# TMA026/MMA430 <br> Exercises and solutions 

Per Ljung<br>perlj@chalmers.se

April 3, 2020

Exercise session 2: 3.8, 3.9, 3.11.

## Exercise 3.8

Give a variational formulation of the problem

$$
\begin{aligned}
-\nabla \cdot(a \nabla u)+c u=f, & \text { in } \Omega \\
a \frac{\partial u}{\partial n}+h(u-g)=k, & \text { on } \Gamma
\end{aligned}
$$

where $f \in L_{2}(\Omega), g, k \in L_{2}(\Gamma)$, and the coefficients $a, c, h$ are smooth and such that $a(x) \geq a_{0}>0$ and $c(x) \geq 0$ for $x \in \Omega$, and $h(x) \geq h_{0}>0$ for $x \in \Gamma$. Prove the existence and uniqueness of a weak solution. Prove the stability estimate

$$
\|u\|_{H^{1}(\Omega)} \leq C\left(\|f\|_{L_{2}(\Omega)}+\|k\|_{L_{2}(\Gamma)}+\|g\|_{L_{2}(\Gamma)}\right) .
$$

Hint: Use Problem 3.4.
Solution: To find the variational formulation, we multiplty by a test function $v \in H^{1}(\Omega)$ and integrate over the domain $\Omega$ to get

$$
-\int_{\Omega} \nabla \cdot(a \nabla u) v \mathrm{~d} x+\int_{\Omega} c u v \mathrm{~d} x=\int_{\Omega} f v \mathrm{~d} x
$$

Applying Green's formula, we can rewrite the first term on the left hand side as

$$
\begin{aligned}
-\int_{\Omega} \nabla \cdot(a \nabla u) v \mathrm{~d} x & =\int_{\Omega} a \nabla u \cdot \nabla v \mathrm{~d} x-\int_{\Gamma} a \frac{\partial u}{\partial n} v \mathrm{~d} s \\
& =\int_{\Omega} a \nabla u \cdot \nabla v \mathrm{~d} x-\int_{\Gamma} k v \mathrm{~d} s+\int_{\Gamma} h u v \mathrm{~d} s-\int_{\Gamma} h g v \mathrm{~d} s
\end{aligned}
$$

where we used the Robin boundary condition in the last step. The variational formulation states: Find $u \in H^{1}(\Omega)$ such that

$$
\underbrace{(a \nabla u, \nabla v)+(c u, v)+(h u, v)_{L_{2}(\Gamma)}}_{=: a(u, v)}=\underbrace{(f, v)+(k+h g, v)_{L_{2}(\Gamma)}}_{=: L(v)},
$$

for all $v \in H^{1}(\Omega)$. To show the existence of a unique weak solution, we wish to apply the Lax-Milgram lemma (Theorem A.3), i.e. it suffices to show that the bilinear form $a(\cdot, \cdot)$ is bounded and coercive, and that the linear functional $L(\cdot)$ is bounded.

For the boundedness of $a(\cdot, \cdot)$, take two arbitrary elements $v, w \in H^{1}(\Omega)$ and note that

$$
\begin{aligned}
|a(v, w)| & \leq\|a\|_{\mathcal{C}}\|\nabla v\|\|\nabla w\|+\|c\|_{\mathcal{C}}\|v\|\|w\|+\|h\|_{\mathcal{C}(\Gamma)}\|w\|_{L_{2}(\Gamma)}\|v\|_{L_{2}(\Gamma)} \\
& \leq\left(\|a\|_{\mathcal{C}}+\|c\|_{\mathcal{C}}\right)\|v\|_{H^{1}}\|w\|_{H^{1}}+\|h\|_{\mathcal{C}(\Gamma)}\|v\|_{L_{2}(\Gamma)}\|w\|_{L_{2}(\Gamma)} \\
& \leq\left(\|a\|_{\mathcal{C}}+\|c\|_{\mathcal{C}}+C^{2}\|h\|_{\mathcal{C}(\Gamma)}\right)\|v\|_{H^{1}}\|w\|_{H^{1}}
\end{aligned}
$$

where in the first inequality we have applied the triangle inequality and the Cauchy-Schwarz inequality, in the second step the fact that $\|\cdot\| \leq\|\cdot\|_{H^{1}}$ and
$|\cdot|_{H^{1}} \leq\|\cdot\|_{H^{1}}$, and in the final step we applied the trace inequality. We conclude that $a(\cdot, \cdot)$ is bounded.

