R}^n .

Brownian motion and Gaussian processes

- ▶ Brownian motion is a Gaussian process, as we can show that any $a_1 B_{t_1} + \dots + a_k B_{t_k}$ is normally distributed.
- ▶ A Gaussian process $\{X_t\}_{t \geq 0}$ is Brownian motion if and only if
 1. $X_0 = 0$.
 2. $E(X_t) = 0$ for all t .
 3. $\text{Cov}(X_s, X_t) = \min\{s, t\}$ for all s, t .
 4. The function $t \mapsto X_t$ is a continuous with probability 1.
- ▶ The proof is fairly straightforward (see Dobrow).
- ▶ One may use the above for example when proving that something is Brownian motion, if it is easier than using the definition directly.

Transformations of Brownian motion

- ▶ The following transformations of Brownian motion are again Brownian motion:
 - ▶ $\{-B_t\}_{t \geq 0}$.
 - ▶ $(B_{t+s} - B_s)_{t \geq 0}$ for any $s \geq 0$.
 - ▶ $\left\{\frac{1}{\sqrt{a}}B_{at}\right\}_{t \geq 0}$ for any $a > 0$.
 - ▶ The process $\{X_t\}_{t \geq 0}$ where $X_0 = 0$ and $X_t = tB_{1/t}$ for $t > 0$.
- ▶ The proofs are fairly straightforward.
- ▶ The process $X_t = x + B_t$ where B_t is Brownian motion and x is some real number is called “Brownian motion started at x ”.

Stopping times

- ▶ Proved above: For any fixed t , $(B_{t+s} - B_t)_{s \geq 0}$ is Brownian motion.
- ▶ Does this also happen if we start the chain anew from T when T is random? It depends!
- ▶ If T is the largest value less than 1 where $B_T = 0$, is $B_{T+s} - B_T$ Brownian motion?
- ▶ No!
- ▶ If T is the smallest value where $B_T = a$ for some constant a , is $B_{T+s} - B_T$ Brownian motion?
- ▶ Yes! The reason is that the event $T = t$ can be determined based on B_r where $0 \leq r \leq t$.
- ▶ Random T 's that have this property are called *stopping times*. For these $B_{T+s} - B_T$ is Brownian motion.

The distribution of the first hitting time

- ▶ Given $a \neq 0$ what is the distribution of the first hitting time $T_a = \min \{t : B_t = a\}$?
- ▶ We prove below that

$$\frac{1}{T_a} \sim \text{Gamma} \left(\frac{1}{2}, \frac{a^2}{2} \right)$$

- ▶ Assuming that $a > 0$ and using that T_a is a stopping time we get for any $t > 0$ that $\Pr(B_{1/t} > a \mid T_a < 1/t) = \Pr(B_{1/t-T_a} > 0) = \frac{1}{2}$.
- ▶ We also have

$$\Pr(B_{1/t} > a \mid T_a < 1/t) = \frac{\Pr(B_{1/t} > a, T_a < 1/t)}{\Pr(T_a < 1/t)} = \frac{\Pr(B_{1/t} > a)}{\Pr(T_a < 1/t)}.$$

- ▶ It follows that $\Pr(T_a < 1/t) = 2 \Pr(B_{1/t} > a)$ and so

$$\Pr\left(\frac{1}{T_a} < t\right) = 2 \Pr(B_{1/t} < a) - 1 = 2 \Pr(B_1 < a\sqrt{t}) - 1.$$

- ▶ Taking the derivative w.r.t. t we get the Gamma density

$$\pi_{1/T_a}(t) = 2 \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{1}{2}(a\sqrt{t})^2\right) \frac{a}{2} t^{-1/2}.$$

Maximum of Brownian motion

- ▶ Define $M_t = \max_{0 \leq s \leq t} B_s$.
- ▶ We may compute for $a > 0$ (using result from previous page)

$$\Pr(M_t > a) = \Pr(T_a < t) = 2 \Pr(B_t > a) = \Pr(|B_t| > a)$$

- ▶ Thus M_t has the same distribution as $|B_t|$, the absolute value of B_t .
- ▶ Example: What is the probability that $M_3 > 5$?
- ▶ Example: Find t such that $\Pr(M_t \leq 4) = 0.9$.