For the coercivity of $a(\cdot, \cdot)$, let $v \in H^{1}(\Omega)$ and note that

$$
\begin{aligned}
a(v, v) & =\int_{\Omega} a|\nabla v|^{2}+c v^{2} \mathrm{~d} x+\int_{\Gamma} h v^{2} \mathrm{~d} s \\
& \geq a_{0}\|\nabla v\|^{2}+h_{0}\|v\|_{L_{2}(\Gamma)}^{2} \\
& =\frac{a_{0}}{2}\|\nabla v\|^{2}+\frac{a_{0}}{2}\|\nabla v\|^{2}+h_{0}\|v\|_{L_{2}(\Gamma)}^{2} \\
& \geq \frac{a_{0}}{2}\|\nabla v\|^{2}+\min \left\{\frac{a_{0}}{2}, h_{0}\right\}\left(\|\nabla v\|^{2}+\|v\|_{L_{2}(\Gamma)}^{2}\right) \\
& \geq \frac{a_{0}}{2}\|\nabla v\|^{2}+\min \left\{\frac{a_{0}}{2}, h_{0}\right\} C^{-2}\|v\|^{2} \\
& \geq \min \left\{\frac{a_{0}}{2}, \min \left\{\frac{a_{0}}{2}, h_{0}\right\} C^{-2}\right\}\|v\|_{H^{1}}^{2} .
\end{aligned}
$$

For this calculation, we first used the fact bounds given on $a, c$, and $h$ to bound them from above ( $c$ vanishes since it is bounded below by 0 ). The next part sets up for the usage of Friedrich's inequality (Problem 3.4 as given in the hint) which is applied in the fifth row. We conclude that $a(\cdot, \cdot)$ is coercive.

At last, we show the boundedness of the linear functional $L(\cdot)$. Let $v \in$ $H^{1}(\Omega)$, and we find that

$$
\begin{aligned}
|L(v)| & \leq\|f\|\|v\|+\|k+g h\|_{L_{2}(\Gamma)}\|v\|_{L_{2}(\Gamma)} \\
& \leq\|f\|\|v\|+\left(\|k\|_{L_{2}(\Gamma)}+\|h\|_{\mathcal{C}(\Gamma)}\|g\|_{L_{2}(\Gamma)}\right)\|v\|_{L_{2}(\Gamma)} \\
& \leq\|f\|\|v\|+\left(\|k\|_{L_{2}(\Gamma)}+\|h\|_{\mathcal{C}(\Gamma)}\|g\|_{L_{2}(\Gamma)}\right) C\|v\|_{H^{1}} \\
& \leq\left(\|f\|+C\left(\|k\|_{L_{2}(\Gamma)}+\|h\|_{\mathcal{C}(\Gamma)}\|g\|_{L_{2}(\Gamma)}\right)\right)\|v\|_{H^{1}}
\end{aligned}
$$

where we first use the triangle inequality and Cauchy-Schwarz, and in the third row the trace inequality. We conclude that $L \in H^{-1}(\Omega)$, with bounded norm

$$
\begin{aligned}
\|L\|_{H^{-1}} & \leq\|f\|+C\|k\|_{L_{2}(\Gamma)}+C\|h\|_{\mathcal{C}(\Gamma)}\|g\|_{L_{2}(\Gamma)} \\
& \leq \max \left\{1, C, C\|h\|_{\mathcal{C}(\Gamma)}\right\}\left(\|f\|+\|k\|_{L_{2}(\Gamma)}+\|g\|_{L_{2}(\Gamma)}\right) .
\end{aligned}
$$

Now, the Lax-Milgram lemma partially yields the conclusion that there exists a unique solution $u \in H^{1}(\Omega)$ to

$$
a(u, v)=L(v), \quad \forall v \in H^{1}(\Omega)
$$

but it moreover gives the stability estimate

$$
\begin{aligned}
\|u\|_{H^{1}} & \leq \alpha^{-1}\|L\|_{H^{-1}} \\
& \leq \alpha^{-1} \max \left\{1, C, C\|h\|_{\mathcal{C}(\Gamma)}\right\}\left(\|f\|+\|k\|_{L_{2}(\Gamma)}+\|g\|_{L_{2}(\Gamma)}\right) \\
& =\tilde{C}\left(\|f\|+\|k\|_{L_{2}(\Gamma)}+\|g\|_{L_{2}(\Gamma)}\right)
\end{aligned}
$$

where $\alpha$ denotes the coercivity constant. This concludes the problem.

## Exercise 3.9

Consider the Neumann problem

$$
\begin{aligned}
-\Delta u & =f, & \text { in } \Omega, \\
\frac{\partial u}{\partial n} & =0, & \text { on } \Gamma .
\end{aligned}
$$

Assume that $f \in L_{2}(\Omega)$ and show that the condition

$$
\int_{\Omega} f \mathrm{~d} x=0
$$

is necessary for the existence of a solution. Moreover, notice that if $u$ satisfies the Neumann problem, then so does $u+c$ for any constant $c$. To obtain uniqueness, we add the extra condition

$$
\int_{\Omega} u \mathrm{~d} x=0
$$

requiring the mean value of $u$ to be zero. Give this problem a variational formulation using the space

$$
V=\left\{v \in H^{1}(\Omega): \int_{\Omega} v \mathrm{~d} x=0\right\} .
$$

Prove that there is a unique weak solution. Hint: See Problem 3.5.
Solution: For the first part, we note that for a solution to exist it must hold that

$$
\begin{aligned}
\int_{\Omega} f \mathrm{~d} x & =-\int_{\Omega} \Delta u \mathrm{~d} x=-\int_{\Omega} \nabla \cdot \nabla u \mathrm{~d} x=-\int_{\Gamma} \nabla u \cdot \mathbf{n} \mathrm{~d} s \\
& =-\int_{\Gamma} \frac{\partial u}{\partial n} \mathrm{~d} s=-\int_{\Gamma} 0 \mathrm{~d} s=0 .
\end{aligned}
$$

Here we used Gauss divergence theorem in the third step. For the second part, we derive a variational formulation by standard procedure. Given the definition of $V$ as in the problem formulation, multiply the equation by a test function $v \in V$ and integrate over the domain to get

$$
-\int_{\Omega} \Delta u v \mathrm{~d} x=\int_{\Omega} f v \mathrm{~d} x
$$

Applying Green's formula to the left hand side gives

$$
-\int_{\Omega} \Delta u v \mathrm{~d} x=\int_{\Omega} \nabla u \cdot \nabla v \mathrm{~d} x-\underbrace{\int_{\Gamma} \frac{\partial u}{\partial n} v \mathrm{~d} s}_{=0}=\int_{\Omega} \nabla u \cdot \nabla v \mathrm{~d} x
$$

due to the homogeneous Neumann condition. The variational formulation becomes: Find $u \in V$ such that

$$
\underbrace{\int_{\Omega} \nabla u \cdot \nabla v \mathrm{~d} x}_{=: a(u, v)}=\underbrace{\int_{\Omega} f v \mathrm{~d} x}_{=: L(v)}, \quad \forall v \in V .
$$

We wish to apply Lax-Milgram to show the uniqueness of the solution. For the boundedness of $a(\cdot, \cdot)$ we immediately get for $v, w \in V$

$$
|a(v, w)| \leq\|\nabla v\|\|\nabla w\| \leq\|v\|_{H^{1}}\|w\|_{H^{1}}
$$

by Cauchy-Schwarz inequality. For the coercivity part, we want to use the hint, i.e. Problem 3.5, which gives the inequality

$$
\|v\| \leq C\left(\|\nabla v\|^{2}+\left(\int_{\Omega} v \mathrm{~d} x\right)^{2}\right)^{1 / 2}
$$

Note that given our space $V$, the integral will be evaluated to zero here, and we have a Poincaré type inequality that corresponds to function of zero mean. Using this, we get for $v \in V$

$$
\begin{aligned}
2 a(v, v) & =2\|\nabla v\|^{2} \\
& =\|\nabla v\|^{2}+\|\nabla v\|^{2}+\left(\int_{\Omega} v \mathrm{~d} x\right)^{2} \\
& \geq\|\nabla v\|^{2}+C^{-1}\|v\|^{2} \\
& \geq \min \left\{1, C^{-1}\right\}\|v\|_{H^{1}}^{2},
\end{aligned}
$$

which gives coercivity with constant $\alpha=\frac{1}{2} \min \left\{C^{-1}, 1\right\}$. At last, the boundedness of $L(\cdot)$ follows immediately from Cauchy-Schwarz, as for $v \in V$ we get

$$
|L(v)| \leq\|f\|\|v\| \leq\|f\|\|v\|_{H^{1}}
$$

The uniqueness now follows from Lax-Milgram.

## Exercise 3.11

Assume that $\Omega \subset \mathbb{R}^{2}$ is a rectangle and that $u$ is a smooth function with $u=0$ on $\Gamma$. Prove that

$$
|u|_{2}=\|\Delta u\| .
$$

Use this to prove (3.36) for $\mathcal{A}=-\Delta$.
Hint: Recall that

$$
|u|_{2}^{2}=\int_{\Omega}\left(\left(\frac{\partial^{2} u}{\partial x_{1}^{2}}\right)^{2}+2\left(\frac{\partial^{2} u}{\partial x_{1} \partial x_{2}}\right)^{2}+\left(\frac{\partial^{2} u}{\partial x_{2}^{2}}\right)^{2}\right) \mathrm{d} x
$$

and integrate by parts in $\int_{\Omega}\left(\frac{\partial^{2} u}{\partial x_{1} \partial x_{2}}\right)^{2} \mathrm{~d} x$. Then recall the definition $\|u\|_{2}=$ $\left(\|u\|^{2}+|u|_{1}^{2}+|u|_{2}^{2}\right)^{1 / 2}$ and prove that $\|u\| \leq C|u|_{1}$ and $|u|_{1} \leq\left(\|u\||u|_{2}\right)^{1 / 2}$.
Solution: At first, we mention that the proving (3.36) part with $\mathcal{A}=-\Delta$ is to prove that

$$
\|u\|_{2} \leq C\|\Delta u\|
$$

We define the rectangle we work with according to Figure 1. Given this domain, we have on each part of the boundary that

$$
\begin{aligned}
& u=0, \quad \frac{\partial u}{\partial x_{1}}=0, \quad \frac{\partial^{2} u}{\partial x_{1}^{2}}=0, \quad n_{1}=0, \quad \text { on } \Gamma_{1}, \\
& u=0, \quad \frac{\partial u}{\partial x_{2}}=0, \quad n_{2}=0, \quad \text { on } \Gamma_{2} .
\end{aligned}
$$



Figure 1: The rectangle with defined boundaries $\Gamma_{1}$ and $\Gamma_{2}$.
We now use the given hint, and begin by applying integration by parts on the integral

$$
\begin{aligned}
\int_{\Omega}\left(\frac{\partial^{2} u}{\partial x_{1} \partial x_{2}}\right)^{2} \mathrm{~d} x & =\int_{\Omega} \frac{\partial}{\partial x_{1}} \frac{\partial u}{\partial x_{2}} \cdot \frac{\partial}{\partial x_{2}} \frac{\partial u}{\partial x_{1}} \mathrm{~d} x \\
& =\int_{\Gamma} n_{1} \frac{\partial u}{\partial x_{2}} \frac{\partial^{2} u}{\partial x_{1} \partial x_{2}} \mathrm{~d} s-\int_{\Omega} \frac{\partial u}{\partial x_{2}} \cdot \frac{\partial}{\partial x_{2}} \frac{\partial^{2} u}{\partial x_{1}^{2}} \mathrm{~d} x \\
& =\int_{\Gamma}\left(n_{1} \frac{\partial u}{\partial x_{2}} \frac{\partial^{2} u}{\partial x_{1} \partial x_{2}}-n_{2} \frac{\partial u}{\partial x_{2}} \frac{\partial^{2} u}{\partial x_{1}^{2}}\right) \mathrm{d} s+\int_{\Omega} \frac{\partial^{2} u}{\partial x_{1}^{2}} \frac{\partial^{2} u}{\partial x_{2}^{2}} \mathrm{~d} x
\end{aligned}
$$

Here, we first used integration by parts in the $x_{1}$-direction, and in the next step in the $x_{2}$-direction. Next, we check the boundary integral on $\Gamma_{1}$ and $\Gamma_{2}$ separately, and note that

$$
\begin{aligned}
& \int_{\Gamma_{1}}(\underbrace{n_{1}}_{=0} \frac{\partial u}{\partial x_{2}} \frac{\partial^{2} u}{\partial x_{1} \partial x_{2}}-n_{2} \frac{\partial u}{\partial x_{2}} \underbrace{\frac{\partial^{2} u}{\partial x_{1}^{2}}}_{=0})=0 \\
& \int_{\Gamma_{2}}(n_{1} \underbrace{\frac{\partial u}{\partial x_{2}}}_{=0} \frac{\partial^{2} u}{\partial x_{1} \partial x_{2}}-\underbrace{n_{2}}_{=0} \frac{\partial u}{\partial x_{2}} \frac{\partial^{2} u}{\partial x_{1}^{2}})=0
\end{aligned}
$$

and hence the whole integral over $\Gamma$ evaluates to zero, and we thus have

$$
\int_{\Omega}\left(\frac{\partial^{2} u}{\partial x_{1} \partial x_{2}}\right)^{2} \mathrm{~d} x=\int_{\Omega} \frac{\partial^{2} u}{\partial x_{1}^{2}} \frac{\partial^{2} u}{\partial x_{2}^{2}} \mathrm{~d} x
$$

Consequently, we find that

$$
\begin{aligned}
|u|_{2}^{2} & =\int_{\Omega}\left(\left(\frac{\partial^{2} u}{\partial x_{1}^{2}}\right)^{2}+2\left(\frac{\partial^{2} u}{\partial x_{1} \partial x_{2}}\right)^{2}+\left(\frac{\partial^{2} u}{\partial x_{2}^{2}}\right)^{2}\right) \mathrm{d} x \\
& =\int_{\Omega}\left(\left(\frac{\partial^{2} u}{\partial x_{1}^{2}}\right)^{2}+2 \frac{\partial^{2} u}{\partial x_{1}^{2}} \frac{\partial^{2} u}{\partial x_{2}^{2}}+\left(\frac{\partial^{2} u}{\partial x_{2}^{2}}\right)^{2}\right) \mathrm{d} x \\
& =\int_{\Omega}\left(\frac{\partial^{2} u}{\partial x_{1}^{2}}+\frac{\partial^{2} u}{\partial x_{2}^{2}}\right)^{2} \mathrm{~d} x \\
& =\|\Delta u\|^{2}
\end{aligned}
$$

and hence

$$
\begin{equation*}
|u|_{2}=\|\Delta u\| . \tag{1}
\end{equation*}
$$

To prove (3.36), we follow the hint. First of all, the inequality

$$
\begin{equation*}
\|u\| \leq C\|\nabla u\|=C|u|_{1} \tag{2}
\end{equation*}
$$

follows by the Poincaré inequality. The last inequality in the hint is found by applying Green's formula, the homogeneous boundary condition, and then Cauchy-Schwarz, i.e

$$
\begin{aligned}
|u|_{1}^{2} & =\int_{\Omega} \nabla u \cdot \nabla u \mathrm{~d} x=\int_{\Gamma} \frac{\partial u}{\partial n} u \mathrm{~d} s-\int_{\Omega} u \Delta u \mathrm{~d} x=-\int_{\Omega} u \Delta u \mathrm{~d} x \\
& \leq\left|\int_{\Omega} u \Delta u \mathrm{~d} x\right| \leq\|u\|\|\Delta u\|=\|u\||u|_{2} \leq C|u|_{1}|u|_{2} \\
& \leq \frac{1}{2}|u|_{1}^{2}+\frac{C^{2}}{2}|u|_{2}^{2} .
\end{aligned}
$$

In the last three steps, we first applied the result (1), followed by the result (22), and at last the inequality $a b \leq \frac{1}{2} a^{2}+\frac{1}{2} b^{2}$. Passing the first term to the left hand side yields

$$
\begin{equation*}
|u|_{1}^{2} \leq C^{2}|u|_{2}^{2} \tag{3}
\end{equation*}
$$

With these results given, we now note that

$$
\begin{aligned}
\|u\|_{2}^{2} & =\|u\|^{2}+|u|_{1}^{2}+|u|_{2}^{2} \leq\left(1+C^{2}\right)|u|_{1}^{2}+|u|_{2}^{2} \\
& \leq \underbrace{\left[\left(1+C^{2}\right) C^{2}+1\right]}_{=: \tilde{C}}|u|_{2}^{2}=\tilde{C}\|\Delta u\|^{2},
\end{aligned}
$$

which concludes the exercise.

